# Spin versions of the complex trigonometric Ruijsenaars-Schneider model from cyclic quivers 

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We study multiplicative quiver varieties associated to specific extensions of cyclic quivers with $m \geq 2$ vertices. Their global Poisson structure is characterized by quasi-Hamiltonian algebras related to these quivers, which were studied by Van den Bergh for an arbitrary quiver. We show that the spaces are generically isomorphic to the case $m=1$ corresponding to an extended Jordan quiver. This provides a set of local coordinates, which we use to interpret integrable systems as spin variants of the trigonometric Ruijsenaars-Schneider (RS) system. This generalizes to new spin cases recent works on classical integrable systems in the RS family.

Keywords: quivers; double bracket; quasi-Hamiltonian algebra; non-commutative geometry; multiplicative quiver variety; Ruijsenaars-Schneider system.

## 1. Introduction

In this article, we continue a recent attempt initiated in [1] to interpret the phase spaces of classical complex integrable systems in the Ruijsenaars-Schneider (or RS) family as moduli spaces constructed from particular quivers. Before focusing on this problem, let's recall the well-understood interpretation in the non-relativistic case of the Calogero-Moser (or CM) system, and its spin variant. In the pioneering work [2], Wilson unveils several structures related to the phase space for the complex CM system, one of which is the hyperkähler structure it possesses. The latter is naturally defined in the context of Nakajima quiver varieties [3], which considers Hamiltonian reduction of representation spaces of quivers. Forgetting all but the topological structure, the phase space is nothing else than the reduced representation space of a deformed preprojective algebra associated to a Jordan quiver extended by one arrow. Therefore, it is natural to ask if one could obtain the symplectic structure also at the level of the algebra. This is indeed the case, if we consider non-commutative symplectic geometry [4,5], or the analogue for non-commutative Poisson geometry [6]. We refer to the review [7] for some details. Going a step further, we can understand the spin generalization of this model discovered by Gibbons and Hermsen [8], by looking at a Jordan quiver consisting of a single loop-arrow, which we extend by several arrows coming from an additional vertex [9,10]. We obtain in this way the model in type $A_{n}$, whose Weyl group $W=S_{n}$ determines the symmetry of the obtained system. A study of various extensions of cyclic quivers generalizes the result to different complex reflection groups [11], in particular the case $W=S_{n} \ltimes \mathbb{Z}_{m}^{n}$ to which we shall come back.

[^0]We postpone the quiver interpretation in the relativistic case, as we first need to focus on the geometric side of these systems. In a way similar to the CM case, it is possible to understand the trigonometric RS system geometrically, either as a symplectic leaf on a space defined by Poisson reduction [12], or directly using quasi-Hamiltonian reduction [1, 13]. While the process of Hamiltonian reduction brings down a Poisson manifold to one of smaller dimension by considering the action of a Lie group, in the quasi-Hamiltonian setting we begin with a space which has some failure to have a Poisson bracket, but we end up with a genuine Poisson manifold. These spaces that are called quasi-Poisson manifolds [14], which are first introduced in [15] for the 'quasi-symplectic' case, find their origin in the need to get Lie group valued moment maps. In some cases, it also provides a finite-dimensional framework for infinitedimensional symplectic reductions introduced by Atiyah and Bott [16]. Therefore, the reduction described above provides an alternative formalism to understand earlier works of Gorsky and Nekrasov [17, 18]. However, if we leave the type $A_{n}$, we can observe that until recent works by Fehér and collaborators (see e.g. [19-23] mostly in the real case), integrable systems in the trigonometric RS family are generally devised using only a suitable Lax matrix, as they originally appear in [24], without geometric perspectives.

The lack of a specific geometrical framework to derive these models is even more apparent for spin versions. To understand what is known at the moment, let us recall how the spin RS system is introduced in the first place. In a celebrated attempt to generalize the relation between the matrix KP equation and the spin CM system [25], Krichever and Zabrodin investigate solutions of the non-abelian 2D Toda chain and discover the Lax matrix for the real spin RS system, already in its elliptic form [26]. This system is parametrized by $n$ particles with positions $q_{i}$, each endowed with $d$ additional degrees of freedom $a_{i}^{\alpha}$, for which we have $d$ conjugate variables $c_{i}^{\alpha}$ that are function of the momentum $\dot{q}_{i}$. There are additional $n$ relations, so that we have $2 n d$ independent coordinates, which appear in the Lax matrix $L$ (that we consider without spectral parameter) such that the Hamiltonian $H_{1}=\operatorname{tr} L$ defines the equations of motion for the spin RS system. A striking feature of this space is the existence of a natural action of a Lie group of dimension $d(d-1)$, such that on the corresponding orbit space we can pick coordinates from the functions ${ }^{1}\left(q_{i}, f_{i j}=\sum_{\alpha} a_{i}^{\alpha} c_{j}^{\alpha}\right)$. Moreover, the Hamiltonian $H_{1}$ descends to this reduced space where it becomes integrable in Liouville sense, and solutions to the equations of motion defined by $H_{1}$ can be found in terms of theta functions. In the rational and trigonometric case, a simpler form for the equations of motions corresponding to the Hamiltonians $\operatorname{tr} L^{k}$ can be found [27, 28]. However, except in the rational case [27] and for two particles in the elliptic case [29], the Poisson structure of the space is only known in a universal form [30] that is not easy to manipulate. It is the existence of a geometric formalism that allows to completely determine the Poisson brackets between the coordinates ( $q_{i}, a_{i}^{\alpha}, c_{i}^{\alpha}$ ) in the rational case for the type $A_{n}$ [27]. Similarly, it is the existence of a geometric interpretation that enables to prove the integrability of such system outside the type $A_{n}$ in the rational [31] or trigonometric [32] cases. (Nevertheless, in those cases we work on the phase space where the individual spins ( $a_{i}^{\alpha}, c_{i}^{\alpha}$ ) are not naturally defined and we only know the collective spins $\left(f_{i j}\right)$.) Thereupon, our understanding of the Hamiltonian formalism for spin RS systems remains quite limited outside the rational case, but it is natural to expect to solve this issue if we find a correct geometric framework.

Now, let's come back to the algebraic interpretation with quivers. A key aspect of the work of Van den Bergh [6] is that it also introduces non-commutative quasi-Poisson geometry. To an arbitrary quiver, considering its double, one can associate a multiplicative preprojective algebra, and construct the corresponding multiplicative quiver varieties (MQV) of Crawley-Boevey and Shaw [33]. The latter

[^1]spaces are Poisson varieties, obtained after quasi-Hamiltonian reduction from the representation spaces of the quiver path algebra, and all the geometric structure can be realized at the level of the path algebra [6]. Therefore, it is a reasonable guess to investigate this theory applied to the quivers studied in [11], and it is done by Chalykh and the author for a cyclic quiver with an extra arrow in [1]. In that case, it is shown that any MQV contains the phase space for the (non-spin) trigonometric RS system. For the simplest cyclic quiver consisting of one loop (i.e. a Jordan quiver) with $d \geq 2$ arrows coming from a new vertex, this is also done by Chalykh and the author, in the companion paper [34]. The natural generalization that these other MQV carry on an open subset the phase space for the spin trigonometric RS system of type $A_{n}$ is obtained. Henceforth, it provides a crucial step to develop the geometric theory of spin RS models farther than the rational case. The next step is to turn to the application of this method on the cyclic quiver with $m \geq 2$ vertices and $d \geq 2$ new arrows pointing towards a chosen vertex in the cycle. This is the purpose of this work, and our most important result is that any such representation space can also be seen as the natural phase space of what we suggest to be the complex trigonometric spin RS system with $W=S_{n} \ltimes \mathbb{Z}_{m}^{n}$. This provides a natural generalization of the case $m=1$ corresponding to the Jordan quiver [34]. Interestingly, there is a Poisson isomorphism between dense open subsets of the spaces corresponding to the cases $m \geq 2$ and $m=1$, hence we also obtain that the representation spaces that we construct carry the system with $W=S_{n}$. In particular, the flows defined by the symmetric functions of the corresponding Lax matrices can be explicitly integrated. We also study Liouville integrability in line with the original approach of Krichever and Zabrodin [26], which is based on the existence of a second reduction for $d \leq n$. The final step dealing with arbitrary extensions of cyclic quivers will be discussed in forthcoming works.

The article is organized as follows. In Section 2, we recall the foundations of the theory of double quasi-Poisson brackets, how we can define such brackets from quivers, and what is the counterpart to that theory on the corresponding representation spaces, based on the work of Van den Bergh [6]. Our presentation of this work relies on [1, Section 2], but we reproduce these results and add useful remarks to provide a self-contained exposition of this non-standard subject. In Section 3, we apply the algebraic part of the theory to the so-called spin cyclic quivers. We obtain their structure of quasi-Hamiltonian algebras and gather several results based on computations with the double quasi-Poisson bracket. All the proofs for that section are collected in Appendix A. The formalism employed being quite new, we suggest to the reader interested in the integrable systems side of this work to skip the first part of this article, and go directly to Section 4, where we overview the MQV associated to the spin Jordan quiver (or spin one-loop quiver) recently introduced in [34]. In Section 5, we follow the method from [34] applied to the cyclic quivers on $m \geq 2$ vertices, to get new MQV. They are generically isomorphic as complex Poisson manifolds to the space obtained in the case of a Jordan quiver reviewed in Section 4, which we prove in Appendix B. We get three families of functions in involution on such a space for each $m \geq 2$, that we write in the set of local coordinates that exists in the Jordan quiver case. In particular, one of them contains the spin RS Hamiltonian $H_{1}$. We count the number of independent elements in each family and perform an additional reduction to obtain integrability in Liouville sense. We can also get an explicit description of some flows, based on computations in Appendix C. We finish by explaining why we believe that this extra reduction should be avoided, and how the other two families corresponds to what should be seen as the spin RS system for $W=S_{n} \ltimes \mathbb{Z}_{m}^{n}$, or a modification of it.

### 1.1 Notations

The sets $\mathbb{N}, \mathbb{Z}, \mathbb{C}$ denote the non-negative integers, integers and complex numbers. We write $\mathbb{N}^{\times}, \mathbb{Z}^{\times}, \mathbb{C}^{\times}$ when we omit the zero element in those sets. Consider a finite set $J,|J|=k$, and totally ordered elements
$\left(a_{j}\right)_{j \in J}$ such that $a_{j_{1}}<\cdots<a_{j_{k}}$ for some $j_{(-)}:\{1, \ldots, k\} \rightarrow J$. Then the corresponding right and left products are defined as $\vec{\prod} a_{j}=a_{j_{1}} \ldots a_{j_{k}}$, while $\overleftarrow{\prod} a_{j}=a_{j_{k}} \ldots a_{j_{1}}$.

We write $\delta_{i j}$ or $\delta_{(i, j)}$ for Kronecker delta function. We extend this definition for a general proposition $P$ by setting $\delta_{P}=+1$ if $P$ is true and $\delta_{P}=0$ if $P$ is false. For example, $\delta_{(i \neq j)}=1-\delta_{i j}$.

Fix a positive integer $d \geq 2$. The ordering function $o:\{1, \ldots, d\}^{\times 2} \rightarrow\{0, \pm 1\}$ is defined by $o(\alpha, \beta)=+1$ if $\alpha<\beta, o(\alpha, \beta)=-1$ if $\alpha>\beta$, and $o(\alpha, \beta)=0$ if $\alpha=\beta$. In other words, it takes the value +1 if the first argument is strictly less than the second, the value 0 if they are equal, and is -1 otherwise. In terms of Kronecker delta function, we have for example $o(\alpha, \beta)=\delta_{(\alpha<\beta)}-\delta_{(\alpha>\beta)}$.

## 2. Preliminaries

We recall the necessary constructions needed in this article as they are introduced in [1], with some additional remarks. Details regarding double brackets and representation spaces can be found in [6, 35], while we refer to [33,36] for generalities on multiplicative preprojective algebras and corresponding MQV.

### 2.1 Double brackets

We review some results of [6, Sections 2-4]. We take all tensor products over $\mathbb{C}$, and fix an associative unital $\mathbb{C}$-algebra $A$. For an element $a \in A \otimes A$, we use Sweedler's notation $a^{\prime} \otimes a^{\prime \prime}$ to denote $\sum_{i} a_{i}^{\prime} \otimes a_{i}^{\prime \prime}$. We set $a^{\circ}=a^{\prime \prime} \otimes a^{\prime}$. More generally, for any $s \in S_{n}$ we define $\tau_{s}: A^{\otimes n} \rightarrow A^{\otimes n}$ by $\tau_{s}\left(a_{1} \otimes \ldots \otimes a_{n}\right)=$ $a_{s^{-1}(1)} \otimes \cdots \otimes a_{s^{-1}(n)}$, so we can write $a^{\circ}=\tau_{(12)} a$.

We view $A^{\otimes n}$ as an $A$-bimodule via the outer bimodule structure $b\left(a_{1} \otimes \ldots \otimes a_{n}\right) c=b a_{1} \otimes \cdots \otimes a_{n} c$. An $n$-bracket is a linear map $\{-, \ldots,-\}\}: A^{\otimes n} \rightarrow A^{\otimes n}$ which is a derivation in its last argument for the outer bimodule structure on $A^{\otimes n}$, and which is cyclically anti-symmetric:

$$
\tau_{(1 \ldots n)} \circ\left\{\{-, \ldots,-\} \circ \circ \tau_{(1 \ldots n)}^{-1}=(-1)^{n+1}\{\{-, \ldots,-\}\}\right.
$$

In the cases of interest, there exists a $\mathbb{C}$-algebra $B$ and a $\mathbb{C}$-algebra map $B \rightarrow A$ turning $A$ into a $B$-algebra, and we identify $B$ with its image in $A$. Then we assume that the bracket is $B$-linear, i.e. it vanishes if one argument is an element of $B$.

We focus on 2- and 3-brackets, which we call double and triple brackets, respectively. In the particular case of a double bracket, the defining relations take the form $\{\{a, b\}\}=-\{\{b, a\}\}^{\circ}$ and $\{\{a, b c\}\}=b\{\{a, c\}\}+$ $\{\{a, b\}\} c$ for any $a, b, c \in A$. This implies that $\{\{b c, a\}\}=\{\{b, a\}\} *+b *\{\{c, a\}\}$, i.e. it is a derivation in the first argument for the inner $A$-bimodule structure on $A \otimes A$ given by $b *\left(a^{\prime} \otimes a^{\prime \prime}\right) * c=a^{\prime} c \otimes b a^{\prime \prime}$. Also, any double bracket $\{\{-,-\}$ defines an induced triple bracket $\{\{-,-,-\}$ given by

$$
\begin{equation*}
\{\{a, b, c\}\}=\left\{\left\{a,\{\{b, c\}\}^{\prime}\right\}\right\} \otimes\{\{b, c\}\}^{\prime \prime}+\tau_{(123)}\left\{\left\{b,\{\{c, a\}\}^{\prime}\right\}\right\} \otimes\{\{c, a\}\}^{\prime \prime}+\tau_{(132)}\left\{\left\{c,\{\{a, b\}\}^{\prime}\right\}\right\} \otimes\{\{a, b\}\}^{\prime \prime} . \tag{2.1}
\end{equation*}
$$

In a similar way to the commutative case, $n$-brackets can be defined from analogues of $n$-vector fields. Following Crawley-Boevey [37], we assume from now on that $A$ is a $B$-algebra and we call the elements of $D_{A / B}:=\operatorname{Der}_{B}(A, A \otimes A)$ double derivations. We see $D_{A / B}$ as an $A$-bimodule by using the inner bimodule structure on $A \otimes A$. That is, if $\delta \in D_{A / B}$, then $(b \delta c)(a)=b * \delta(a) * c$ for any $a, b, c \in A$. Let $D_{B} A:=T_{A} D_{A / B}$ be the tensor algebra of this bimodule.

Proposition 2.1 [6, Proposition 4.1.1] There is a well-defined linear map $\mu:\left(D_{B} A\right)_{n} \rightarrow\{B$-linear $n$-brackets on $A\}, Q \mapsto\left\{\{-, \ldots,-\}_{Q}\right.$ which on $Q=\delta_{1} \ldots \delta_{n}$ is given by

$$
\begin{aligned}
& \{-, \ldots,-\}_{Q}=\sum_{i=0}^{n-1}(-1)^{(n-1) i} \tau_{(1 \ldots n)}^{i} \circ\left\{\{-, \ldots,-\}_{Q} \circ \tau_{(1 \ldots n)}^{-i},\right. \\
& \left\{\left\{a_{1}, \ldots, a_{n} \tilde{\}}_{Q}=\delta_{n}\left(a_{n}\right)^{\prime} \delta_{1}\left(a_{1}\right)^{\prime \prime} \otimes \delta_{1}\left(a_{1}\right)^{\prime} \delta_{2}\left(a_{2}\right)^{\prime \prime} \otimes \ldots \otimes \delta_{n-1}\left(a_{n-1}\right)^{\prime} \delta_{n}\left(a_{n}\right)^{\prime \prime}\right.\right.
\end{aligned}
$$

The map $\mu$ factors through $D_{B} A /\left[D_{B} A, D_{B} A\right]$ (for the graded commutator).
In the particular case of $\delta_{1} \delta_{2} \in\left(D_{B} A\right)_{2}$, we have for any $b, c \in A$

$$
\begin{equation*}
\{\{b, c\}\}_{\delta_{1} \delta_{2}}=\delta_{2}(c)^{\prime} \delta_{1}(b)^{\prime \prime} \otimes \delta_{1}(b)^{\prime} \delta_{2}(c)^{\prime \prime}-\delta_{1}(c)^{\prime} \delta_{2}(b)^{\prime \prime} \otimes \delta_{2}(b)^{\prime} \delta_{1}(c)^{\prime \prime} . \tag{2.2}
\end{equation*}
$$

Note also that $D_{B} A$ admits a canonical double Schouten-Nijenhuis bracket, which makes $D_{B} A$ into a double Gerstenhaber algebra [6, Sections 2.7, 3.2]. This is a (graded) double bracket, that we denote by $\left\{\{-,-\}_{\mathrm{SN}}\right.$.

For any $n \geq 2$, the multiplication map $m: A^{\otimes n} \rightarrow A$ is defined by concatenation of the factors, $m$ ( $a_{1} \otimes$ $\left.\ldots \otimes a_{n}\right)=a_{1} \ldots a_{n}$. For any $n$-bracket $\{\{-, \ldots,-\}\}$, this induces an associated bracket $\{-, \ldots,-\}:=$ $m \circ\{\{-, \ldots,-\}\}$. In the case of a double bracket,

$$
\begin{equation*}
\{a, b\}=m \circ\{\{a, b\}\}=\{\{a, b\}\}^{\prime}\{\{a, b\}\}^{\prime \prime} . \tag{2.3}
\end{equation*}
$$

Assume that the double bracket $\{[-,-\}\}$ is such that the bracket associated to the induced triple bracket (2.1) satisfies $\{-,-,-\}=0$. Then the bracket $\{-,-\}$ associated to the double bracket is a left Loday bracket (also called left Leibniz bracket), and it also satisfies Leibniz's rule in its second argument, i.e. $\{-,-\}: A \times A \rightarrow A$ is a bilinear map such that

$$
\{a,\{b, c\}\}=\{\{a, b\}, c\}+\{b,\{a, c\}\}, \quad\{a, b c\}=\{a, b\} c+b\{a, c\} .
$$

It descends to a map $A /[A, A] \times A \rightarrow A$, then to an antisymmetric map on the vector space $A /[A, A]$, so that $(A /[A, A],\{-,-\})$ is a Lie algebra $[6$, Section 2.4]. Since each map $\{a,-\}$ is a derivation on $A$, thus $\{-,-\}$ endows $A$ with a non-commutative Poisson structure in the sense of [38], called an $H_{0}$-Poisson structure.

We can extend the procedure to graded setting, and denote the bracket associated to $\left\{[-,-\}_{\}_{S N}}\right.$ as $\{-,-\}_{\mathrm{SN}}:=m \circ\{\{-,-\}\}_{\mathrm{SN}}$. Hence, the pair $\left(D_{B} A,\{-,-\}_{\mathrm{SN}}\right)$ may be viewed as a non-commutative version of the algebra of polyvector fields on a manifold with the Schouten-Nijenhuis bracket.

### 2.2 Double quasi-Poisson algebras

Consider $B$ of the form $B=\mathbb{C} e_{1} \oplus \ldots \oplus \mathbb{C} e_{K}$ with $e_{r} e_{s}=\delta_{r s} e_{s}$, so that $\sum_{s} e_{s}=1 \in A$. We define for all $s$ a double derivation $E_{s} \in D_{A / B}$ such that $E_{s}(a)=a e_{s} \otimes e_{s}-e_{s} \otimes e_{s} a$, and we call them the gauge elements. As in [6, Section 5], a double quasi-Poisson bracket on $A$ is a ( $B$-linear) double bracket $\{\{-,-\}\}$, such that the induced triple bracket satisfies $\left\{\{-,-,-\}=\frac{1}{12} \sum_{s}\left\{\{-,-,-\}_{E_{s}^{3}}\right.\right.$, where the triple brackets in the right-hand side are defined in Proposition 2.1. In this case, we say that $A$ is a double quasi-Poisson algebra. Note that the associated brackets $\{-,-,-\}_{E_{s}^{3}}$ are identically zero, so that the
double quasi-Poisson bracket $\{\{-,-\}\}$ on $A$ defines a left Loday bracket $\{-,-\}$ by (2.3), which descends to a Lie bracket on $A /[A, A]$. Assume that there is an element $P \in\left(D_{B} A\right)_{2}$ such that $\{P, P\}_{\mathrm{SN}}=\frac{1}{6} \sum_{s} E_{s}^{3}$ $\bmod \left[D_{B} A, D_{B} A\right]$ (for the graded commutator). Then, we say that $A$ is a differential double quasi-Poisson algebra with the differential double quasi-Poisson bracket $\{-,-\}_{P}$. This implies that $\left\{\{-,-\}_{P}\right.$ is a double quasi-Poisson bracket using [6, Theorem 4.2.3].

A multiplicative moment map for a double quasi-Poisson algebra ( $A,\{[-,-\}\}$ ) is an element $\Phi=$ $\sum_{s=1}^{K} \Phi_{s}$ with $\Phi_{s} \in e_{s} A e_{s}$ such that we have $\left\{\left\{\Phi_{s},-\right\}\right\}=\frac{1}{2}\left(\Phi_{s} E_{s}+E_{s} \Phi_{s}\right) \in D_{A / B}$ for any $s$. This condition may be written explicitly as requiring for all $a \in A$

$$
\begin{equation*}
\left.\left\{\Phi_{s}, a\right\}\right\}=\frac{1}{2}\left(\Phi_{s} E_{s}+E_{s} \Phi_{s}\right)(a)=\frac{1}{2}\left(a e_{s} \otimes \Phi_{s}-e_{s} \otimes \Phi_{s} a+a \Phi_{s} \otimes e_{s}-\Phi_{s} \otimes e_{s} a\right) . \tag{2.4}
\end{equation*}
$$

When a double quasi-Poisson algebra is equipped with a multiplicative moment map, we say that it is a quasi-Hamiltonian algebra.

Combining (2.3) and (2.4), we obtain $\{\Phi, a\}=a \Phi-\Phi a$ and $\{a, \Phi\}=0$ for any $a \in A$. Hence, if $q_{0} \in \mathbb{C}$ and $\{-,-\}$ is the left Loday bracket obtained from the double bracket on $A$, we get that $\left\{J_{0}, A\right\} \subset J_{0},\left\{A, J_{0}\right\} \subset J_{0}$ for $J_{0}$ the ideal generated by $\Phi-q_{0}$. Therefore, $A / J_{0}$ is a left Loday algebra. If we consider $q=\sum_{s} q_{s} e_{s} \in B$ and write $J$ for the ideal generated by $\Phi-q$, we only have $\{A, J\} \subset J$ in general, so that $A_{q}:=A / J$ is not necessarily a left Loday algebra. Nevertheless, since $\{J, A\} \subset J$ modulo commutators, the vector space $A_{q} /\left[A_{q}, A_{q}\right]$ is a Lie algebra for the Lie bracket obtained from $\{-,-\}$ through $A \rightarrow A_{q} /\left[A_{q}, A_{q}\right]$. This endows $A_{q}$ with an $H_{0}$-Poisson structure [6, Proposition 5.1.5].

Finally, assume that $A$ is (formally) smooth. If $A$ is a double quasi-Poisson algebra with double bracket defined by $P \in\left(D_{B} A\right)_{2}$, we say that the element $P$ is non-degenerate if the map of $A$-bimodules $\Omega_{B}^{1} A \oplus\left(\oplus_{s} A E_{s} A\right) \rightarrow D_{A / B}$ given by (b.da.c, $\left.\delta\right) \mapsto b\left\{\{a,-\}_{P} c+\delta\right.$ is surjective. Here, $\left\{\{-,-\}_{P}\right.$ is the double bracket defined by Proposition 2.1, and $\Omega_{B}^{1} A$ refer to the bimodule of non-commutative relative 1 -forms [39, Section 2]. We refer to the brilliant work of Van den Bergh [35] for details and the relation to a 'double version' of [15].

### 2.3 Multiplicative preprojective algebras

Let $Q=(Q, I)$ be a quiver with vertex set $I$ and arrow set $Q$, and consider the maps $t, h: Q \rightarrow I$ that associate to every arrow $a$ its tail and head, $t(a)$ and $h(a)$. We construct the double $\bar{Q}$ of $Q$ by adjoining to every $a \in Q$ an opposite arrow, denoted $a^{*}$. We naturally extend $t$ and $h$, so that $t(a)=h\left(a^{*}\right)$ and $h(a)=t\left(a^{*}\right)$. We define $\epsilon: \bar{Q} \rightarrow\{ \pm 1\}$ the function that takes value +1 on arrows of $Q$, and -1 on each arrow of $\bar{Q} \backslash Q$. We write $\mathbb{C} \bar{Q}$ for the path algebra of $\bar{Q}$, whose underlying vector space is spanned by all possible paths formed on $\bar{Q}$ (including each trivial path $e_{s}$ associated to $s \in I$ ). The multiplication is given by concatenation of paths, and in particular the $\left(e_{s}\right)_{s}$ form a complete set of orthogonal idempotents. We view $\mathbb{C} \bar{Q}$ as a $B$-algebra, with $B=\oplus_{s \in I} \mathbb{C} e_{s}$. Finally, we extend $*$ to an involution on $\mathbb{C} \bar{Q}$ by setting $\left(a^{*}\right)^{*}=a$ for all $a \in Q$.

Remark 2.2 As in [1, 6], we write paths in $\mathbb{C} \bar{Q}$ from left to right. Hence, $a b$ means ' $a$ followed by $b$ ', and the path $a b$ is trivially zero if $h(a) \neq t(b)$.

Let $A$ be obtained from $\mathbb{C} \bar{Q}$ by inverting all elements $\left(1+a a^{*}\right)_{a \in \bar{Q}}$. For all $a \in \bar{Q}$, define the element $\frac{\partial}{\partial a}$ of $D_{B} A$ which on $b \in \bar{Q}$ acts as

$$
\frac{\partial b}{\partial a}= \begin{cases}e_{t(a)} \otimes e_{h(a)} & \text { if } a=b  \tag{2.5}\\ 0 & \text { otherwise }\end{cases}
$$

We consider a minor generalization of the construction of multiplicative preprojective algebra, without the use of a total ordering on the arrows of the quiver, see the first remark at the end of [1, Section 2.5]. For each $s \in I$, we fix a total ordering $<_{s}$ on the arrows meeting at $s$, that is on all $a \in \bar{Q}$ with $h(a)=s$ or $t(a)=s$. We also assume that if two arrows $a, b$ meet at $s$ and $r$, then either we have both $a<_{s} b$ and $a<_{r} b$ or we have both $b<_{s} a$ and $b<_{r} a$. We denote such a relation by $<$ and refer to is as an ordering, though it is not necessarily a partial order. ${ }^{2}$ We define the element $\Phi=\left(\Phi_{s}\right)_{s} \in \oplus_{s} e_{s} A e_{s}$ by
where the product is taken with respect to the ordering, see Section 1.1. Following [33], given $q=$ $\sum_{s \in I} q_{s} e_{s}$ with $q_{s} \in \mathbb{C}^{\times}$, we define the (deformed) multiplicative preprojective algebra as the quotient $\Lambda^{q}=A /(\Phi-q)$. Up to isomorphism, the algebra $\Lambda^{q}$ is independent of the ordering [33, Theorem 1.4].

The next result states that $\Phi$ is a moment map for a specific quasi-Hamiltonian algebra structure on A. In particular, we have an $H_{0}$-Poisson structure on $\Lambda^{q}$ by Section 2.2.

Theorem 2.3 [ 6 , Theorem 6.7.1] The algebra $A$ is quasi-Hamiltonian for the differential double quasiPoisson bracket defined by

$$
\begin{equation*}
\mathrm{P}=\frac{1}{2} \sum_{a \in \bar{Q}} \epsilon(a)\left(1+a^{*} a\right) \frac{\partial}{\partial a} \frac{\partial}{\partial a^{*}}-\frac{1}{2} \sum_{\substack{a, b \in \bar{Q} \\ t(a)=t(b), a<b}}\left(\frac{\partial}{\partial a^{*}} a^{*}-a \frac{\partial}{\partial a}\right)\left(\frac{\partial}{\partial b^{*}} b^{*}-b \frac{\partial}{\partial b}\right), \tag{2.7}
\end{equation*}
$$

and the multiplicative moment map given by $\Phi=\left(\Phi_{s}\right)_{s}$, where $\Phi_{s}$ is defined in (2.6).
In fact, P is non-degenerate by [35, Section 8]. The following result gives an explicit form to the double quasi-Poisson bracket which we denote as $\{\{-,-\}$, and that is defined by P using Proposition 2.1.

Proposition 2.4 [1, Proposition 2.6] Take an ordering in $\bar{Q}$ so that the arrows of $\bar{Q}$ are ordered in such a way that $a<a^{*}<b<b^{*}$ for any $a, b \in Q$ with $a<b$. Then one has

$$
\begin{align*}
\{a, a\}\} & =\frac{1}{2} \epsilon(a)\left(a^{2} \otimes e_{t(a)}-e_{h(a)} \otimes a^{2}\right) \delta_{h(a), t(a)}  \tag{2.8a}\\
\left\{\left\{a, a^{*}\right\}\right\} & =e_{h(a)} \otimes e_{t(a)}+\frac{1}{2} a^{*} a \otimes e_{t(a)}+\frac{1}{2} e_{h(a)} \otimes a a^{*}
\end{align*}
$$

[^2]\[

$$
\begin{align*}
& +\frac{1}{2}\left(a^{*} \otimes a-a \otimes a^{*}\right) \delta_{h(a), t(a)}  \tag{2.8b}\\
\{a, b\}\} & =\frac{1}{2}\left(e_{h(a)} \otimes a b\right) \delta_{h(a), t(b)}+\frac{1}{2}\left(b a \otimes e_{t(a)}\right) \delta_{h(b), t(a)} \\
& -\frac{1}{2}(b \otimes a) \delta_{h(a), h(b)}-\frac{1}{2}(a \otimes b) \delta_{t(a), t(b)} \quad\left(a, b \in \bar{Q}, a<b, b \neq a^{*}\right) . \tag{2.8c}
\end{align*}
$$
\]

This defines all double brackets since when $a>b,\{\{a, b\}\}=-\{\{b, a\}\}^{\circ}$.
We finish by a remark on the structure of the moment map of a subquiver. assume that $\bar{Q}^{\prime}$ is a quiver with vertex set $I^{\prime} \subset I$ and $\bar{Q}^{\prime}=\left\{a \in \bar{Q} \mid t(a) \in I^{\prime}\right.$ and $\left.h(a) \in I^{\prime}\right\}$. This means that if we look at the subset of vertices $I^{\prime}$ of $\bar{Q}$ and erase all the arrows of $\bar{Q}$ which are not both starting and ending at an element of $I^{\prime}$, we get $\bar{Q}^{\prime}$. Moreover, we require that $\bar{Q}$ and $\bar{Q}^{\prime}$ are endowed respectively with orderings $<,<^{\prime}$ such that, whenever $a, b \in \bar{Q}^{\prime}, a<^{\prime} b$ if $a<b$ in the initial quiver $\bar{Q}$, and whenever $a \in \bar{Q}^{\prime}$ but $c \in \bar{Q} \backslash \bar{Q}^{\prime}$ we have $a<c$.

We construct $A^{\prime}$ as $A$ above, and we see $A^{\prime}$ as a subalgebra of $A$ (after adding the removed idempotents $e_{s}$ for $s \in I \backslash I^{\prime}$ ). Define elements $\Phi^{\prime}, \mathrm{P}^{\prime}$ by replacing $\bar{Q}$ with $\bar{Q}^{\prime}$ in (2.6) and (2.7). Remark that we can write $\mathrm{P}=\mathrm{P}^{\prime}+\mathrm{P}_{\text {out }}$ and $\Phi=\left(\Phi+\sum_{s \notin I^{\prime}} e_{s}\right) \Phi_{\text {out }}$ for some $\mathrm{P}_{\text {out }} \in\left(D_{B} A\right)_{2}$ and $\Phi_{\text {out }}=\left(\Phi_{\text {out, } s}\right)_{s \in I}$. Last statement is, in fact, a consequence of the fusion process which is used to endow a quiver with a quasi-Hamiltonian structure [6, Sections 6.5-6.7].

Lemma 2.5 For all $b, c \in A^{\prime} \subset A$, we have $\{\{b, c\}\}_{P}=\left\{\{b, c\}_{P^{\prime}}\right.$. In particular, for all $s \in I^{\prime}$, we have $\left\{\left\{\Phi_{s}^{\prime}, c\right\}\right\}_{\mathrm{P}}=\frac{1}{2}\left(\Phi_{s}^{\prime} E_{s}+E_{s} \Phi_{s}^{\prime}\right)(c)$.

Proof. By linearity of the map in Proposition 2.1, we can write $\left\{\{-,-\}_{\mathrm{P}^{\prime}}=\left\{\{-,-\}_{\mathrm{P}}+\left\{\{-,-\}_{\mathrm{P}_{\text {out }}}\right.\right.\right.$. From (2.2), we get that $\{b, c\}\}_{P_{\text {out }}}$ is a sum of terms of the form

$$
\begin{equation*}
\delta_{2}(c)^{\prime} \delta_{1}(b)^{\prime \prime} \otimes \delta_{1}(b)^{\prime} \delta_{2}(c)^{\prime \prime}-\delta_{1}(c)^{\prime} \delta_{2}(b)^{\prime \prime} \otimes \delta_{2}(b)^{\prime} \delta_{1}(c)^{\prime \prime} \tag{2.9}
\end{equation*}
$$

for any $b, c \in A$. By construction, $\mathrm{P}_{\text {out }}$ is a sum of (double) biderivations, and each biderivation carries at least one factor $\partial / \partial d$ for $d \in \bar{Q} \backslash \bar{Q}^{\prime}$. Therefore, if both $b, c \in A^{\prime}$, all terms in (2.9) must vanish, and $\left\{\{b, c\}_{\mathrm{P}_{\text {out }}}=0\right.$.

Applying this to $\Phi_{s}^{\prime}$ and $c \in A^{\prime},\left\{\left\{\Phi_{s}^{\prime}, c\right\}\right\}_{\mathrm{P}}=\left\{\left\{\Phi_{s}^{\prime}, c\right\}\right\}_{\mathrm{P}^{\prime}}$. By construction, $\Phi^{\prime}$ is a multiplicative moment map for $\{\{-,-\}\}_{P^{\prime}}$, so it satisfies (2.4).

### 2.4 Geometric counterpart to the definitions

Fix a $\mathbb{C}$-algebra $A$ and $N \in \mathbb{N}$. The representation space $\operatorname{Rep}(A, N)$ is the affine scheme whose coordinate ring $\mathrm{O}(\operatorname{Rep}(A, N))$ is generated by symbols $a_{i j}$ for $a \in A$ and $i, j=1, \ldots, N$, such that they are $\mathbb{C}$-linear in $a$, they satisfy $(a b)_{i j}=\sum_{k} a_{i k} b_{k j}$ for any $a, b \in A$, and $1_{i j}=\delta_{i j}$. Alternatively, we can see $\operatorname{Rep}(A, N)$ as parametrising algebra homomorphisms $\varrho: A \rightarrow \operatorname{Mat}_{N}(\mathbb{C})$, and we get $a_{i j}(\varrho)=\varrho(a)_{i j}$ at any point $\varrho \in \operatorname{Rep}(A, N)$. Following [6, Section 7], to any $a \in A$ we associate a matrix-valued function $\mathcal{X}(a):=$ $\left(a_{i j}\right)_{i j}$ on $\operatorname{Rep}(A, N)$. Similarly, any double derivation $\delta \in \operatorname{Der}(A, A \otimes A)$ gives rise to a matrix-valued vector field $\mathcal{X}(\delta)=\left(\delta_{i j}\right)_{i j}$ on $\operatorname{Rep}(A, N)$, where $\delta_{i j}$ is a derivation of $\mathrm{O}(\operatorname{Rep}(A, N))$ defined by the rule $\delta_{i j}\left(a_{u v}\right)=\delta^{\prime}(a)_{u j} \delta^{\prime \prime}(a)_{i v}$. In particular, if $\{[-,-\}\}$ is a double bracket on $A$, we have for any $a \in A$ that the double derivation $\{\{a,-\}\}$ defines a matrix-valued vector field $X_{a}$ such that $\left(X_{a}\right)_{i j}\left(b_{u v}\right)=\left\{\{a, b\}_{u j}^{\prime}\left\{\{a, b\}_{i v}^{\prime \prime}\right.\right.$.

We can generalize the definition in a relative setting for a $B$-algebra $A$, where $B$ is of the form $B=\mathbb{C} e_{1} \oplus \cdots \oplus \mathbb{C} e_{K}$ with $e_{r} e_{s}=\delta_{r s} e_{s}$. Representation spaces are now indexed by $K$-tuples $\alpha=$ $\left(\alpha_{1}, \ldots, \alpha_{K}\right) \in \mathbb{N}^{K}$. Given $\alpha$ with $\alpha_{1}+\cdots+\alpha_{K}=N$, we embed $B$ diagonally into Mat ${ }_{N}(\mathbb{C})$ so that $\mathrm{Id}_{N}$ is split into a sum of $K$ diagonal blocks of respective sizes $\alpha_{1}, \ldots, \alpha_{K}$, representing the idempotents $\left(e_{s}\right)_{s}$. By definition, $\operatorname{Rep}_{B}(A, \alpha)=\operatorname{Hom}_{B}\left(A, \operatorname{Mat}_{N}(\mathbb{C})\right)$, and it can be viewed as an affine scheme in the same way as $\operatorname{Rep}(A, N)$. Note in particular that for any $\Phi \in \oplus_{s} e_{s} A e_{s}$, the matrix-valued function $\mathcal{X}(\Phi)$ on $\operatorname{Rep}_{B}(A, \alpha)$ is a block matrix $\mathcal{X}(\Phi) \in \prod_{s} \operatorname{Mat}_{\alpha_{s}}(\mathbb{C})$.

Assume that $A$ is equipped with a $B$-linear double bracket $\{[-,-\}\}$. Then the representation spaces are endowed with an anti-symmetric biderivation as follows.

Proposition 2.6 [6, Proposition 7.5.1, Section 7.8] There is a unique anti-symmetric biderivation $\{-,-\}$ : $\mathrm{O}\left(\operatorname{Rep}_{B}(A, \alpha)\right) \times \mathrm{O}\left(\operatorname{Rep}_{B}(A, \alpha)\right) \rightarrow \mathrm{O}\left(\operatorname{Rep}_{B}(A, \alpha)\right)$ such that for all $a, b \in A$,

$$
\begin{equation*}
\left\{a_{i j}, b_{u v}\right\}=\left\{\{ a , b \} _ { u j } ^ { \prime } \left\{\{a, b\}_{i v}^{\prime \prime} .\right.\right. \tag{2.10}
\end{equation*}
$$

Moreover, if $\{\{-,-\}\}=\{\{-,-\}\}_{P}$ for some $P \in\left(D_{B} A\right)_{2}$, then $\{-,-\}$ is defined by the bivector field $\operatorname{tr}(\mathcal{X}(P))$ and we denote it by $\{-,-\}_{P}$.

The identity (2.10) extends to relate the double bracket $\left\{[-,-\}_{\mathrm{SN}}\right.$ on $D_{B} A$ with the Schouten-Nijenhuis bracket [,-- ] between polyvector fields on $\operatorname{Rep}_{B}(A, \alpha)$ [6, Proposition 7.6.1].

On $\operatorname{Rep}(A, N)$ we have a natural action of $\mathrm{GL}_{N}$, induced by conjugation action on $\mathrm{Mat}_{N}(\mathbb{C})$. Similarly, we have an action of $\mathrm{GL}_{\alpha}=\prod_{s} \mathrm{GL}_{\alpha_{s}}$ on $\operatorname{Rep}_{B}(A, \alpha)$. Provided that $A$ is quasi-Hamiltonian, $\operatorname{Rep}_{B}(A, \alpha)$ is a quasi-Hamiltonian manifold [14], as defined now in the smooth case (see [6, Sections 7.11-7.13] for the algebraic case).

Let $G$ be a Lie group with Lie algebra $\mathfrak{g}$. Moreover, assume that $\mathfrak{g}$ admits a non-degenerate $G$-invariant bilinear form $(-,-)$. If $\left(e_{a}\right),\left(e^{a}\right)$ are dual bases of $\mathfrak{g}$ with respect to $(-,-)$, we define the Cartan 3 -tensor $\phi=\frac{1}{12} C^{a b c} e_{a} \wedge e_{b} \wedge e_{c}$, for $C^{a b c}=\left(e^{a},\left[e^{b}, e^{c}\right]\right)$ the tensor of structure constants. For all $\xi \in \mathfrak{g}$, write $\xi^{L}$ and $\xi^{R}$ to denote the left and right invariant vector fields on $G$, respectively.

Given a $G$-manifold $M$, the $G$-action gives rise to a Lie algebra homomorphism $(-)_{M}: \mathfrak{g} \rightarrow$ Der $\mathrm{O}(M)$. This can be extended to polyvector fields and we can define the 3-tensor $\phi_{M}$. We say that $M$ is a quasi-Poisson manifold if there exists an invariant bivector field $P$ on $M$ such that $[P, P]=\phi_{M}$ under the Schouten-Nijenhuis bracket. We can use $P$ to define a bracket $\{-,-\}$ on $\mathrm{O}(M)$ in the obvious way.

A multiplicative moment map is an Ad-equivariant map $\Phi: M \rightarrow G$ satisfying

$$
\begin{equation*}
\{g \circ \Phi,-\}=\frac{1}{2}\left(\left(e_{a}^{L}+e_{a}^{R}\right)(g) \circ \Phi\right)\left(e^{a}\right)_{M}, \tag{2.11}
\end{equation*}
$$

for all functions $g \in \mathrm{O}(G)$, and we say that the triple $(M, P, \Phi)$ is a Hamiltonian quasi-Poisson manifold. In the case where the action of $G$ on $M$ is free and proper, for each conjugacy class $\mathcal{C}_{g}$ of $g \in G$ we can form the Poisson manifold $\Phi^{-1}\left(\mathcal{C}_{g}\right) / G$. This process is called quasi-Hamiltonian reduction.

Theorem 2.7 [ 6 , Section 7.8, 7.13] Assume that $(A, P)$ is a differential double quasi-Poisson algebra, which is quasi-Hamiltonian for the multiplicative moment map $\Phi \in \oplus_{s} e_{s} A e_{s}$. We have that $\operatorname{Rep}_{B}(A, \alpha)$ is a $\mathrm{GL}_{\alpha}$-space with a quasi-Poisson bracket $\{-,-\}_{P}$ determined from $\{\{-,-\}\}_{P}$ by (2.10). Then the matrixvalued function $\mathcal{X}(\Phi): \operatorname{Rep}_{B}(A, \alpha) \rightarrow \prod_{s} \operatorname{Mat}_{\alpha_{s}}(\mathbb{C})$ is a multiplicative moment map for $\operatorname{Rep}_{B}(A, \alpha)$. Therefore, if it smooth, $\operatorname{Rep}_{B}(A, \alpha)$ is a Hamiltonian quasi-Poisson manifold.

We can note that any multiple of the identity $\operatorname{Id}_{\alpha}=\prod_{s} \operatorname{Id}_{\alpha_{s}}$ acts trivially on $\operatorname{Rep}_{B}(A, \alpha)$. This leads us to define

$$
\begin{equation*}
G(\alpha)=\left(\prod_{s \in I} \mathrm{GL}_{\alpha_{s}}\right) / \mathbb{C}^{\times} \tag{2.12}
\end{equation*}
$$

where $\mathbb{C}^{\times} \subset \mathrm{GL}_{\alpha}$ is the subgroup $\left\{\lambda \operatorname{Id}_{\alpha} \mid \lambda \in \mathbb{C}^{\times}\right\}$. Combining Theorem 2.7 with [35, Proposition 5.2] and [14, Theorem 10.3], we obtain

Corollary 2.8 Assume that $(A, P, \Phi)$ is a quasi-Hamiltonian algebra, with $P$ non-degenerate. If $\mathcal{C}_{g} \subset$ $\mathrm{GL}_{\alpha}$ is a conjugacy class such that $Y:=\mathcal{X}(\Phi)^{-1}\left(\mathcal{C}_{g}\right)$ is smooth, and if the action of $G(\alpha)$ on $Y$ is free and the affine GIT quotient $Y / / G$ is a geometric quotient, then it is a Poisson manifold with non-degenerate Poisson bracket defined by $\operatorname{tr}(\mathcal{X}(\mathrm{P}))$, that we denote $Y / G$.

Note that in the case where the conjugacy class is given by $\prod_{s} q_{s} \mathrm{Id}_{\alpha_{s}}$ with all $q_{s} \in \mathbb{C}^{\times}$, we know that $Y / / G$ has a Poisson bracket because $A /\left(\Phi-\sum_{s} q_{s} e_{s}\right)$ has an $H_{0}$-Poisson structure by [38, Section 4]. However, we need the quasi-Poisson formalism to conclude that the Poisson bracket is non-degenerate in Corollary 2.8.

Now, fix a conjugacy class $\mathcal{C}_{g}$ in $\operatorname{Lie}\left(\mathrm{GL}_{\alpha}\right)$ and assume that $F, G \in \mathrm{O}\left(\mathcal{X}(\Phi)^{-1}\left(\mathcal{C}_{g}\right)\right)$ are invariant under the $\mathrm{GL}_{\alpha}$ action. We can write $F=\operatorname{tr}(\mathcal{X}(a))$ and $G=\operatorname{tr}(\mathcal{X}(b))$ for some $a, b \in A$. Assuming that all spaces involved are smooth, we get from Proposition 2.6, Theorem 2.7 and (2.3) that

$$
\begin{equation*}
\{F, G\}_{P}=\operatorname{tr} \mathcal{X}\left(\{\{a, b\}\}^{\prime}\{\{a, b\}\}^{\prime \prime}\right)=\operatorname{tr} \mathcal{X}(\{a, b\}), \tag{2.13}
\end{equation*}
$$

where the bracket on the right-hand side is the associated bracket $\{-,-\}=m \circ\{[-,-\}$. In particular, we only need to compute $\{a, b\}$ modulo commutators in $A /[A, A]$ to get the Poisson bracket between $\operatorname{tr}(\mathcal{X}(a))$ and $\operatorname{tr}(\mathcal{X}(b))$. In slightly more general setting, given arbitrary $a, b \in A$ we find in the same way

$$
\begin{equation*}
\{\operatorname{tr}(\mathcal{X}(a)), \mathcal{X}(b)\}_{P}=\mathcal{X}(\{a, b\}), \tag{2.14}
\end{equation*}
$$

where this time we have the associated bracket $\{-,-\}: A /[A, A] \times A \rightarrow A$.

### 2.5 Multiplicative quiver varieties

From now on, fix $B=\oplus_{s \in I} \mathbb{C} e_{s}$ as in Section 2.3. We always work in a relative setting and omit the subscript $B$ from the notation. The matrix $\mathcal{X}(a)$ representing an element $a \in A$ is an $|I| \times|I|$ block matrix. In the case of an arrow $a \in \bar{Q}$, we can use the idempotents to write $a=e_{t(a)} a e_{h(a)}$, so $a$ is represented by a matrix with at most one non-zero block of size $\alpha_{t(a)} \times \alpha_{h(a)}$ placed in the $t(a)$ th block row and $h(a)$ th block column. Therefore, this can be viewed as a quiver representation, consisting of vector spaces $\mathcal{V}_{s}=\mathbb{C}^{\alpha_{s}}$, $s \in I$ and linear maps $X_{a}: \mathcal{V}_{h(a)} \rightarrow \mathcal{V}_{t(a)}$ for each $a \in \bar{Q}$. With this interpretation, we have

$$
\begin{equation*}
X_{a} \in \operatorname{Mat}_{\alpha_{t(a)}, \alpha_{h(a)}}(\mathbb{C}), \quad \operatorname{Rep}(\mathbb{C} \bar{Q}, \alpha) \cong \prod_{a \in \bar{Q}} \operatorname{Mat}_{\alpha_{t(a)}, \alpha_{h(a)}}(\mathbb{C}) . \tag{2.15}
\end{equation*}
$$

Next, $\operatorname{Rep}(A, \alpha)$ is an affine open subset of $\operatorname{Rep}(\mathbb{C} \bar{Q}, \alpha)$, so it is also smooth. It is naturally acted on by $\prod_{i \in I} \mathrm{GL}_{\alpha_{s}}$ through conjugation. This induces an action of $G(\alpha)$ as defined in (2.12). By Theorems 2.3 and
2.7, and Proposition 2.6, $\operatorname{Rep}(A, \alpha)$ is a quasi-Hamiltonian $G(\alpha)$-manifold, with quasi-Poisson bracket defined by the bivector $\operatorname{tr}(\mathcal{X}(\mathrm{P}))$ and with multiplicative moment map $\mathcal{X}(\Phi)$. The representation space $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ corresponds to the subset such that $\mathcal{X}(\Phi)=\prod_{s} q_{s} \operatorname{Id}_{\alpha_{s}}$, so it is a closed affine subvariety in $\operatorname{Rep}(A, \alpha)$. We set $q^{\alpha}=\prod_{s \in I} q^{\alpha_{s}}$, and note that $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ is empty when $q^{\alpha} \neq 1$ by [33, Lemma 1.5].

The points in the affine variety $\mathcal{S}_{\alpha, q}:=\operatorname{Rep}\left(\Lambda^{q}, \alpha\right) / / G(\alpha)$ are closed $G(\alpha)$ orbits of $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$, so correspond to semi-simple representations of $\Lambda^{q}$ of dimension $\alpha$. In the case where all representations in $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ are simple, we have the following description of the space.

Theorem 2.9 [1, Theorem 2.8] Let $p(\alpha)=1+\sum_{a \in Q} \alpha_{t(a)} \alpha_{h(a)}-\alpha \cdot \alpha$, where $\alpha \cdot \alpha=\sum_{s \in I} \alpha_{s}^{2}$. Suppose that $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ is non-empty and all representations in $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ are simple. Then $\alpha$ is a positive root of $Q$ and $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$ is a smooth affine variety of dimension $g+2 p(\alpha)$, with $g=\operatorname{dim} G(\alpha)=\alpha \cdot \alpha-1$. The group $G(\alpha)$ acts freely on $\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)$, so $\mathcal{S}_{\alpha, q}=\operatorname{Rep}\left(\Lambda^{q}, \alpha\right) / G(\alpha)$ is a Poisson manifold of dimension $2 p(\alpha)$, obtained by quasi-Hamiltonian reduction.

As we explained in Section 2.4, the Poisson bracket on $\mathrm{O}\left(\mathcal{S}_{\alpha, q}\right)=\mathrm{O}\left(\operatorname{Rep}\left(\Lambda^{q}, \alpha\right)\right)^{G(\alpha)}$ is obtained from the $G(\alpha)$-invariant bivector field $\operatorname{tr}(\mathcal{X}(\mathrm{P}))$. Moreover, since P is non-degenerate by [35, Section 8], Corollary 2.8 yields that $\mathcal{S}_{\alpha, q}$ is a symplectic manifold when any representation in $\underset{\sim}{\operatorname{Rep}}\left(\Lambda^{q}, \alpha\right)$ is simple.

Let $Q$ be an arbitrary quiver with vertex set $I$. A framing of $Q$ is a quiver $\widetilde{Q}$ with set of vertices $\widetilde{I}=I \cup\{\infty\}$ and whose arrows are the ones of $Q$ together with additional arrows $\infty \rightarrow s$ to the vertices of $Q$. We allow multiple arrows to a single vertex. Given arbitrary $\alpha \in \mathbb{N}^{I}$ and $q \in\left(\mathbb{C}^{\times}\right)^{I}$, we extend them from $I$ to $\widetilde{I}$ by putting $\alpha_{\infty}=1$ and $q_{\infty}=q^{-\alpha}$, i.e. $\widetilde{\alpha}=(1, \alpha)$ and $\widetilde{q}=q^{-\alpha} e_{\infty}+\sum_{s \in I} q_{s} e_{s}$. By construction $\widetilde{q}^{\tilde{\alpha}}=1$. We can consider the multiplicative preprojective algebra of $\widetilde{Q}$ with parameter $\widetilde{q}$, and consider the representation space $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right)$. We refer to the quotients

$$
\begin{equation*}
\widetilde{\mathcal{M}}_{\alpha, q}(Q):=\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right) / / G(\widetilde{\alpha}), \quad \text { where } G(\widetilde{\alpha}) \cong \prod_{s \in I} \mathrm{GL}_{\alpha_{s}}=\mathrm{GL}_{\alpha} \tag{2.16}
\end{equation*}
$$

as multiplicative quiver varieties, that we abbreviate MQV.
We say that $q=\sum_{s \in I} q_{s} e_{s}$ is regular if $q^{\alpha} \neq 1$ for any root $\alpha$ of the quiver $Q$. We have the following result, which is a multiplicative analogue of [3, Theorem 2.8] and [40, Proposition 3].

Proposition 2.10 [1, Proposition 2.9] Choose an arbitrary framing $\widetilde{Q}$ of $Q$ and let $\widetilde{\alpha}$ and $\widetilde{q}$ be defined as above. If $q$ is regular, then every module of dimension $\widetilde{\alpha}$ over the multiplicative preprojective algebra $\Lambda^{\widetilde{q}}$ is simple. Hence, the group $\mathrm{GL}_{\alpha}$ acts freely on $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right)$ and the $\operatorname{MQV} \widetilde{\mathcal{M}}_{\alpha, q}(Q)$ is smooth.

When $q$ is regular and $\widetilde{\mathcal{M}}_{\alpha, q}(Q) \neq \emptyset$, this implies that $\widetilde{\alpha}=(1, \alpha)$ is a positive root of $\widetilde{Q}$ and $\widetilde{\mathcal{M}}_{\alpha, q}(Q)$ is a smooth affine variety of dimension $2 p(\widetilde{\alpha})$ by Theorem 2.9.

## 3. Quasi-Hamiltonian algebra structure

The developments of this section are parallel to [1,34], and can be seen as application of Van den Bergh's work [6] that we recalled in Sections 2.1-2.3. Fix $m, d \geq 2$ and let $I=\mathbb{Z} / m \mathbb{Z}$. Except when it is stated differently, we assume for the rest of this article that we take the indices $r, s$ in $I$, and that the Greek letters $\alpha, \beta, \gamma, \epsilon$ placed as indices always range through $1, \ldots, d$.

By a spin cyclic quiver, we mean the double quiver $\bar{Q}$ of a quiver $Q$, where $Q$ has $m+1$ vertices labelled by $I \cup\{\infty\}$, $m$ arrows $x_{s}: s \rightarrow s+1$ and $d$ framing arrows $v_{1}, \ldots, v_{d}: \infty \rightarrow 0$. We write for the
doubles $y_{s}=x_{s}^{*}: s+1 \rightarrow s$ and $w_{\alpha}=v_{\alpha}^{*}: 0 \rightarrow \infty$. We consider the following ordering at each vertex

$$
\begin{array}{lr}
\text { at } \infty: & v_{1}<w_{1}<\cdots<v_{d}<w_{d}, \\
\text { at } s \in I \backslash\{0\}: & x_{s}<y_{s}<x_{s-1}<y_{s-1}, \\
\text { at } 0: & x_{0}<y_{0}<x_{m-1}<y_{m-1}<v_{1}<w_{1}<\cdots<v_{d}<w_{d} .
\end{array}
$$

We form the algebra $A$ obtained by inverting all the elements $\left(1+a a^{*}\right)_{a \in \bar{Q}}$ in $\mathbb{C} \bar{Q}$. Using Proposition 2.4, we get a double quasi-Poisson bracket on $A$, which satisfies the following identities between the arrows of the cycle

$$
\begin{align*}
\left\{\left\{x_{r}, x_{s}\right\}=\right. & \frac{1}{2} x_{r-1} x_{r} \otimes e_{r} \delta_{(s, r-1)}-\frac{1}{2} e_{r+1} \otimes x_{r} x_{r+1} \delta_{(s, r+1)},  \tag{3.1a}\\
\left\{\left\{y_{r}, y_{s}\right\}=\right. & \frac{1}{2} e_{r} \otimes y_{r} y_{r-1} \delta_{(s, r-1)}-\frac{1}{2} y_{r+1} y_{r} \otimes e_{r+1} \delta_{(s, r+1)},  \tag{3.1b}\\
\left\{\left\{x_{r}, y_{s}\right\}=\right. & \delta_{s r}\left(e_{r+1} \otimes e_{r}+\frac{1}{2} y_{r} x_{r} \otimes e_{r}+\frac{1}{2} e_{r+1} \otimes x_{r} y_{r}\right) \\
& -\frac{1}{2} x_{r} \otimes y_{r-1} \delta_{(s, r-1)}+\frac{1}{2} y_{r+1} \otimes x_{r} \delta_{(s, r+1)} . \tag{3.1c}
\end{align*}
$$

Note the difference of signs for last two terms in (3.1c) compared to [1, (4.1c)], which is a consequence of the different ordering taken at each vertex $s \in I$. The double brackets involving elements of the cycle and framing arrows are determined by

$$
\begin{align*}
& \left\{\left\{x_{r}, w_{\alpha}\right\}\right\}=\frac{1}{2} \delta_{(r, m-1)} e_{r+1} \otimes x_{r} w_{\alpha}-\frac{1}{2} \delta_{(r, 0)} x_{r} \otimes w_{\alpha},  \tag{3.2a}\\
& \left\{\left\{x_{r}, v_{\alpha}\right\}\right\}=\frac{1}{2} \delta_{(r, 0)} v_{\alpha} x_{r} \otimes e_{r}-\frac{1}{2} \delta_{(r, m-1)} v_{\alpha} \otimes x_{r},  \tag{3.2b}\\
& \left\{\left\{y_{r}, w_{\alpha}\right\}\right\}=\frac{1}{2} \delta_{(r, 0)} e_{r} \otimes y_{r} w_{\alpha}-\frac{1}{2} \delta_{(r, m-1)} y_{r} \otimes w_{\alpha},  \tag{3.2c}\\
& \left\{\left\{y_{r}, v_{\alpha}\right\}\right\}=\frac{1}{2} \delta_{(r, m-1)} v_{\alpha} y_{r} \otimes e_{r+1}-\frac{1}{2} \delta_{(r, 0)} v_{\alpha} \otimes y_{r} . \tag{3.2d}
\end{align*}
$$

The remaining double brackets are nothing else than

$$
\begin{gather*}
\left\{\left\{v_{\alpha}, v_{\beta}\right\}\right\}=-\frac{1}{2} o(\alpha, \beta)\left(v_{\beta} \otimes v_{\alpha}+v_{\alpha} \otimes v_{\beta}\right),  \tag{3.3a}\\
\left\{\left\{w_{\alpha}, w_{\beta}\right\}\right\}=  \tag{3.3b}\\
\left\{\left\{\frac{1}{2} o(\alpha, \beta)\left(w_{\beta} \otimes w_{\alpha}+w_{\alpha} \otimes w_{\beta}\right),\right.\right. \\
\left.\left\{v_{\alpha}, w_{\beta}\right\}\right\}=  \tag{3.3c}\\
\delta_{\alpha \beta}\left(e_{0} \otimes e_{\infty}+\frac{1}{2} w_{\alpha} v_{\alpha} \otimes e_{\infty}+\frac{1}{2} e_{0} \otimes v_{\alpha} w_{\alpha}\right) \\
\\
+\frac{1}{2} o(\alpha, \beta)\left(e_{0} \otimes v_{\alpha} w_{\beta}+w_{\beta} v_{\alpha} \otimes e_{\infty}\right) .
\end{gather*}
$$

To derive (3.3a), note that Proposition 2.4 gives for $\alpha<\beta$ that $\left\{\left\{v_{\alpha}, v_{\beta}\right\}\right\}=-\frac{1}{2}\left(v_{\beta} \otimes v_{\alpha}+v_{\alpha} \otimes v_{\beta}\right)$. This is because $v_{\alpha}<v_{\beta}$ and their heads/tails coincide. We then find (3.3a) by cyclic antisymmetry of the double bracket. Identities (3.3b) and (3.3c) are obtained in the same way.

Introduce the elements $x=\sum_{s} x_{s}, y=\sum_{s} y_{s}$ and set $F_{a}=\sum_{s \in I} e_{s+a} \otimes e_{s} \in A \otimes A$ for any $a \in \mathbb{Z}$. Of great help for our study are the elements

$$
\begin{equation*}
F_{1}=\sum_{s \in I} e_{s+1} \otimes e_{s}, \quad F_{-1}=\sum_{s \in I} e_{s-1} \otimes e_{s}=\sum_{s \in I} e_{s} \otimes e_{s+1} \tag{3.4}
\end{equation*}
$$

With these notations, Equations (3.1a)-(3.1c) become

$$
\begin{align*}
& \{\{x, x\}\}=\frac{1}{2}\left(x^{2} F_{1}-F_{1} x^{2}\right), \quad\{\{y, y\}\}=-\frac{1}{2}\left(y^{2} F_{-1}-F_{-1} y^{2}\right)  \tag{3.5a}\\
& \{\{x, y\}\}=F_{1}+\frac{1}{2}\left(y x F_{1}+F_{1} x y-x F_{1} y+y F_{1} x\right), \tag{3.5b}
\end{align*}
$$

while (3.2a)-(3.2d) take the form

$$
\begin{array}{ll}
\left\{\left\{x, w_{\alpha}\right\}\right\}=\frac{1}{2} e_{0} \otimes x w_{\alpha}-\frac{1}{2} e_{0} x \otimes w_{\alpha}, & \left\{\left\{x, v_{\alpha}\right\}\right\}=\frac{1}{2} v_{\alpha} x \otimes e_{0}-\frac{1}{2} v_{\alpha} \otimes x e_{0}, \\
\left\{\left\{y, w_{\alpha}\right\}\right\}=\frac{1}{2} e_{0} \otimes y w_{\alpha}-\frac{1}{2} e_{0} y \otimes w_{\alpha}, & \left\{\left\{y, v_{\alpha}\right\}\right\}=\frac{1}{2} v_{\alpha} y \otimes e_{0}-\frac{1}{2} v_{\alpha} \otimes y e_{0} . \tag{3.6b}
\end{array}
$$

(The expressions (3.6a)-(3.6b) could be written using $F_{1}$ and $F_{-1}$ instead of writing the idempotents $e_{0}$, but this form is not better suited for calculations.) Adding to $A$ local inverses $x_{s}^{-1}=e_{s+1} x_{s}^{-1} e_{s}$ such that $x_{s} x_{s}^{-1}=e_{s}$ and $x_{s}^{-1} x_{s}=e_{s+1}$, we get locally invertible elements $z_{s}=y_{s}+x_{s}^{-1}$ and we form $z=x^{-1}+y=\sum_{s} z_{s}$. Equations (3.5a), (3.6a)-(3.6b) can be written with $z$ instead of $y$, while (3.5b) becomes

$$
\begin{equation*}
\{\{x, z\}\}=\frac{1}{2}\left(z x F_{1}+F_{1} x z-x F_{1} z+z F_{1} x\right) . \tag{3.7}
\end{equation*}
$$

The algebra $A$ is quasi-Hamiltonian for the double bracket given above and the multiplicative moment $\operatorname{map} \Phi=\sum_{s} e_{s} \Phi e_{s}+e_{\infty} \Phi e_{\infty}$ where

$$
\begin{align*}
e_{0} \Phi e_{0} & =\left(e_{0}+x_{0} y_{0}\right)\left(e_{0}+y_{m-1} x_{m-1}\right)^{-1} \quad \prod_{\alpha=1, \ldots, d}\left(e_{0}+w_{\alpha} v_{\alpha}\right)^{-1},  \tag{3.8a}\\
e_{s} \Phi e_{s} & =\left(e_{s}+x_{s} y_{s}\right)\left(e_{s}+y_{s-1} x_{s-1}\right)^{-1}, \quad s \in I \backslash\{0\},  \tag{3.8b}\\
e_{\infty} \Phi e_{\infty} & =\prod_{\alpha=1, \ldots, d}\left(e_{\infty}+v_{\alpha} w_{\alpha}\right) . \tag{3.8c}
\end{align*}
$$

Here, we use the invertibility of $1+x_{0} y_{0}$ and the idempotent decomposition of $1 \in A$ to get that $e_{0}+x_{0} y_{0}$ is locally invertible with inverse $\left(e_{0}+x_{0} y_{0}\right)^{-1}:=e_{0}\left(1+x_{0} y_{0}\right)^{-1} e_{0}$, and the same holds for all the arrows in $\bar{Q}$. If we further localize at $x$, we can write $\left(e_{s}+x_{s} y_{s}\right)\left(e_{s}+y_{s-1} x_{s-1}\right)^{-1}$ as $x_{s} z_{s} x_{s-1}^{-1} z_{s-1}^{-1}$.

Following the Jordan quiver case [34, Section 3.1], we introduce the spin elements

$$
\begin{equation*}
a_{\alpha}^{\prime}=w_{\alpha}, \quad c_{1}^{\prime}=v_{1} z, \quad c_{\alpha}^{\prime}=v_{\alpha}\left(e_{0}+w_{\alpha-1} v_{\alpha-1}\right) \ldots\left(e_{0}+w_{1} v_{1}\right) z \tag{3.9}
\end{equation*}
$$

and we can define $c_{\alpha}^{\prime}$ inductively using

$$
\begin{equation*}
c_{\alpha}^{\prime}=\sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+v_{\alpha} z \tag{3.10}
\end{equation*}
$$

It is important to remark that $a_{\alpha}^{\prime}=e_{0} a_{\alpha}^{\prime} e_{\infty}$ but $c_{\alpha}^{\prime}=e_{\infty} c_{\alpha}^{\prime} e_{m-1}$ is not a path to 0 . This is due to the fact that $v_{\alpha} z=v_{\alpha} z_{m-1}$. To get the double brackets between the elements ( $x, z, a_{\alpha}^{\prime}, c_{\alpha}^{\prime}$ ), it remains to find the ones involving $c_{\alpha}^{\prime}$. The next result is obtained in Appendix A:

Lemma 3.1 For any $\alpha, \beta=1, \ldots, d$,

$$
\begin{align*}
\left\{\left\{x, c_{\alpha}^{\prime}\right\}\right\} & =\frac{1}{2} c_{\alpha}^{\prime} x \otimes e_{m-1}+\frac{1}{2} c_{\alpha}^{\prime} \otimes x e_{m-1}, \quad\left\{\left\{z, c_{\alpha}^{\prime}\right\}\right\}=-\frac{1}{2} c_{\alpha}^{\prime} z \otimes e_{m-1}+\frac{1}{2} c_{\alpha}^{\prime} \otimes z e_{m-1}  \tag{3.11a}\\
\left\{\left\{a_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} & =\frac{1}{2}\left(o(\alpha, \beta)-\delta_{\alpha \beta}\right) e_{\infty} \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime}-\delta_{\alpha \beta}\left(e_{\infty} \otimes e_{0} z+\sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes a_{\lambda}^{\prime} c_{\lambda}^{\prime}\right)  \tag{3.11b}\\
\left\{\left\{c_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} & =\frac{1}{2} o(\alpha, \beta)\left(c_{\beta}^{\prime} \otimes c_{\alpha}^{\prime}-c_{\alpha}^{\prime} \otimes c_{\beta}^{\prime}\right) . \tag{3.11c}
\end{align*}
$$

where the last sum in (3.11b) is omitted for $\lambda=1$.
Motivated by the geometric interpretation through (2.13), we are interested in the bracket $\{-,-\}$ associated to $\{\{-,-\}\}$ between the elements $x^{k}$ and $a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}$, for any $k, l \in \mathbb{N}$. Hereafter, given any $b \in A$ we also denote by $b$ its equivalence class in $A /[A, A]$. We compute

Lemma 3.2 For any $k, l \geq 1$, we get in $A /[A, A]$,

$$
\begin{align*}
\left\{x^{k}, x^{l}\right\}= & 0, \quad\left\{x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}=k a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l},  \tag{3.12a}\\
\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}= & \frac{1}{2}\left(\sum_{v=1}^{k}-\sum_{v=1}^{l}\right)\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-v}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l-v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{v}\right) \\
& +\frac{1}{2} o(\alpha, \gamma)\left(a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}+a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}\right) \\
& +\frac{1}{2} o(\epsilon, \beta)\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l}-a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}\right) \\
& +\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}-\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l} \\
& +\delta_{\alpha \epsilon}\left(z+\sum_{\lambda=1}^{\epsilon-1} a_{\lambda}^{\prime} c_{\lambda}^{\prime}\right) x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}-\delta_{\beta \gamma} a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k}\left(z+\sum_{\mu=1}^{\beta-1} a_{\mu}^{\prime} c_{\mu}^{\prime}\right) x^{l} . \tag{3.12b}
\end{align*}
$$

In particular, in order for the elements on which we take the bracket to be non-zero in $A /[A, A]$, we need $k=0 \bmod m$ for $x^{k}$, or $l-1=0 \bmod m$ for $a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}$.

In fact, (3.12a) holds in $A$ for the left Loday bracket $\{-,-\}$, i.e. we do not necessarily need to regard it as the operation $A /[A, A] \times A /[A, A] \rightarrow A /[A, A]$. Note also that it is sufficient to consider in the two first sums over $v$ in (3.12b) the terms for which $v=1 \bmod m$. All the computations are provided in Appendix A.

We work in slightly more general setting from now on, and consider $u \in\left\{x, y, z, \sum_{s} e_{s}+x y\right\}$. We already have $\epsilon(x)=+1, \epsilon(y)=-1$, and we set $\epsilon(z)=-1, \epsilon\left(\sum_{s} e_{s}+x y\right)=+1$. We can write in the three first cases $\{u, u\}\}=\frac{1}{2} \epsilon(u)\left[u^{2} F_{\epsilon(u)}-F_{\epsilon(u)} u^{2}\right]$, while $\{\{u, u\}\}=\frac{1}{2}\left[u^{2} F_{0}-F_{0} u^{2}\right]$ if $u=\sum_{s} e_{s}+x y$. The identities can be directly checked, see e.g. [1, Lemmas A.1, A.2] for some of them. Using these brackets, we get the following result which is proved in Appendix A.

Lemma 3.3 For any $k, l \geq 1, \alpha, \beta=1, \ldots, d$, we have $\left\{\left\{u^{k}, w_{\alpha} v_{\beta} u^{l}\right\}\right\}=0$ under the left Loday bracket in $A$. The equality descends to $A /[A, A]$ and we have in particular that the $\mathbb{C}$-vector space generated by the elements $\left(u^{k}, w_{1} v_{1} u^{k}\right)$ is a commutative Lie subalgebra in $(A /[A, A],\{-,-\})$.

Let $\phi$ be the moment map associated to the subquiver supported at $I$. That is $\phi=\sum_{s} \phi_{s}$ for $\phi_{s}=$ $\left(e_{s}+x_{s} y_{s}\right)\left(e_{s}+y_{s-1} x_{s-1}\right)^{-1}$ or $\phi_{s}=x_{s} z_{s} x_{s-1}^{-1} z_{s-1}^{-1}$ when we localize $A$ at $x$. We assume in the next result that $A$ is localized at $u$.

Proposition 3.4 Let $U_{+, \eta}=u(1+\eta \phi), U_{-, \eta}=u\left(1+\eta \phi^{-1}\right)$, for arbitrary $\eta \in \mathbb{C}$ playing the role of a spectral parameter. Let $K, L \in \mathbb{N}^{\times}$. Then, if $\epsilon(u)=-1$,

$$
\begin{equation*}
\left\{U_{+, \eta}^{K}, U_{+, \eta^{\prime}}^{L}\right\}=0 \quad \bmod [A, A], \quad \text { for any } \eta, \eta^{\prime} \in \mathbb{C} . \tag{3.13}
\end{equation*}
$$

$$
\text { If } \epsilon(u)=+1,
$$

$$
\begin{equation*}
\left\{U_{-, \eta}^{K}, U_{-, \eta^{\prime}}^{L}\right\}=0 \quad \bmod [A, A], \quad \text { for any } \eta, \eta^{\prime} \in \mathbb{C} . \tag{3.14}
\end{equation*}
$$

Note that when $u$ is not $\sum_{s} e_{s}+x y$ and $K$ is not divisible by $m$, then $U_{+, \eta}^{K}=0 \bmod [A, A]$ and the result is trivial. This is because $u^{m} \in \oplus_{s} e_{s} A e_{s}$ but $u \notin \oplus_{s} e_{s} A e_{s}$ in those cases. The proof of Proposition 3.4 is provided in Appendix A.

For a $(m+1)$-uple $\left(q_{\infty}, q_{s}\right) \in \mathbb{C}^{\times} \times\left(\mathbb{C}^{\times}\right)^{I}$, we set $\widetilde{q}=q_{\infty} e_{\infty}+\sum_{s} q_{s} e_{s}$ and the multiplicative preprojective algebra $\Lambda^{\widetilde{q}}$ is the quotient of $A$ by the two-sided ideal $J$ generated by the relation $\Phi=\widetilde{q}$, where $\Phi$ is given by (3.8a)-(3.8c). The different equalities derived above in the Lie algebra $(A /[A, A],\{-,-\})$ descend to $\Lambda^{\tilde{q}} /\left[\Lambda^{\tilde{q}}, \Lambda^{\tilde{q}}\right]$ by Section 2.2.

## 4. A natural phase space for the spin RS model

We recall the important results from [34] that are needed for our study, and we take the freedom to adapt the notations to suit our case.

Fix $t \in \mathbb{C}^{\times}$not a root of unity, $n \in \mathbb{N}^{\times}$and $d \geq 2$. A dense open subset $\mathcal{C}_{n, t, d}^{\circ}$ of the MQV $\mathcal{C}_{n, t, d}$ of dimension $(1, n)$ defined from a spin Jordan quiver with $d$ framing arrows is given by equivalence classes
of $2 d+2$ elements $\left(A, B, V_{\alpha}^{\prime}, W_{\alpha}^{\prime}\right)$, where $A, B \in \mathrm{GL}_{n}(\mathbb{C})$ and $V_{\alpha}^{\prime} \in \mathrm{Mat}_{1 \times n}, W_{\alpha}^{\prime} \in \mathrm{Mat}_{n \times 1}$ are matrices satisfying

$$
\begin{equation*}
A B A^{-1} B^{-1} \prod_{\alpha=1, \ldots, d}\left(\operatorname{Id}_{n}+W_{\alpha}^{\prime} V_{\alpha}^{\prime}\right)^{-1}=t \mathrm{Id}_{n}, \tag{4.1}
\end{equation*}
$$

under the equivalence defined from the action of the group $\mathrm{GL}_{n}(\mathbb{C})$ by

$$
\begin{equation*}
g .\left(A, B, V_{\alpha}^{\prime}, W_{\alpha}^{\prime}\right)=\left(g A g^{-1}, g B g^{-1}, V_{\alpha}^{\prime} g^{-1}, g W_{\alpha}^{\prime}\right), \quad g \in \mathrm{GL}_{n}(\mathbb{C}) \tag{4.2}
\end{equation*}
$$

In fact, $\mathcal{C}_{n, t, d}^{\circ}$ is a smooth symplectic complex manifold of dimension $2 n d$, and we denote its Poisson bracket by $\{-,-\}_{\mathrm{P}}$. For any representative of an equivalence class, we form the matrices $\mathbf{A} \in \mathrm{Mat}_{n \times d}(\mathbb{C})$ and $\mathbf{C} \in \operatorname{Mat}_{d \times n}(\mathbb{C})$ by

$$
\begin{equation*}
\mathbf{A}_{i \alpha}=\left[W_{\alpha}^{\prime}\right]_{i}, \quad \mathbf{C}_{\alpha j}=\left[V_{\alpha}^{\prime}\left(\operatorname{Id}_{n}+W_{\alpha-1}^{\prime} V_{\alpha-1}^{\prime}\right) \ldots\left(\operatorname{Id}_{n}+W_{1}^{\prime} V_{1}^{\prime}\right) B\right]_{j} \tag{4.3}
\end{equation*}
$$

so that the moment map equation can be rewritten as

$$
\begin{equation*}
A B A^{-1}=t B+t \mathbf{A C} \tag{4.4}
\end{equation*}
$$

Then a point of $\mathcal{C}_{n, t, d}^{\circ}$ is determined by the equivalence class of $\left(A, B, V_{\alpha}^{\prime}, W_{\alpha}^{\prime}\right)$ as above, or equivalently by an element $(A, B, \mathbf{A}, \mathbf{C})$ modulo identification by the group action $g \cdot(A, B, \mathbf{A}, \mathbf{C})=\left(g A g^{-1}, g B g^{-1}, g \mathbf{A}, \mathbf{C} g^{-1}\right)$ for any $g \in \mathrm{GL}_{n}(\mathbb{C})$. Choosing the functions

$$
\begin{equation*}
f_{k}:=\operatorname{tr}\left(A^{k}\right), \quad g_{k}^{\alpha \beta}=\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k}\right), \quad k \in \mathbb{N}, \alpha, \beta=1, \ldots, d, \tag{4.5}
\end{equation*}
$$

the Poisson structure is determined from the identities

$$
\begin{align*}
\left\{f_{k}, f_{l}\right\}_{\mathrm{P}}= & 0, \quad\left\{f_{k}, g_{l}^{\alpha \beta}\right\}_{\mathrm{P}}=k g_{k+l}^{\alpha \beta}  \tag{4.6a}\\
\left\{g_{k}^{\gamma \epsilon}, g_{l}^{\alpha \beta}\right\}_{\mathrm{P}}= & \frac{1}{2}\left(\sum_{r=1}^{k}-\sum_{r=1}^{l}\right)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{r} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k+l-r}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k+l-r} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{r}\right)\right) \\
& +\frac{1}{2} o(\alpha, \gamma)\left(\operatorname{tr}\left(\mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k} \mathbf{A} E_{\alpha \beta} \mathbf{C} A^{l}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l}\right)\right) \\
& +\frac{1}{2} o(\epsilon, \beta)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{l}\right)-\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l}\right)\right) \\
& +\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l}\right)-\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l}\right) \\
& +\delta_{\alpha \epsilon} \operatorname{tr}\left(\left[B+\sum_{\lambda=1}^{\epsilon-1} \mathbf{A} E_{\lambda \lambda} \mathbf{C}\right] A^{k} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l}\right) \\
& -\delta_{\beta \gamma} \operatorname{tr}\left(\left[B+\sum_{\mu=1}^{\beta-1} \mathbf{A} E_{\mu \mu} \mathbf{C}\right] A^{l} \mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k}\right) \tag{4.6b}
\end{align*}
$$

see [34, Lemma A.2]. This space admits local coordinates on an open subset which is dense ${ }^{3}$ in $\mathcal{C}_{n, t, d}^{\circ}$ as follows. Define the open subspace $\mathcal{C}_{n, t, d}^{\prime} \subset \mathcal{C}_{n, t, d}^{\circ}$ which is such that for any equivalence class of quadruple $(A, B, \mathbf{A}, \mathbf{C}) \in \mathcal{C}_{n, t, d}^{\circ}$, the matrix $A$ is diagonalizable with non-zero eigenvalues $\left(x_{i}\right)_{i}$ satisfying $x_{i} \neq x_{j}, x_{i} \neq t x_{j}$ for each $i \neq j$, and when we choose a representative with $A$ in diagonal form, the matrix $\mathbf{A}$ is such that the entries in each of its rows sum up to a non-zero value. Hence, we can pick a representative with $A$ in diagonal form as above, and such that $\sum_{\alpha} \mathbf{A}_{i \alpha}=1$ in $\mathcal{C}_{n, t, d}^{\prime}$. Note that this is uniquely defined up to action by a permutation matrix. Introduce

$$
\begin{equation*}
\mathfrak{C}_{\text {reg }}=\left\{x=\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{C}^{n} \mid x_{i} \neq 0, x_{i} \neq x_{j}, x_{i} \neq t x_{j} \text { for all } i \neq j\right\} \tag{4.7}
\end{equation*}
$$

For $\alpha=1, \ldots, d$ take $\left(\mathbf{a}^{\alpha}\right)^{\top}, \mathbf{c}^{\alpha} \in \mathbb{C}^{n}$. We define $\mathfrak{h} \subset \mathfrak{C}_{\text {reg }} \times\left(\mathbb{C}^{n}\right)^{\times d} \times\left(\mathbb{C}^{n}\right)^{\times d}$ to be a generic subspace such that on global coordinates $\left(x_{i}, \mathbf{a}_{i}^{\alpha}, \mathbf{c}_{i}^{\alpha}\right)_{i \alpha}$ we require $\sum_{\alpha} \mathbf{a}_{i}^{\alpha}=1$, see [34, Section 4.1]. We can define a map $\xi: \mathfrak{h} \rightarrow \mathcal{C}_{n, t, d}^{\prime}$ which associates to $\left(x_{i}, \mathbf{a}_{i}^{\alpha}, \mathbf{c}_{i}^{\alpha}\right)_{i \alpha}$ the equivalence class of the element $(A, B, \mathbf{A}, \mathbf{C})$, where

$$
\begin{align*}
& A=\operatorname{diag}\left(x_{1}, \ldots, x_{n}\right), \quad B=\left(B_{i j}\right), \quad \mathbf{A}=\left(\mathbf{A}_{i \alpha}\right), \mathbf{C}=\left(\mathbf{C}_{\alpha i}\right) \\
& \text { with } B_{i j}=t \frac{\sum_{\alpha} \mathbf{a}_{i}^{\alpha} \mathbf{c}_{j}^{\alpha}}{x_{i} x_{j}^{-1}-t}, \quad \mathbf{A}_{i \alpha}=\mathbf{a}_{i}^{\alpha}, \quad \mathbf{C}_{\alpha i}=\mathbf{c}_{i}^{\alpha} . \tag{4.8}
\end{align*}
$$

This map is such that the following result holds.
Proposition 4.1 [34, Propositions 4.1, 4.3] The map $\xi: \mathfrak{h} / S_{n} \rightarrow \mathcal{C}_{n, t, d}^{\prime}$ given by (4.8) defines a local diffeomorphism. It is a Poisson morphism when $\mathfrak{h} / S_{n}$ is equipped with the Poisson bracket $\{-,-\}$ defined on coordinates by

$$
\begin{align*}
\left\{x_{j}, x_{i}\right\}= & 0, \quad\left\{\mathbf{a}_{j}^{\alpha}, x_{i}\right\}=0, \quad\left\{\mathbf{c}_{j}^{\alpha}, x_{i}\right\}=-\delta_{i j} \mathbf{c}_{j}^{\alpha} x_{i},  \tag{4.9a}\\
\left\{\mathbf{a}_{j}^{\gamma}, \mathbf{a}_{i}^{\alpha}\right\}= & \frac{1}{2} \delta_{(i \neq j)} \frac{x_{j}+x_{i}}{x_{j}-x_{i}}\left(\mathbf{a}_{j}^{\gamma} \mathbf{a}_{i}^{\alpha}+\mathbf{a}_{i}^{\gamma} \mathbf{a}_{j}^{\alpha}-\mathbf{a}_{j}^{\gamma} \mathbf{a}_{j}^{\alpha}-\mathbf{a}_{i}^{\gamma} \mathbf{a}_{i}^{\alpha}\right)+\frac{1}{2} o(\alpha, \gamma)\left(\mathbf{a}_{j}^{\gamma} \mathbf{a}_{i}^{\alpha}+\mathbf{a}_{i}^{\gamma} \mathbf{a}_{j}^{\alpha}\right) \\
& +\frac{1}{2} \sum_{\sigma=1}^{d} o(\gamma, \sigma) \mathbf{a}_{i}^{\alpha}\left(\mathbf{a}_{j}^{\gamma} \mathbf{a}_{i}^{\sigma}+\mathbf{a}_{i}^{\gamma} \mathbf{a}_{j}^{\sigma}\right)-\frac{1}{2} \sum_{\kappa=1}^{d} o(\alpha, \kappa) \mathbf{a}_{j}^{\gamma}\left(\mathbf{a}_{j}^{\kappa} \mathbf{a}_{i}^{\alpha}+\mathbf{a}_{i}^{\kappa} \mathbf{a}_{j}^{\alpha}\right),  \tag{4.9b}\\
\left\{\mathbf{c}_{j}^{\epsilon}, \mathbf{a}_{i}^{\alpha}\right\}= & \delta_{\epsilon \alpha} B_{i j}-\mathbf{a}_{i}^{\alpha} B_{i j}+\frac{1}{2} \delta_{(i \neq j)} \frac{x_{j}+x_{i}}{x_{j}-x_{i}} \mathbf{c}_{j}^{\epsilon}\left(\mathbf{a}_{j}^{\alpha}-\mathbf{a}_{i}^{\alpha}\right)-\delta_{(\alpha<\epsilon)} \mathbf{a}_{i}^{\alpha} \mathbf{c}_{j}^{\epsilon} \\
& -\mathbf{a}_{i}^{\alpha} \sum_{\lambda=1}^{\epsilon-1} \mathbf{a}_{i}^{\lambda}\left(\mathbf{c}_{j}^{\lambda}-\mathbf{c}_{j}^{\epsilon}\right)+\delta_{\epsilon \alpha} \sum_{\lambda=1}^{\epsilon-1} \mathbf{a}_{i}^{\lambda} \mathbf{c}_{j}^{\lambda}+\frac{1}{2} \sum_{\kappa=1}^{d} o(\alpha, \kappa) \mathbf{c}_{j}^{\epsilon}\left(\mathbf{a}_{j}^{\kappa} \mathbf{a}_{i}^{\alpha}+\mathbf{a}_{i}^{\kappa} \mathbf{a}_{j}^{\alpha}\right),  \tag{4.9c}\\
\left\{\mathbf{c}_{j}^{\epsilon}, \mathbf{c}_{i}^{\beta}\right\}= & \frac{1}{2} \delta_{(i \neq j)} \frac{x_{j}+x_{i}}{x_{j}-x_{i}}\left(\mathbf{c}_{j}^{\epsilon} \mathbf{c}_{i}^{\beta}+\mathbf{c}_{i}^{\epsilon} \mathbf{c}_{j}^{\beta}\right)+\mathbf{c}_{i}^{\beta} B_{i j}-\mathbf{c}_{j}^{\epsilon} B_{j i}+\frac{1}{2} o(\epsilon, \beta)\left(\mathbf{c}_{i}^{\epsilon} \mathbf{c}_{j}^{\beta}-\mathbf{c}_{j}^{\epsilon} \mathbf{c}_{i}^{\beta}\right)
\end{align*}
$$

[^3]\[

$$
\begin{equation*}
+\mathbf{c}_{i}^{\beta} \sum_{\lambda=1}^{\epsilon-1} \mathbf{a}_{i}^{\lambda}\left(\mathbf{c}_{j}^{\lambda}-\mathbf{c}_{j}^{\epsilon}\right)-\mathbf{c}_{j}^{\epsilon} \sum_{\mu=1}^{\beta-1} \mathbf{a}_{j}^{\mu}\left(\mathbf{c}_{i}^{\mu}-\mathbf{c}_{i}^{\beta}\right) . \tag{4.9d}
\end{equation*}
$$

\]

Furthermore, letting $f_{i j}=\sum_{\alpha} \mathbf{a}_{i}^{\alpha} \mathbf{c}_{j}^{\alpha}$, the subalgebra generated by $\left(x_{i}, f_{i j}\right)_{i j}$ inside $\mathrm{O}\left(\mathfrak{h} / S_{n}\right)$ is a Poisson subalgebra under $\{-,-\}$.

In these local coordinates, the matrix $B$ is the Lax matrix of the spin trigonometric RS system. Furthermore, the equation of motions defined by $\frac{d}{d t}=\{\operatorname{tr} B,-\}_{\mathrm{P}}$ are normalized versions of the equations of motion for the spin RS Hamiltonian, as originally defined in [26]. The form of the Poisson brackets between the elements $\left(x_{i}, f_{i j}\right)_{i j}$ was conjectured in [27].

## 5. MQV for spin cyclic quivers

Consider the multiplicative preprojective algebra for a spin cyclic quiver as in Section 3. In accordance with Section 2.5 , choose a dimension vector $\widetilde{\alpha}=(1, \alpha)$ with $\alpha \in\left(\mathbb{N}^{\times}\right)^{I}$, and set $q_{\infty}=q^{-\alpha}=\prod_{s \in I} q_{s}^{-\alpha_{s}}$.

A representation of $\Lambda^{\tilde{q}}$ of dimension $\tilde{\alpha}$ is a collection of vector spaces $\left(\mathcal{V}_{\infty}, \mathcal{V}_{s}\right)=\left(\mathbb{C}, \mathbb{C}^{\alpha_{s}}\right)$ together with linear maps representing arrows of $\bar{Q}$ and satisfying (3.8a)-(3.8c). Denote in an obvious way the matrices representing the arrows as $\left(X_{s}, Y_{s}, V_{\alpha}, W_{\alpha}\right)$. Therefore, points of $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right)$ are represented by $2 m+2 d$ elements ( $X_{s}, Y_{s}, V_{\alpha}, W_{\alpha}$ ),

$$
X_{s} \in \operatorname{Mat}_{\alpha_{s} \times \alpha_{s+1}}(\mathbb{C}), \quad Y_{s} \in \operatorname{Mat}_{\alpha_{s+1} \times \alpha_{s}}(\mathbb{C}), \quad V_{\alpha} \in \operatorname{Mat}_{\alpha_{0} \times 1}(\mathbb{C}), \quad W_{\alpha} \in \operatorname{Mat}_{1 \times \alpha_{0}}(\mathbb{C}),
$$

for $s \in I, \alpha \in\{1, \ldots, d\}$ satisfying

$$
\begin{align*}
& \left(\operatorname{Id}_{\alpha_{0}}+X_{0} Y_{0}\right)\left(\operatorname{Id}_{\alpha_{0}}+Y_{m-1} X_{m-1}\right)^{-1}=q_{0} \prod_{\alpha=1, \ldots, d}\left(\operatorname{Id}_{\alpha_{0}}+W_{\alpha} V_{\alpha}\right),  \tag{5.1a}\\
& \left(\operatorname{Id}_{\alpha_{s}}+X_{s} Y_{s}\right)\left(\operatorname{Id}_{\alpha_{s}}+Y_{s-1} X_{s-1}\right)^{-1}=q_{s} \operatorname{Id}_{\alpha_{s}}, \quad s \in I \backslash\{0\}  \tag{5.1b}\\
& \quad \overrightarrow{\prod_{\alpha=1, \ldots, d}}\left(1+V_{\alpha} W_{\alpha}\right)=q_{\infty} \tag{5.1c}
\end{align*}
$$

and such that all factors have non-zero determinant. The group $G(\widetilde{\alpha})=\prod_{s \in I} \mathrm{GL}_{\alpha_{s}}(\mathbb{C})$ acts on these elements by

$$
\begin{equation*}
g .\left(X_{s}, Y_{s}, V_{\alpha}, W_{\alpha}\right)=\left(g_{s} X_{s} g_{s+1}^{-1}, g_{s+1} Y_{s} g_{s}^{-1}, V_{\alpha} g_{0}^{-1}, g_{0} W_{\alpha}\right), \quad g \in G(\widetilde{\alpha}) \tag{5.2}
\end{equation*}
$$

and the orbits in $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right) / / G(\widetilde{\alpha})$ correspond to isomorphism classes of semisimple representations. We are particularly interested in the cases where $X=\sum_{s} X_{s}$ is invertible at some points, hence we restrict our attention to the spaces such that $\alpha_{s}=n \in \mathbb{N}^{\times}$for all $s \in I$. We now define

$$
\mathcal{C}_{n, \tilde{q}, d}(m)=\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right) / / G(\widetilde{\alpha}),
$$

which is the spin analogue of the space $\mathcal{C}_{n, q}(m)$ introduced in [1, Section 4], see also [41, Section 5]. By construction, this is a MQV for a framed cyclic quiver, and we denote its Poisson bracket by $\{-,-\}_{\mathrm{p}}$.

Let us identify $I$ and $\{0, \ldots, m-1\}$ to introduce the elements

$$
\begin{equation*}
t_{s}:=\prod_{0 \leq s^{\prime} \leq s} q_{s^{\prime}}, \quad s=0, \ldots, m-1, \quad t:=t_{m-1} \tag{5.3}
\end{equation*}
$$

so that $q_{\infty}=t^{-n}$. We also set $t_{-1}=1$ to state the next result, which is an application of 2.5 with the regularity condition from [1, Section 4].

Proposition 5.1 Suppose that $t_{s}^{-1} t_{s^{\prime}} \neq t^{k}$ for any $k \in \mathbb{Z},-1 \leq s<s^{\prime} \leq m-1$ with $\left(s, s^{\prime}\right) \neq(-1, m-1)$, or that $t^{k} \neq 1$ for any $k \in \mathbb{Z}^{\times}$. Then $\mathcal{C}_{n, \tilde{q}, d}(m)$ is a smooth variety of dimension $2 n d$, with a non-degenerate Poisson bracket denoted by $\{-,-\}_{\mathrm{P}}$.

From now on, we assume the regularity condition of the proposition. In particular, $t$ is not a root of unity.

### 5.1 Local coordinates

Consider the open subset $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m) \subset \mathcal{C}_{n, \tilde{q}, d}(m)$ on which the $X_{s}$ are invertible. Similarly to the Jordan quiver case reviewed in Section 4, introduce $Z_{s}:=Y_{s}+X_{s}^{-1}$, and form the matrices $\mathbf{A}^{(m)} \in \operatorname{Mat}_{n \times d}(\mathbb{C})$, $\mathbf{C}^{(m)} \in \mathrm{Mat}_{d \times n}(\mathbb{C})$ by

$$
\begin{equation*}
\mathbf{A}_{i \alpha}^{(m)}=\left[W_{\alpha}\right]_{i}, \quad \mathbf{C}_{\alpha j}^{(m)}=t^{-1}\left[V_{\alpha}\left(\operatorname{Id}_{n}+W_{\alpha-1} V_{\alpha-1}\right) \ldots\left(\operatorname{Id}_{n}+W_{1} V_{1}\right) Z\right]_{j} \tag{5.4}
\end{equation*}
$$

so that the $\alpha$ th column of $\mathbf{A}^{(m)}$ represents the spin element $a_{\alpha}^{\prime}$, while the $\alpha$ th row of $\mathbf{C}^{(m)}$ represent $t^{-1} c_{\alpha}^{\prime}$. Note the factor $t^{-1}$ necessary to define $\mathbf{C}^{(m)}$. In particular, (5.1a)-(5.1b) adopt the compact form

$$
\begin{equation*}
X_{0} Z_{0} X_{m-1}^{-1}=q_{0} Z_{m-1}+q_{0} t \mathbf{A}^{(m)} \mathbf{C}^{(m)}, \quad X_{s} Z_{s}=q_{s} Z_{s-1} X_{s-1} . \tag{5.5}
\end{equation*}
$$

Then (5.1c) is just a corollary of these relations. Up to changing basis, a point ( $X_{s}, Y_{s}, V_{\alpha}, W_{\alpha}$ ) can be represented by an element of the equivalence class such that $X_{0}, \ldots, X_{m-2}=\operatorname{Id}_{n}$. Therefore, setting $A:=X_{m-1}$ and $B:=q_{0}^{-1} Z_{0}$, we find that the condition (5.5) gives $Z_{s}=t_{s} B$ for $s \neq m-1, Z_{m-1}=t A^{-1} B$, and $A, B$ satisfy

$$
\begin{equation*}
q_{0} B A^{-1}=q_{0} t A^{-1} B+q_{0} t \mathbf{A}^{(m)} \mathbf{C}^{(m)} \tag{5.6}
\end{equation*}
$$

Hence a point in $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ is completely determined by the data $\left(A, B, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ up to $\mathrm{GL}_{n}$ action by $g \cdot\left(g A g^{-1}, g B g^{-1}, g \mathbf{A}^{(m)}, \mathbf{C}^{(m)} g^{-1}\right)$ seen as $\prod_{s} g \in G(\widetilde{\alpha})$, with $A, B$ invertible and the elements $\operatorname{Id}_{n}+W_{\alpha} V_{\alpha}$ (that can be reconstructed from (5.4)) invertible. Comparing with (4.4), we find

Proposition 5.2 Let $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m) \subset \mathcal{C}_{n, \widetilde{q}, d}(m)$ be as above. Let $\mathcal{C}_{n, t, d}^{\circ}$ be the spin RS space considered in Section 4 with parameter $t=\prod_{s} q_{s}$, so that $\mathcal{C}_{n, t, d}^{\circ}$ is a smooth variety. Then the map $\psi: \mathcal{C}_{n, t, d}^{\circ} \rightarrow \mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ sending $(A, B, \mathbf{A}, \mathbf{C})$ to $X_{s}=\operatorname{Id}_{n}, Z_{s}=t_{s} B$ for $s=0, \ldots, m-2$ and $X_{m-1}=A, Z_{m-1}=t A^{-1} B$, $\mathbf{A}^{(m)}=A^{-1} \mathbf{A}, \mathbf{C}^{(m)}=\mathbf{C}$ defines an isomorphism of varieties.

Proof. The only non-trivial identity to show is that we can recover $\operatorname{det}\left(\mathrm{Id}_{n}+W_{\alpha} V_{\alpha}\right) \neq 0$ for all $\alpha$. We define in $\mathcal{C}_{n, t, d}^{\circ}$ the elements $W_{\beta}^{\prime}=\left(\mathbf{A}_{i \beta}\right)_{i}, C_{\beta}^{\prime}=\left(\mathbf{C}_{\beta i}\right)_{i}$ and inductively

$$
V_{\beta}^{\prime}=C_{\beta}^{\prime} B^{-1}\left(\operatorname{Id}_{n}+W_{1}^{\prime} V_{1}^{\prime}\right)^{-1} \ldots\left(\mathrm{Id}_{n}+W_{\beta-1}^{\prime} V_{\beta-1}^{\prime}\right)^{-1}
$$

By definition of the space $\mathcal{C}_{n, t, d}^{\circ}$ with (4.3), $1+V_{\beta}^{\prime} W_{\beta}^{\prime} \neq 0$ for all $\beta$. Now we remark in $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m)$ that $W_{\beta}=\left(\left(A^{-1} \mathbf{A}\right)_{i \beta}\right)_{i}=A^{-1} W_{\beta}^{\prime}$. We can also rewrite (5.4) as

$$
V_{\beta}=C_{\beta}^{\prime} B^{-1} A\left(\mathrm{Id}_{n}+W_{1} V_{1}\right)^{-1} \ldots\left(\operatorname{Id}_{n}+W_{\beta-1} V_{\beta-1}\right)^{-1}
$$

to get that $V_{1}=V_{1}^{\prime} A$ and by induction $V_{\beta}=V_{\beta}^{\prime} A$. Thus $1+V_{\beta} W_{\beta}=1+V_{\beta}^{\prime} W_{\beta}^{\prime} \neq 0$ for all $\beta$.
We can, in fact, compare the Poisson structures on both spaces.

Proposition 5.3 The isomorphism $\psi: \mathcal{C}_{n, t, d}^{\circ} \rightarrow \mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m)$ from Proposition 5.2 is Poisson.

The proof can be found in Appendix B. In particular, we can transfer the invariant local coordinates on $\mathcal{C}_{n, t, d}^{\prime} \subset \mathcal{C}_{n, t, d}^{\circ}$ obtained in Proposition 4.1 to the open subset $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m) \subset \mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ defined by $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)=$ $\psi\left(\mathcal{C}_{n, t, d}^{\prime}\right)$. In such a case, we can always consider for a point of $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ a gauge with representative of the form ( $X, Z, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}$ ) given by Proposition 5.2, with the extra condition that $X_{m-1}$ is in diagonal form with diagonal entries $\left(x_{i}\right)_{i}$ defining a point of $\mathfrak{C}_{\text {reg }}(4.7)$ and $\sum_{\alpha}\left(X \mathbf{A}^{(m)}\right)_{i \alpha}=1$ for all $i$.

### 5.2 New variants of the spin RS system

Set $X=\sum_{s} X_{s}, Y=\sum_{s} Y_{s}$ and denote by 1 the sum of the $m$ copies of the identity matrix on each $\mathcal{V}_{s}=\mathbb{C}^{n}, s \in I$. Let $\Theta=(1+X Y)(1+Y X)^{-1}$ be the moment map restricted to the cyclic quiver without framing, so that $\Theta=\mathcal{X}(\phi)$ for $\phi$ defined in Section 3. Proposition 3.4 and (2.13) imply the following result.

Theorem 5.4 The following families of functions are Poisson commuting for any parameter $\eta$ :

$$
\begin{aligned}
& \left\{\operatorname{tr}\left(\left(1+\eta \Theta^{-1}\right) X\right)^{j} \mid j \in \mathbb{N}\right\}, \quad\left\{\operatorname{tr}\left(\left(1+\eta \Theta^{-1}\right)(1+X Y)\right)^{j} \mid j \in \mathbb{N}\right\} \\
& \left\{\operatorname{tr}((1+\eta \Theta) Y)^{j} \mid j \in \mathbb{N}\right\}, \quad\left\{\operatorname{tr}\left((1+\eta \Theta)\left(Y+X^{-1}\right)\right)^{j} \mid j \in \mathbb{N}\right\}
\end{aligned}
$$

Apart from the first family, we need $j \in m \mathbb{N}$ to have non-zero elements.
We will write down the families from Theorem 5.4 in $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$, where we can use the coordinates $\left(x_{i}, f_{i j}\right)_{i j}$ with $f_{i j}=\sum_{\alpha} \mathbf{a}_{i}^{\alpha} \mathbf{c}_{j}^{\alpha}$. Hence, our first task is to use the known matrices ( $A, B, S=\mathbf{A C}$ ) instead of the matrices describing a point in $\mathcal{C}_{n, \widetilde{q}, d}^{\prime}(m)$. Using the isomorphism from Theorem 5.2, they are given by

$$
A=\operatorname{diag}\left(x_{1}, \ldots, x_{n}\right), \quad B=\left(B_{i j}\right)_{i j}, \quad B_{i j}=\frac{t f_{i j} x_{j}}{x_{i}-t x_{j}}, \quad S=\left(S_{i j}\right)_{i j}, S_{i j}=f_{i j} .
$$

Decomposing the moment map (restricted to the cycle) $\Theta=X Z X^{-1} Z^{-1}$ as $\Theta=\sum_{s} \Theta_{s}$, we get from (5.1b) that $\Theta_{s}=q_{s} \operatorname{Id}_{n}$ for $s \neq 0$, and from (5.1a) that $\Theta_{0}=q_{0} \operatorname{Id}_{n}+q_{0} t \mathbf{A}^{(m)} \mathbf{C}^{(m)} Z_{m-1}^{-1}$. Hence

$$
\begin{align*}
\Theta_{0} Z_{m-1} & =q_{0} Z_{m-1}+q_{0} t \mathbf{A}^{(m)} \mathbf{C}^{(m)}=q_{0} t A^{-1} B+q_{0} t A^{-1} \mathbf{A C}=q_{0} t A^{-1}(B+S)  \tag{5.7}\\
\Theta_{s} Z_{s-1} & =q_{s} Z_{s-1}=q_{s} t_{s-1} B, \quad s \neq 0 .
\end{align*}
$$

The first family contains the symmetric functions of the positions $\left(x_{i}\right)_{i}$ so we omit it. For the fourth family in Theorem 5.4, we see that $(1+\eta \Theta)\left(Y+X^{-1}\right)$ is constituted of $m$ blocks $Z_{s-1}+\eta \Theta_{s} Z_{s-1}$. Thus, the block $Z_{s-1}+\eta \Theta_{s} Z_{s-1}$ is given by $\left(1+\eta q_{0}\right) t A^{-1} B+\eta q_{0} t A^{-1} S$ for $s=0$ and $t_{s-1}\left(1+\eta q_{s}\right) B$ otherwise. We can rewrite $[(1+\eta \Theta) Z]^{m}$ as a matrix with diagonal blocks

$$
\begin{equation*}
\left(t^{2} \prod_{s \neq 0} t_{s-1}\left(1+\eta q_{s}\right)\right) B^{s} A^{-1}\left(\left[t^{-1}+\eta^{\prime}\right] B+\eta^{\prime} S\right) B^{m-s-1}, \quad \text { for } \eta^{\prime}=q_{0} t^{-1} \eta \tag{5.8}
\end{equation*}
$$

In other words, we are interested in studying the family

$$
\begin{equation*}
G_{j}^{m}:=\operatorname{tr}\left[A^{-1}\left(\left[t^{-1}+\eta^{\prime}\right] B+\eta^{\prime} S\right) B^{m-1}\right]^{j} \tag{5.9}
\end{equation*}
$$

In particular, if we write $G_{j}^{m}$ as a polynomial in $\eta^{\prime}$ under the form $G_{j}^{m}=\sum_{l=0}^{j}\left(\eta^{\prime}\right)^{l} G_{j, l}^{m}$, we get that all the $\left(G_{j, l}^{m}\right)_{j, l}$ are Poisson commuting (for fixed $m$ ) by Theorem 5.4. Now, remark that (4.4) gives $\left[t^{-1}+\eta^{\prime}\right] B+\eta^{\prime} S=t^{-1} B+\eta^{\prime} t^{-1} A B A^{-1}$. We can write

$$
\begin{equation*}
G_{j, l}^{m}=t^{-j} \sum_{i_{1}, \ldots, j_{j m}=1}^{n} \prod_{a=1}^{j m} \frac{f_{i_{i a} i_{a+1}} x_{i_{a+1}}}{x_{i_{a}}-t x_{i_{a+1}}} \sum_{\substack{|\subset\{0, \ldots, j-1\}\\| 1 \mid=l}}\left(\prod_{s \in I} x_{i_{s m+2}}^{-1}\right)\left(\prod_{s \notin I} x_{i_{s m+1}}^{-1}\right) . \tag{5.10}
\end{equation*}
$$

This was obtained by developing $G_{j}^{m}:=\operatorname{tr}\left[\left(t^{-1} A^{-1} B+t^{-1} \eta^{\prime} B A^{-1}\right) B^{m-1}\right]^{j}$, which explains the two products at the end of the expression, that represent whether $A^{-1}$ occurs before or after $B$ in the ( $s m+1$ )th factor $A^{-1} B+\eta^{\prime} B A^{-1}$. In particular, $G_{j, j}=G_{j, 0}$ for all $j=1, \ldots, n$.

We now look at the third family in Theorem 5.4. We can see that for any $j \geqslant 1$ in $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$

$$
\begin{align*}
& \operatorname{tr}((1+\eta \Theta) Y)^{j m}=\operatorname{tr}\left((1+\eta \Theta)\left(Z-X^{-1}\right)\right)^{j m} \\
& =m \operatorname{tr}\left(\left(\operatorname{Id}_{n}+\eta \Theta_{0}\right)\left(Z_{m-1}-X_{m-1}^{-1}\right) \ldots\left(\operatorname{Id}_{n}+\eta \Theta_{2}\right)\left(Z_{1}-X_{1}^{-1}\right)\left(\operatorname{Id}_{n}+\eta \Theta_{1}\right)\left(Z_{0}-X_{0}^{-1}\right)\right)^{j} \tag{5.11}
\end{align*}
$$

We get, for any $s \neq 0$,

$$
\begin{aligned}
\left(\mathrm{Id}_{n}+\eta \Theta_{s}\right)\left(Z_{s-1}-X_{s-1}^{-1}\right) & =\left(1+\eta q_{s}\right)\left(t_{s-1} B-\mathrm{Id}_{n}\right)=t_{s-1}\left(1+\eta q_{s}\right)\left(B-t_{s-1}^{-1} \mathrm{Id}_{n}\right), \\
\left(\mathrm{Id}_{n}+\eta \Theta_{0}\right)\left(Z_{m-1}-X_{m-1}^{-1}\right) & =\left(\operatorname{Id}_{n}+\eta q_{0} t A^{-1}(B+S)\left(t A^{-1} B\right)^{-1}\right)\left(t A^{-1} B-A^{-1}\right) \\
& =t A^{-1}\left(\left(1+\eta q_{0}\right) \mathrm{Id}_{n}+\eta q_{0} S B^{-1}\right)\left(B-t^{-1} \mathrm{Id}_{n}\right)
\end{aligned}
$$

Hence, introducing $H_{j}^{m}=m^{-1} C^{-j} \operatorname{tr}((1+\eta \Theta) Y)^{j m}$ for $C=t \prod_{s \neq 0} t_{s-1}\left(1+\eta q_{s}\right)$, we get

$$
\begin{align*}
H_{j}^{m} & =\operatorname{tr}\left(A^{-1}\left(\left(1+\eta q_{0}\right) \mathrm{Id}_{n}+\eta q_{0} S B^{-1}\right)\left(B-t_{m-1}^{-1} \mathrm{Id}_{n}\right) \ldots\left(B-t_{0}^{-1} \mathrm{Id}_{n}\right)\right)^{j} \\
& =\operatorname{tr}\left(\left[\left(1+\eta q_{0}\right) \mathrm{Id}_{n}+\eta q_{0} S B^{-1}\right] \mathbf{P}(B) A^{-1}\right)^{j}, \tag{5.12}
\end{align*}
$$

by setting

$$
\begin{equation*}
\mathbf{P}(B)=\prod_{0 \leqslant s \leqslant m-1}^{\overleftarrow{ }}\left(B-t_{s}^{-1} \mathrm{Id}_{n}\right) \tag{5.13}
\end{equation*}
$$

Again, we are interested in the different functions obtained by developing with respect to $\eta$, that is we write $H_{j}^{m}=\sum_{l=0}^{j} \eta^{l} H_{j, l}^{m}$. We can explicitly write down the elements for $l=0$ and get

$$
\begin{equation*}
H_{j, 0}^{m}=\sum_{i_{1}, \ldots, i_{j}} \prod_{a=0}^{j-1} x_{i_{a(m+1)+1}} \prod_{s=1}^{m}\left(\frac{x_{i_{a m+s+1}} f_{i_{a m+s} i_{a m+s+1}}}{x_{i_{a m+s}}-t x_{i_{a m+s+1}}}-t_{s-1}^{-1} \frac{\delta_{\left(i_{a m+s} i_{a m+s+1}\right)}}{x_{i_{a m+s+1}}}\right) . \tag{5.14}
\end{equation*}
$$

As noticed for the family $\left(G_{j, l}^{m}\right)_{j, l}$, the functions $H_{j, j}^{m}$ and $H_{j, 0}^{m}$ are not independent. Using that $\Theta=$ $X Z X^{-1} Z^{-1}$, we can write $(1+\eta \Theta)\left(Z-X^{-1}\right)$ as $\left(Z-X^{-1}\right)+\eta X Z\left(Z-X^{-1}\right) Z^{-1} X^{-1}$, so that in (5.11) it gives after expanding in $\eta$

$$
\begin{equation*}
\operatorname{tr}((1+\eta \Theta) Y)^{j m}=\operatorname{tr}\left(\left(Z-X^{-1}\right)\right)^{j m}+\cdots+\eta^{j m} \operatorname{tr}\left(X Z\left(Z-X^{-1}\right) Z^{-1} X^{-1}\right)^{j m} \tag{5.15}
\end{equation*}
$$

thus the factors in $\eta^{0}$ and $\eta^{j m}$ agree, implying that $H_{j, j}^{m}$ and $H_{j, 0}^{m}$ are multiples of each other, after normalisation by the constant $m^{-1} C^{-j}$ from above.

Let's remark two results about those families. First, in the limit $q_{0} \rightarrow \infty$ where we fix the other $q_{s}$, all $t_{s} \rightarrow \infty$ and we can see from (5.13) that $H_{j, 0}^{m} \rightarrow G_{j, 0}^{m}$. So, by rescaling the $H_{j, l}^{m}$, we can recover all the $\left(G_{j, l}^{m}\right)_{j, l}$ in that limit. Though it is an alternative proof of their involution, the phase space is not defined in that limit. Second, For a given $m$, each function $H_{j, l}^{m}$ can be written as a linear combination of $\left(G_{j^{\prime}, l l}^{m^{\prime}}\right)_{j^{\prime}, l l^{\prime}}$ with smaller indices. If we allow the definition of $G_{1,0}^{m}=t^{-1} \operatorname{tr} B^{m} A^{-1}$ and $G_{1,1}^{m}=t^{-1} \operatorname{tr} A^{-1} S B^{m-1}$ for $m=0,1$, we get for example,

$$
\begin{equation*}
H_{1,1}^{2}=t t_{0}\left(G_{1,0}^{2}+G_{1,1}^{2}\right)-t\left(\frac{t_{0}}{t_{1}}+1\right)\left(G_{1,0}^{1}+G_{1,1}^{1}\right)+\frac{t}{t_{1}}\left(G_{1,0}^{0}+G_{1,1}^{0}\right) \tag{5.16}
\end{equation*}
$$

Finally, we look at the second family $\operatorname{tr}\left(\left(1+\eta \Theta^{-1}\right)(1+X Y)\right)^{j}$ in Theorem 5.4, for any $j \in \mathbb{N}$. We first remark that in $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m),\left(1+\eta \Theta^{-1}\right) X Z=X Z+\eta Z X$. Meanwhile, $X_{s} Z_{s}$ is nothing else than $t_{s} B$, while for $s \neq m-1 Z_{s} X_{s}=t_{s} B$ but $Z_{m-1} X_{m-1}=t A^{-1} B A$. This gives us, if we call the elements $F_{j}^{m}$,

$$
\begin{equation*}
F_{j}^{m}=\sum_{s=0}^{m-1} \operatorname{tr}\left(X_{s} Z_{s}+\eta Z_{s} X_{s}\right)^{j}=\left(\sum_{s=0}^{m-2} t_{s}(1+\eta)\right) \operatorname{tr}(B)^{j}+t \operatorname{tr}\left(B+\eta A^{-1} B A\right)^{j} . \tag{5.17}
\end{equation*}
$$

It is just a family equivalent to $\left(G_{j}^{1}\right)_{j}$ with $G_{j}^{1}=\operatorname{tr}\left(B+\eta A^{-1} B A\right)^{j}$, corresponding to the spin RS system, see [34]. Developing $F_{j}^{m}=\sum_{l=0}^{j} \eta^{l} F_{j, l}^{m}$, we also get that $F_{j, 0}^{m}$ and $F_{j, j}^{m}$ are proportional.

### 5.3 Explicit flows

We now show that we can get explicit expressions for the flows associated to particular elements of the families in Theorem 5.4 in $\mathcal{C}_{n, \tilde{q}, d}(m)$. Computations for the results that we use now and the general philosophy behind them are gathered in Appendix C.

Recall that the family $\left(G_{k}^{m}\right)_{k}$ is defined in $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ from the elements $\operatorname{tr}\left(U_{\eta}^{k}\right)$, where $U_{\eta}=Z(1+\eta \Theta)$ represents the element $z(1+\eta \phi) \in A$. We get from Lemma C. 1 and (2.14)

$$
\frac{1}{k}\left\{\operatorname{tr} U_{\eta}^{k}, X\right\}_{\mathrm{P}}=-\eta \Theta U_{\eta}^{k-1} Z X-X U_{\eta}^{k-1} Z, \quad \frac{1}{k}\left\{\operatorname{tr} U_{\eta}^{k}, Z\right\}_{\mathrm{P}}=-Z U_{\eta}^{k-1} Z+U_{\eta}^{k-1} Z^{2}
$$

while the Poisson brackets with $V_{\beta}$ or $W_{\beta}$ vanish. It does not look possible to explicitly integrate most flows. Indeed, even the matrix $U_{\eta}$ is not a constant of motion under $\operatorname{tr} U_{\eta}^{k}$, though its symmetric functions certainly are. However, looking at order 0 in $\eta$, we get $\operatorname{tr} Z^{k}$ which is $G_{k, 0}^{m}$ up to a constant, and if we look at the flow defined by $d / d t_{k}=\frac{1}{k}\left\{\operatorname{tr} Z^{k},-\right\}_{\mathrm{P}}$, we get the defining ODEs

$$
\frac{d X}{d t_{k}}=-X Z^{k}, \quad \frac{d Z}{d t_{k}}=0, \quad \frac{d V_{\beta}}{d t_{k}}=0, \quad \frac{d W_{\beta}}{d t_{k}}=0
$$

which can be easily integrated.
Proposition 5.5 Given the initial condition $\left(X(0), Z(0), V_{\beta}(0), W_{\beta}(0)\right)$, the flow at time $t_{k}$ defined by the Hamiltonian $\operatorname{tr} Z^{k}$ for $k \in m \mathbb{N}$ is given by

$$
X\left(t_{k}\right)=X(0) \exp \left(-t_{k} Z(0)^{k}\right), \quad Z\left(t_{k}\right)=Z(0), \quad V_{\beta}\left(t_{k}\right)=V_{\beta}(0), \quad W_{\beta}\left(t_{k}\right)=W_{\beta}(0)
$$

In particular, the flows are complete in $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ so that we can reintroduce $\mathbf{A}^{(m)}$ and $\mathbf{C}^{(m)}$ for all times, although some $X\left(t_{k}\right)$ could be non-diagonalizable. Remark also that this expression does not exactly coincide with [1, Proposition 4.7] when $d=1$. This is due to our different choice of ordering at the vertices $s \in I$, so that $\mathcal{C}_{n, \tilde{q}, d}(m)$ for $d=1$ is isomorphic to the space in [1, Section 4] but this map is not the identity map. This is also true for the next flows.

For the other family $\left(H_{k}^{m}\right)_{k}$, expressed from $\operatorname{tr} \bar{U}_{\eta}^{k}$ if we set $\bar{U}_{\eta}=Y(1+\eta \Theta)$, Lemma C. 2 and (2.14) give

$$
\frac{1}{k}\left\{\operatorname{tr} \bar{U}_{\eta}^{k}, X\right\}_{\mathrm{P}}=-\bar{U}_{\eta}^{k-1}-X \bar{U}_{\eta}^{k-1} Y-\eta \Theta \bar{U}_{\eta}^{k-1}(1+Y X), \quad \frac{1}{k}\left\{\operatorname{tr} \bar{U}_{\eta}^{k}, Y\right\}_{\mathrm{P}}=-Y \bar{U}_{\eta}^{k-1} Y+U_{\eta}^{k-1} Y^{2}
$$

and the Poisson brackets with $V_{\beta}$ or $W_{\beta}$ vanish. Again, we can write the flows for the functions which are the coefficients at order 0 in $\eta$. If we want to obtain the flow of $\operatorname{tr} Y^{k}$ which is a multiple $H_{k, 0}^{1}$, we get by writing $d / d \tau_{k}=\frac{1}{k}\left\{\operatorname{tr} Y^{k},-\right\}_{\mathrm{P}}$ that

$$
\frac{d X}{d \tau_{k}}=-Y^{k-1}-X Y^{k}, \quad \frac{d Y}{d \tau_{k}}=0, \quad \frac{d V_{\beta}}{d \tau_{k}}=0, \quad \frac{d W_{\beta}}{d \tau_{k}}=0
$$

Proposition 5.6 Given the initial condition $\left(X(0), Y(0), V_{\beta}(0), W_{\beta}(0)\right)$ the flow at time $\tau_{k}$ defined by the Hamiltonian $\operatorname{tr} Y^{k}$ for $k \in m \mathbb{N}$ is given by

$$
\begin{aligned}
& X\left(\tau_{k}\right)=X(0) \exp \left(-\tau_{k} Y(0)^{k}\right)+Y(0)^{-1}\left[\exp \left(-\tau_{k} Y(0)^{k}\right)-\mathrm{Id}_{n}\right], \\
& Y\left(\tau_{k}\right)=Y(0), \quad W_{\beta}\left(\tau_{k}\right)=W_{\beta}(0), \quad V_{\beta}\left(\tau_{k}\right)=V_{\beta}(0)
\end{aligned}
$$

The expression for $X\left(\tau_{k}\right)$ is analytic in $Y(0)$ so does not require its invertibility. The dynamics take place in $\mathcal{C}_{n, \widetilde{q}, d}(m)$.

Reproducing this scheme for the family $\left(F_{k}^{m}\right)_{k}$ using Lemma C. 3 and (2.14), this yields for $\tilde{U}_{\eta}=$ $(1+X Y)\left(1+\eta \Theta^{-1}\right)$

$$
\begin{aligned}
\frac{1}{k}\left\{\operatorname{tr} \tilde{U}_{\eta}^{k}, X\right\}_{\mathrm{P}} & =-\tilde{U}_{\eta}^{k-1}(1+X Y) X-\eta X \Theta^{-1} \tilde{U}_{\eta}^{k-1}(1+X Y) \\
\frac{1}{k}\left\{\operatorname{tr} \tilde{U}_{\eta}^{k}, 1+X Y\right\}_{\mathrm{P}} & =(1+X Y) \tilde{U}_{\eta}^{K-1}(1+X Y)-\tilde{U}_{\eta}^{K-1}(1+X Y)^{2},
\end{aligned}
$$

and the Poisson brackets with $V_{\beta}$ or $W_{\beta}$ vanish. It is easier to work with $1+X Y$ instead of $Y$ in this case, because when we look at order 0 in $\eta$ we obtain for the flow of $\operatorname{tr}(1+X Y)^{k}$ after setting $d / d \tilde{t}_{k}=$ $\frac{1}{k}\left\{\operatorname{tr}(1+X Y)^{k},-\right\}_{\mathrm{P}}$ that

$$
\frac{d X}{d \tilde{t}_{k}}=-(1+X Y)^{k} X, \quad \frac{d(1+X Y)}{d \tilde{t}_{k}}=0, \quad \frac{d V_{\beta}}{d \tilde{t}_{k}}=0, \quad \frac{d W_{\beta}}{d \tilde{t}_{k}}=0 .
$$

Proposition 5.7 Given the initial condition ( $\left.X(0), Y(0), V_{\beta}(0), W_{\beta}(0)\right)$, setting $T=1+X Y$, the flow at time $\tilde{t}_{k}$ defined by the Hamiltonian $\operatorname{tr} T^{k}$ for $k \in \mathbb{N}$ is given by

$$
X\left(\tilde{t}_{k}\right)=\exp \left(-\tilde{t}_{k} T(0)^{k}\right) X(0), \quad T\left(\tilde{t}_{k}\right)=T(0), \quad V_{\beta}\left(\tilde{t}_{k}\right)=V_{\beta}(0), \quad W_{\beta}\left(\tilde{t}_{k}\right)=W_{\beta}(0)
$$

In particular, assuming that $X(0)$ is invertible, this completely determines the solution $Y\left(\tilde{t}_{k}\right)=$ $X\left(\tilde{t}_{k}\right)^{-1}\left[T\left(\tilde{t}_{k}\right)-1\right]$ for all time $\tilde{t}_{k}$.

The extra assumption that $X(0)$ is invertible is satisfied in our interpretation of this family as being the one containing the spin RS Hamiltonian. In that case, the flows take place in $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ where they are complete. Using the isomorphism of Proposition 5.2, we can see that they can be related to the corresponding flows derived in [28, 34].

A natural question to ask is to obtain locally the flows that we could not compute explicitly. As we see in Section 5.5, we can define integrable systems from these families in order to compute them by quadrature. However, this requires the additional assumption $d \leqslant n$, which we comment in Section 5.6.1.

### 5.4 Linear independence

We assume from now on that $d \leqslant n$ and look at the number of independent functions in each family. Since the family $\left(F_{j, l}^{m}\right)_{j, l}$ corresponds to functions for the spin RS system, we already know that this contains $n d-d(d-1) / 2$ linearly independent elements [26].

For the families $\left(G_{j, l}^{m}\right)_{j, l}$ and $\left(H_{j, l}^{m}\right)_{j, l}$, remark that there can be at most $n(n+1) / 2$ linearly independent functions. Indeed, we look at the symmetric functions of $n \times n$ matrices (see (5.9), (5.12)), so we have by developing in $\eta, n+n(n+1) / 2$ functions for $j=1, \ldots, n$, with $n$ constraints coming from the relation between the terms $(j, 0)$ and $(j, j)$. It now suffices to remark that we can write these functions generically in the form $\left\{\operatorname{tr}(C+\eta T)^{j} \mid 1 \leqslant j \leqslant n\right\}$ for $C$ invertible with distinct eigenvalues, and $T$ of rank $d$, with distinct non-zero eigenvalues. This yields $(n-d)(n-d+1) / 2$ additional constraints, as we now explain with the family $\left(G_{j, l}^{m}\right)_{j, l}$. The other case is similar.

We adapt the method introduced for the spin CM family [25, 42], and we write $G_{k}^{m}=\operatorname{tr}(C+\eta T)^{k}$ for $C=A^{-1} B^{m}, T=S B^{m-1} A^{-1}$ and $\eta=\eta^{\prime} /\left(t^{-1}+\eta^{\prime}\right)$, see (5.9). Remark that $C, T$ take the form stated above. Consider the spectral curve

$$
\begin{equation*}
\Gamma(\eta, \mu) \equiv \operatorname{det}\left((C+\eta T)-\mu \mathrm{Id}_{n}\right)=0 \tag{5.18}
\end{equation*}
$$

We write $\Gamma(\eta, \mu) \equiv \sum_{i=0}^{n} r_{i}(\eta) \mu^{i}=0$, where $r_{i}(\eta)$ is a symmetric function of order $n-i$ of $C+\eta T$, so is a function of $\left\{G_{k, K}^{m} \mid 0 \leqslant K \leqslant k, 1 \leqslant k \leqslant n-i\right\}$, if we consider the expansion ${ }^{4} G_{k}^{m}=\sum_{K=0}^{k} G_{k, K}^{m} \eta^{K}$. We can expand each $r_{i}(\eta)$ in terms of $\eta$ as $r_{i}(\eta)=\sum_{s=0}^{n-i} I_{n-i, s} \eta^{s}$. Hence the set of linearly independent functions is contained in the $\left\{I_{n-i, s}\right\}$, which are functions of the $n+n(n+1) / 2$ functions $\left\{G_{k, K}^{m}\right\}$. It remains to see how many relations exist on the $\left\{I_{n-i, s}\right\}$. In a neighbourhood of $\eta=\infty$, we can write

$$
\begin{equation*}
\Gamma(\eta, \mu)=\prod_{i=1}^{n}\left(\mu-\mu_{i}(\eta)\right), \quad \text { for } \mu_{i}(\eta)=\eta v_{i} \tag{5.19}
\end{equation*}
$$

for $\left(v_{i}\right)_{i}$ the eigenvalues of $T$. At a generic point, we can order the $\left(v_{i}\right)_{i}$ so that $\nu_{1}<\nu_{2}<\cdots<v_{d}$ are non-zero, and $v_{d+1}=\cdots=v_{n}=0$. Thus near $\eta=\infty$ we write $\Gamma(\eta, \mu)=\mu^{n-d} \prod_{i=1}^{d}\left(\mu-\eta v_{i}\right)$. From this behaviour at infinity, we require that if we write $\Gamma(\eta, \mu) \equiv \sum_{i=0}^{n} \Gamma_{i}(\mu) \eta^{i}$, then $\Gamma_{i}(\mu)=0$ for all $i=d+1, \ldots, n$. Each $\Gamma_{i}(\mu)$ has order $n-i$ as a polynomial in $\mu$ whose coefficients are functions of the $\left\{I_{n-i, s}\right\}$. Hence, we get the expansion $\Gamma_{i}(\mu)=\sum_{s=0}^{n-i} J_{n-i, s} \mu^{s}$, for some functions $J_{n-i, s}\left(I_{k, t}\right)$. Their vanishing for $i>d$ is equivalent to imposing

$$
\sum_{i=d+1}^{n}(n-i+1)=\frac{(n-d)(n-d+1)}{2}
$$

relations, which proves our claim. Imposing the initial $n$ relations, which are independent from the ones just obtained, we have a total of $n d-d(d-1) / 2$ independent functions.

### 5.5 Additional reduction

We would like to construct a space of dimension $2 n d-d(d-1)$ into which the different families descend. Introduce the $d(d-1)$-dimensional algebraic group

$$
\begin{equation*}
\mathcal{H}=\left\{h=\left(h_{\alpha \beta}\right) \in \mathrm{GL}_{d}(\mathbb{C}) \mid \sum_{\beta=1}^{d} h_{\alpha \beta}=1 \text { for all } \alpha\right\}, \tag{5.20}
\end{equation*}
$$

whose elements are invertible $d \times d$ matrices such that the vector $(1, \ldots, 1)^{\top}$ is an eigenvector with eigenvalue +1 . This is precisely the algebraic group $\mathcal{H}$ needed to get Liouville integrability of the RS system in the original work [26].

Define the action of $\mathcal{H}$ on $\left(X, Z, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ by $h \cdot\left(X, Z, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)=\left(X, Z, \mathbf{A}^{(m)} h, h^{-1} \mathbf{C}^{(m)}\right)$. By definition of $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ at the end of Section 5.1, we can always take a representative $\left(X, Z, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ on this subspace such that $\sum_{\alpha}\left(X \mathbf{A}^{(m)}\right)_{i \alpha}=1$ for all $i$. This condition is preserved under the action of $\mathcal{H}$. Hence, we define the reduced space $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ as the affine GIT quotient $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)=\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m) / / \mathcal{H}$. It has dimension $2 n d-d(d-1)$ and is generically smooth as we will shortly see. The coordinate ring $\mathrm{O}\left(\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)\right)$ is generated by elements of the form $\operatorname{tr} \gamma$, where $\gamma$ is a word in the letters $X, Z, S=\mathbf{A}^{(m)} \mathbf{C}^{(m)}$. If we write such functions in coordinates by lifting them to $\mathcal{C}_{n, \widetilde{q}, d}^{\prime}(m)$, they become invariant polynomial in the elements $\left(x_{i}, x_{i} x_{j}^{-1}-t, f_{i j}\right)_{i j}$, which form a Poisson subalgebra of $\{-,-\}$ by Proposition 4.1. Thus the Poisson bracket $\{-,-\}_{\mathrm{P}}$ descends to $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$. It is such that the projection $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m) \rightarrow \mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ dual to the inclusion $\mathrm{O}\left(\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)^{\mathcal{H}}\right) \rightarrow \mathrm{O}\left(\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)\right)$ is a Poisson morphism.

[^4]Theorem 5.8 The families $\left\{F_{j, l}^{m} \mid(j, l) \in J_{d}\right\},\left\{G_{j, l}^{m} \mid(j, l) \in J_{d}\right\}$ and $\left\{H_{j, l}^{m} \mid(j, l) \in J_{d}\right\}$ define completely integrable systems on the smooth part of $\mathcal{C}_{n, \boldsymbol{q}, d}^{\mathcal{H}}(m)$, for $J_{d}=\{(j, l) \mid j=1, \ldots, n, l=0, \ldots, \min (j-1, d)\}$.

Proof. We show the existence of a non-empty open subset of $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ where $\mathcal{H}$ acts properly and freely in Lemmas 5.9 and 5.10, so that the corresponding space of $\mathcal{H}$-orbits defines a smooth complex manifold of dimension $2 n d-d(d-1)$ inside $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$. In particular, a point $(X, Z, \mathbf{A}, \mathbf{C})$ in the subspace is characterized by the fact that all the $d$-dimensional minors of $\mathbf{A}$ are non-zero. This is the complement of the Zariski closed subsets defined by having a vanishing minor of dimension $d$. Thus this subspace is dense in $\mathcal{C}_{n, \tilde{\tilde{q}, d}}^{\prime}(m)$, and so does its reduction in $\mathcal{C}_{n, \tilde{\tilde{q}, d}}^{\mathcal{H}}(m)$. The elements in each family are $\mathcal{H}$-invariant, and also linearly independent by the argument developed in Section 5.4. Thus the proof follows for the first two families. For the last family, remark that we also need to restrict to the open subset where $Y$ is invertible before performing the reduction, but this is dense again.

Using the isomorphism of Proposition 5.2, a point $\left(X, Z, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ of $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ can be equivalently characterized by a quadruple ( $A, B, \mathbf{A}, \mathbf{C}$ ) satisfying (4.8). By abuse of notation, we denote this point by $(X, Z, \mathbf{A}, \mathbf{C})$ and assume that it has the form just stated. We remark that the $\mathcal{H}$-action is given by $h \cdot(X, Z, \mathbf{A}, \mathbf{C})=\left(X, Z, \mathbf{A} h, h^{-1} \mathbf{C}\right)$ so that $\sum_{\alpha}(\mathbf{A} h)_{i \alpha}=1$ for all $i$.

Lemma 5.9 The action is free on the subset of $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ where, given a point $(X, Z, \mathbf{A}, \mathbf{C})$, either $\mathbf{A}$ or $\mathbf{C}$ has rank $d$.

Proof. Assume $\mathbf{A}$ has rank $d$, the proof being the same if we assume the latter for $\mathbf{C}$. By definition, there exists $K=\left(k_{1}, \ldots, k_{d}\right) \subset\{1, \ldots, n\}$ such that $\overline{\mathbf{A}}=\left(\mathbf{A}_{k_{\alpha} \beta}\right)$ is a $d \times d$ matrix which has rank $d$, so is invertible. If we take some $h$ in the stabilizer of the point ( $X, Z, \mathbf{A}, \mathbf{C}$ ), then in particular $\mathbf{A} h=\mathbf{A}$ and thus $\overline{\mathbf{A}} h=\overline{\mathbf{A}}$. Indeed,

$$
\begin{equation*}
(\overline{\mathbf{A}} h)_{\alpha \beta}=\sum_{\gamma} \mathbf{A}_{k_{\alpha} \gamma} h_{\gamma \beta}=(\mathbf{A} h)_{k_{\alpha} \beta}=\mathbf{A}_{k_{\alpha} \beta}=\overline{\mathbf{A}}_{\alpha \beta} . \tag{5.21}
\end{equation*}
$$

Since $\overline{\mathbf{A}}$ is invertible, $h=\mathrm{Id}_{d}$.
Lemma 5.10 The action is proper on the subset $\overline{\mathcal{S}} \subset \mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$ where, given a point $(X, Z, \mathbf{A}, \mathbf{C})$, all the minors of dimension $d$ of $\mathbf{A}$ are invertible.

Proof. The claim follows if we can show that given sequences $\left(h_{m}\right) \subset \mathcal{H},\left(X_{m}, Z_{m}, \mathbf{A}_{m}, \mathbf{C}_{m}\right) \subset \overline{\mathcal{S}}$ satisfying $\left(X_{m}, Z_{m}, \mathbf{A}_{m}, \mathbf{C}_{m}\right) \rightarrow(X, Z, \mathbf{A}, \mathbf{C}) \in \overline{\mathcal{S}}$ and $h_{m} \cdot\left(X_{m}, Z_{m}, \mathbf{A}_{m}, \mathbf{C}_{m}\right) \rightarrow\left(X^{\prime}, Z^{\prime}, \mathbf{A}^{\prime}, \mathbf{C}^{\prime}\right) \in \overline{\mathcal{S}}$, then $h_{m}$ converges in $\mathcal{H}$. Note that trivially $X^{\prime}=X$ and $Z^{\prime}=Z$.

For any choice of $K=\left(k_{1}, \ldots, k_{d}\right) \subset\{1, \ldots, n\}$, we can form $\overline{\mathbf{A}}$ as in Lemma 5.9. We also use the notation $\bar{D}$ for the $d \times d$ matrix obtained in that way from some $n \times d$ matrix $D$. We see that $h_{m}=\overline{\mathbf{A}}_{m}^{-1} \overline{h_{m} \cdot \mathbf{A}_{m}}$, since the minors of $\mathbf{A}_{m}$ are invertible and $\overline{h_{m} \cdot \mathbf{A}_{m}}=\overline{\mathbf{A}}_{m} h_{m}$.

From this, form $h:=\overline{\mathbf{A}}^{-1} \overline{\mathbf{A}^{\prime}}$. This element does not depend on the choice of $K:$ take any two $K, L \subset\{1, \ldots, n\}$ and construct $\overline{\mathbf{A}}_{m}^{(K)}$ and $\overline{\mathbf{A}}_{m}^{(L)}$ for all $m$ as before, where the superscript denotes the partition to which we refer. They are both invertible, so they are related by $\overline{\mathbf{A}}_{m}^{(K)}=T_{m} \overline{\mathbf{A}}_{m}^{(L)}$ for some $T_{m} \in \mathrm{GL}_{d}(\mathbb{C})$. Forming $h^{(K)}$ and $h^{(L)}$ from them, we get

$$
h^{(K)}=\lim _{m \rightarrow \infty}\left(\overline{\mathbf{A}}_{m}^{(K)}\right)^{-1}\left(h_{m} \cdot \overline{\mathbf{A}}_{m}^{(K)}\right)=\lim _{m \rightarrow \infty}\left(\overline{\mathbf{A}}_{m}^{(L)}\right)^{-1} T_{m}^{-1} T_{m}\left(h_{m} \cdot \overline{\mathbf{A}}_{m}^{(L)}\right)=h^{(L)} .
$$

Next, remark that $h \in \mathrm{GL}_{d}(\mathbb{C})$ : as $h=\overline{\mathbf{A}}^{-1} \overline{\mathbf{A}^{\prime}}$ and both elements on the right-hand side have non-zero determinant, so too has $h$. Finally, $h \in \mathcal{H}$ because

$$
\sum_{\beta} h_{\alpha \beta}=\sum_{\gamma, \beta}\left(\overline{\mathbf{A}}^{-1}\right)_{\alpha \gamma} \overline{\mathbf{A}}_{\gamma \beta}^{\prime}=\sum_{\gamma}\left(\overline{\mathbf{A}}^{-1}\right)_{\alpha \gamma} 1=1 .
$$

Here we use that $\sum_{\alpha} \mathbf{A}_{i \alpha}=1$ for all $i$, implies that we have $\sum_{\alpha} \overline{\mathbf{A}}_{\gamma \alpha}=1$ for all $\gamma$. That is $\overline{\mathbf{A}} \in \mathcal{H}$, which in turn yields $\overline{\mathbf{A}}^{-1} \in \mathcal{H}$.

We summarize the projection from the representation space of the multiplicative preprojective algebra to the space we have just constructed as

$$
\begin{equation*}
\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right) \longrightarrow \mathcal{C}_{n, \tilde{q}, d}(m) \supsetneq \mathcal{C}_{n, \tilde{q}, d}^{\prime}(m) \longrightarrow \mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m) \tag{5.22}
\end{equation*}
$$

Let us formulate one last comment on the reduced space $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$. We can integrate some equations of motions for the families in Theorem 5.4, thus defining flows in $\mathcal{C}_{n, \tilde{q}, d}(m)$. If flows quit the subspace $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$, then the last projection given in (5.22) cannot be defined, so the flows are not complete in $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{T}}(m)$. This suggests that $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ is not the natural phase space for our systems in the complex case, and it motivates a search for other first integrals, see Section 5.6.1.

### 5.6 Final remarks

We finish by some additional comments that could lead to new investigations about these models.
5.6.1 Integrability before reduction In Section 5.5, we constructed the space $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ as the complex analogue of the phase space for the real trigonometric spin RS system considered by Krichever and Zabrodin [26]. However, we noticed in the complex setting that some flows are not complete inside $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$, but they are in the larger space $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ by Proposition 5.7. This suggests that we should be able to build an integrable system containing the Hamiltonian for the trigonometric spin RS system directly in $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m)$. This is proved in [34], and we can in fact adapt the method to our case for the different Hamiltonians $\operatorname{tr} Z^{k m}, \operatorname{tr} Y^{k m}, \operatorname{tr} X^{k m}$ and $\operatorname{tr}(1+X Y)^{k}, k \in \mathbb{N}$. In the case $d=2$, it easily follows from the next result, which is a direct application of Lemma 3.3.

THEOREM 5.11 The following families of functions on $\mathcal{C}_{n, \tilde{q}, d}(m)$ are linearly independent and in involution

$$
\begin{aligned}
& \left\{\operatorname{tr} X^{j m}, \operatorname{tr}\left(W_{1} V_{1} X^{j m}\right) \mid j=1, \ldots, n\right\}, \quad\left\{\operatorname{tr}(1+X Y)^{j}, \operatorname{tr}\left(W_{1} V_{1}(1+X Y)^{j}\right) \mid j=1, \ldots, n\right\}, \\
& \left\{\operatorname{tr} Y^{j m}, \operatorname{tr}\left(W_{1} V_{1} Y^{j m}\right) \mid j=1, \ldots, n\right\}, \quad\left\{\operatorname{tr} Z^{j m}, \operatorname{tr}\left(W_{1} V_{1} Z^{j m}\right) \mid j=1, \ldots, n\right\},
\end{aligned}
$$

where the last family is viewed on the subspace $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m) \subset \mathcal{C}_{n, \widetilde{q}, d}(m)$ where $X$ is invertible.
For the case $d \geq 3$, the construction is more involved as we need more Poisson commuting functions, and we leave the details of adapting [34, Section 5.2] to the reader. Rather, we will look at another feature of these systems which is their degenerate integrability (also called non-commutative integrability or superintegrability), and was first remarked for the spin RS system by Reshetikhin in the real rational case [31].

Our method follows [34]. We only consider $U=Y$ or $U=Z$, as they define new non-trivial Hamiltonians. We introduce the commutative algebra $\mathcal{Q}_{U}$ generated by the elements $\operatorname{tr} W_{\alpha} V_{\beta} U^{l m}$ for all $1 \leq \alpha, \beta \leq d$, with $l \in \mathbb{N}$.

Lemma 5.12 The algebra $\mathcal{Q}_{U}$ is a Poisson algebra under the Poisson bracket $\{-,-\}_{\mathrm{p}}$.
Proof. We show that $\left\{\operatorname{tr} W_{\alpha} V_{\beta} Y^{l m}, \operatorname{tr} W_{\gamma} V_{\epsilon} Y^{k m}\right\}_{P} \in \mathcal{Q}_{U}$ which proves the case $U=Y$. We leave the similar case $U=Z$ to the reader.

By inspecting the double brackets between the elements ( $y, v_{\alpha}, w_{\alpha}$ ) in Section 3, we see that the double bracket $\left\{\left\{w_{\alpha} v_{\beta} y^{l m}, w_{\gamma} v_{\epsilon} y^{k m}\right\}\right\}$ is such that its two components are (sums of) words in $w_{\alpha}, w_{\gamma}, v_{\beta}, v_{\epsilon}, y$. At the same time, this double bracket is an element of $e_{0} A e_{0} \otimes e_{0} A e_{0}$, so its two components are in fact words in $w_{\mu} v_{v}$ and $y^{m}$, with $\mu \in\{\alpha, \gamma\}, \nu \in\{\beta, \epsilon\}$. Applying the multiplication map also yields a word $\rho \in e_{0} A e_{0}$ written with the same letters. Moreover, a careful analysis of the double bracket shows that $\rho$ has to contain at least a factor $w_{\mu} v_{\nu}$. Using (2.13), these remarks yield that

$$
\left\{\operatorname{tr} W_{\alpha} V_{\beta} Y^{\operatorname{lm}}, \operatorname{tr} W_{\gamma} V_{\epsilon} Y^{k m}\right\}_{\mathrm{P}}=\operatorname{tr} R, \quad \text { for some } R \in \mathbb{C}\left[Y^{m}, W_{\alpha} V_{\beta}, W_{\alpha} V_{\epsilon}, W_{\gamma} V_{\epsilon}, W_{\gamma} V_{\beta}\right] \backslash \mathbb{C}\left[Y^{m}\right] .
$$

Now, the terms of $\operatorname{tr} R$ are of the form

$$
\operatorname{tr}\left(\left(Y^{m}\right)^{a_{1}} W_{\mu_{1}} V_{v_{1}}\left(Y^{m}\right)^{a_{2}} W_{\mu_{2}} V_{v_{2}} \ldots W_{\mu_{j}} V_{v_{j}}\left(Y^{m}\right)^{a_{j}}\right)=\left(V_{v_{1}} Y^{a_{2} m} W_{\mu_{2}}\right) \ldots\left(V_{v_{j}} Y^{\left(a_{j}+a_{1}\right) m} W_{\mu_{1}}\right)
$$

Since $V_{\nu} Y^{a} W_{\mu}=\operatorname{tr} W_{\mu} V_{\nu} Y^{a} \in \mathcal{Q}_{U}$, any term of $\operatorname{tr} R$ is an element of $\mathcal{Q}_{U}$.
Next, we remark by multiplying the identities (5.1a)-(5.1b) that we can write on the subspace \{det $U \neq 0\}$ of $\mathcal{C}_{n, \tilde{q}, d}(m)$ that

$$
\begin{equation*}
M U^{m} M^{-1}=t \prod_{\alpha=1, \ldots, d}\left(\mathrm{Id}_{n}+W_{\alpha} V_{\alpha}\right) U^{m} \tag{5.23}
\end{equation*}
$$

with $M=X_{0}$ if $U=Z$ or $M=\left(X_{0}+Y_{0}^{-1}\right)$ if $U=Y$. In particular, by taking traces of higher powers of this identity, we get that any $\operatorname{tr} U^{l m} \in \mathcal{Q}_{U}$ for $U=Y, Z$. Meanwhile, we have that the elements $\left(\operatorname{tr} U^{k m}\right)$ Poisson commute with any function $\operatorname{tr} W_{\alpha} V_{\beta} U^{k l}$ by Lemma 3.3 and (2.13). Thus, they are in the centre of the Poisson algebra $\mathcal{Q}_{U}$.

Proposition 5.13 The algebra $\mathcal{Q}_{U}$ has dimension $2 n d-n$ and its centre is generated by the elements $\operatorname{tr} U^{m}, \ldots, \operatorname{tr} U^{m n}$, so it has dimension $n$.

Proof. A first method is to adapt the case when $m=1$ given in [34, Proposition 5.2]. We sketch another possible proof when $U=Y$, based on a suitable choice of local coordinates similar to [34, Lemma 5.6].

Consider non-zero elements $y_{1}, \ldots, y_{n} \in \mathbb{C}$ satisfying $y_{i} \neq y_{j}, y_{i} \neq t y_{j}$, for $i \neq j$. Consider also arbitrary $w_{\alpha, i}, v_{\alpha, i} \in \mathbb{C}$ for $i=1, \ldots, n$ and $1 \leq \alpha<d$. We denote by $\mathfrak{h}^{\prime}$ the subspace of $\mathbb{C}^{2 n d-n}$ with the above elements as coordinates, under the additional $d-1$ conditions that $\sum_{i} v_{\alpha, i} w_{\alpha, i} \neq 0$. We then define the matrices $Y_{s} \in \mathrm{GL}_{n}(\mathbb{C})$ for $s \in I$, and $W_{\alpha} \in \operatorname{Mat}_{n \times 1}(\mathbb{C})$, $V_{\alpha} \in \operatorname{Mat}_{1 \times n}(\mathbb{C})$ for $1 \leq \alpha<d$ by

$$
Y_{0}=\operatorname{diag}\left(y_{1}, \ldots, y_{n}\right), Y_{s}=\operatorname{Id}_{n} \text { for } s \neq 0, \quad\left(V_{\alpha}\right)_{i}=v_{\alpha, i}, \quad\left(W_{\alpha}\right)_{i}=w_{\alpha, i}
$$

For a generic point of $\mathfrak{h}^{\prime}$, we can then find $V_{d} \in \operatorname{Mat}_{n \times 1}(\mathbb{C})$ such that, if $W_{d}:=(1, \ldots, 1)^{\top}$, the matrices $Y_{0}$ and $F_{d}=t\left(\mathrm{Id}_{n}+W_{d} V_{d}\right) \ldots\left(\mathrm{Id}_{n}+W_{1} V_{1}\right) Y_{0}$ have the same spectrum. Indeed, this is just a rank one perturbation of the matrix $t\left(\operatorname{Id}_{n}+W_{d-1} V_{d-1}\right) \ldots\left(\operatorname{Id}_{n}+W_{1} V_{1}\right) Y_{0}$. In particular, there exists a $n$-dimensional family of matrices $M$ that put $F_{d}$ in the diagonal form $Y_{0}$.

By construction, all the above matrices satisfy (5.23). We set $M_{0}=M$ and define inductively $M_{s}=$ $q_{s} Y_{s-1} M_{s-1} Y_{s}^{-1}$ for $s=1, \ldots, m-1$. Then, we put $X_{s}=M_{s}-Y_{s}^{-1}$ for all $s \in I$. It is then easy to see that the relations in (5.1a) and (5.1b) hold, and that all the invertibility conditions required to define a point in $\left\{\operatorname{det} Y^{m} \neq 0\right\} \subset \mathcal{C}_{n, \tilde{q}, d}(m)$ are satisfied. Hence, we can complete the $2 n d-n$ functions ( $y_{i}, v_{\alpha, i}, w_{\alpha, i}$ ) to get a local coordinate system around a generic point of $\mathcal{C}_{n, \tilde{q}, d}(m)$.

Finally, note that in terms of these coordinates we can write that

$$
f_{k}=\operatorname{tr} Y^{k m}=\sum_{i} y_{i}^{k}, \quad g_{k, \alpha}=\operatorname{tr} W_{d} Y^{k m} V_{\alpha}=\sum_{i} y_{i}^{k} v_{\alpha, i}, \quad h_{k, \alpha}=\operatorname{tr} W_{\alpha} Y^{k m} V_{1}=\sum_{i} y_{i}^{k} v_{1, i} w_{\alpha, i},
$$

for $\alpha \neq d$. These functions belong to $\mathcal{Q}_{U}$, and we can easily check that the subset $\left\{f_{k}, g_{k, \alpha}, h_{k, \alpha} \mid k=\right.$ $1, \ldots, n, 1 \leq \alpha<d\}$ is formed of functionally independent elements.

As a consequence, the functions $\operatorname{tr} U^{m}, \ldots, \operatorname{tr} U^{m n}$ are degenerately integrable. Their flows are complete by Propositions 5.5 and 5.6.

We will write down a complete proof for both Liouville and degenerate integrability of the four cases $U=X, Y, Z, 1+X Y$ for an arbitrary framing of a cyclic quiver in subsequent work.
5.6.2 Self-duality The work of Reshetikhin [31] considers the duality between the spin hyperbolic CM system and the spin rational RS system. This was discovered in the non-spin case by Ruijsenaars [43], together with the self-duality of the hyperbolic RS system. In the complex setting where the hyperbolic and trigonometric cases are the same, the latter self-duality can be obtained by noticing that, with the notations of Section 4 in the non-spin case $m=d=1$, the transformation $\varpi:(A, B) \mapsto(B, A)$ is an (anti-)symplectic mapping [1, Proposition 3.8]. We can make a step in that direction for the spin case, though this requires the additional reduction of Section 5.5. Hence, we assume $d \leq n$.

To work in full generalities, let $A$ be the algebra localized at $x$ constructed in Section 3. Consider the quasi-Hamiltonian algebra $\hat{A}$ obtained from $A$ by removing the elements $v_{\alpha}, w_{\alpha}, e_{\infty}$, i.e. $\hat{A}=A /\left\langle e_{\infty}\right\rangle$. This can be seen as the analogue of $A$ obtained by construction from the non-framed cyclic quiver, that is the subquiver $\bar{Q}^{\prime} \subset \bar{Q}$ supported at $I=\mathbb{Z} / m \mathbb{Z}$. We can easily see that the algebra homomorphism $\iota: \hat{A} \rightarrow \hat{A}$ defined by

$$
\begin{equation*}
\iota\left(e_{s}\right)=e_{m-s}, \quad \iota\left(x_{s}\right)=z_{m-s-1}, \quad \iota\left(z_{s}\right)=x_{m-s-1}, \tag{5.24}
\end{equation*}
$$

satisfies $\iota^{2}=\operatorname{id}_{\hat{A}}$. It corresponds to flipping $\bar{Q}^{\prime}$ such that the vertex 0 is fixed. Moreover, from (3.5a), with $z$ instead of $y$, and (3.7) we can show that

$$
(\iota \otimes \iota)\{\{x, x\}\}=-\{\{\iota(x), \iota(x)\}\}, \quad(\iota \otimes \iota)\{\{z, z\}\}=-\{\imath \iota(z), \iota(z)\}\}, \quad(\iota \otimes \iota)\{\{x, z\}\}=-\{\{\iota(x), \iota(z)\}\},
$$

so that $\iota$ is an anti-morphism of quasi-Poisson algebras. (We can check this equivalently on $\left\{\left\{x_{s}, x_{r}\right\}\right\}$, $\left\{\left\{z_{s}, z_{r}\right\}\right\}$ and $\left\{\left\{x_{r}, z_{s}\right\}\right\}$.) In particular, $\iota(\phi)=\iota\left(x z x^{-1} z^{-1}\right)=\phi^{-1}$, so $\iota$ maps the moment map of $\hat{A}$ to its inverse.

Remark that from Section 5.5 and (5.5), the coordinate ring $\mathrm{O}\left(\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)\right)$ is generated by elements of the form $\operatorname{tr}(\Gamma)$, where $\Gamma$ is a sum of matrices whose factors are either $X$ or $Z$, so that the Poisson structure on $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ is completely defined from the double brackets $\{\{x, x\}\},\{\{z, z\}\}$ and $\{\{x, z\}\}$. Indeed, they define the quasi-Poisson brackets in $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right)$ for the elements ( $X_{i j}, Z_{i j}$ ), which determine the Poisson bracket on $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ by construction. This yields the following result.

Proposition 5.14 The map $\iota: \hat{A} \rightarrow \hat{A}$ induces a (generically defined) anti-Poisson morphism $\varpi$ : $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m) \rightarrow \mathcal{C}_{n, \hat{q}, d}^{\mathcal{H}}(m)$ determined by $(X, Z) \mapsto(Z, X)$, where $\hat{q}=\left(\hat{q}_{\infty}, \hat{q}_{s}\right)$ is defined by $\hat{q}_{s}=q_{m-s}^{-1}$, $\hat{q}_{\infty}=q_{\infty}^{-1}$.

In particular, since $\iota(z)=x, \iota(\phi)=\phi^{-1}$, we have that $\varpi((1+\eta \Phi) Z)=\left(1+\eta \Phi^{-1}\right) X$. Hence, we have that the first and fourth families in Theorem 5.4 are swapped under $\varpi$.

As indicated in Proposition 5.14, $\varpi$ is only defined at a generic point, e.g. in $\mathcal{C}_{n, \tilde{q}, d}^{\mathcal{H}}(m)$ there are points where the product $Z_{0} \ldots Z_{m-1}$ is not semisimple. Hence, we do not have self-duality of the system in the strict sense of [21, 43-45] which requires a global Poisson isomorphism. Nevertheless, the underlying interpretation on the quiver $\bar{Q}^{\prime}$ is easy to understand, and works also for $m=1$, where it extends the geometric approach to the self-duality for the trigonometric RS to the spin case. Given the natural appearance of the self-duality for the non-spin case in gauge theory [46, 47], it would be interesting to understand the interpretation of the spin case within this framework.

Let us formulate two final remarks. Firstly, if we replace $z$ by $y$ in the definition of $\iota$ (5.24), this also gives an anti-morphism of quasi-Poisson algebras. Hence, the integrable system containing $\operatorname{tr} X$ is dual to the integrable system containing $\operatorname{tr} Z$, but also to the one containing $\operatorname{tr} Y$ by adapting the above argument. Secondly, note that this isomorphism $\iota: \hat{A} \rightarrow \hat{A}$ does not directly extend to $A$ itself. We will return to this issue in further work, in order to lift the map $\varpi$ to a well-defined map on $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m)$.
5.6.3 Relation to generalized symmetric group It is remarked in [1] that in the case $d=1$, the new Hamiltonians obtained for a cyclic quiver on $m$ vertices correspond to $W=S_{n} \ltimes \mathbb{Z}_{m}^{n}$. In the study of (non-multiplicative) quiver varieties, the Hamiltonians of CM type obtained in the spin case have also that particular symmetry [11, Section VI]. Thus, we would expect that the elements of the families $\left(G_{j, l}^{m}\right)_{j, l}$ and $\left(H_{j, l}^{m}\right)_{j, l}$ are also related to the generalized symmetric groups $G(m, 1, n)=S_{n} \ltimes \mathbb{Z}_{m}^{n}$. To establish this link, consider $p \in \mathcal{C}_{n, \tilde{q}, d}^{\prime}(m) \subset \mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ determined by a point of $\mathcal{C}_{n, t, d}^{\prime}$ as in Proposition 5.2. Using the local coordinates of $\mathcal{C}_{n, t, d}^{\prime}(4.8)$, the point $p=\left(X_{s}, Z_{s}, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ is characterized by $X_{s}=\operatorname{Id}_{n}$ for $s \neq m-1$, $X_{m-1}=\operatorname{diag}\left(x_{1}, \ldots, x_{n}\right)$, and the matrices $\left(Z_{s}, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ are given by

$$
\left(Z_{s}\right)_{i j}=t_{s} \frac{t f_{i j}}{x_{i} x_{j}^{-1}-t}, s \neq m-1, \quad\left(Z_{m-1}\right)_{i j}=t \frac{t x_{i}^{-1} f_{i j}}{x_{i} x_{j}^{-1}-t}, \quad\left(\mathbf{A}^{(m)}\right)_{i \alpha}=\frac{\mathbf{a}_{i}^{\alpha}}{x_{i}},\left(\mathbf{C}^{(m)}\right)_{\alpha j}=\mathbf{c}_{j}^{\alpha} .
$$

In particular, the matrices $\left(X_{s}\right)_{s}$ take two different forms: either the identity or a diagonal matrix whose entries are interpreted as particle positions. To set them all to the same diagonal matrix, recall that an element $g \in G(\widetilde{\alpha})$ acts as in (5.2), so we can write this action as

$$
\begin{equation*}
g .\left(X_{s}, Z_{s}, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)=\left(g_{s} X_{s} g_{s+1}^{-1}, g_{s+1} Z_{s} g_{s}^{-1}, \mathbf{C}^{(m)} g_{0}^{-1}, g_{0} \mathbf{A}^{(m)}\right), \quad g \in G(\widetilde{\alpha}) \tag{5.25}
\end{equation*}
$$

Choose elements $\left(\lambda_{i}\right)_{i}$ such that $\lambda_{i}^{m}=x_{i}$. They are non-zero distinct and satisfy $\lambda_{i}^{m} \lambda_{j}^{-m} \neq t$ for all $i \neq j$. We can form the element $\prod_{s} g_{s} \in G(\widetilde{\alpha})$ with $g_{s}=\operatorname{diag}\left(\lambda_{1}^{m-s}, \ldots, \lambda_{n}^{m-s}\right)$ for $s=0, \ldots, m-1$, and acting
on $p$ in its above form yields

$$
X_{s}=\operatorname{diag}\left(\lambda_{1}, \ldots, \lambda_{n}\right),\left(Z_{s}\right)_{i j}=t_{s} \frac{t f_{i j}}{\lambda_{i}^{m}-t \lambda_{j}^{m}} \lambda_{i}^{m-s-1} \lambda_{j}^{s}, \quad\left(\mathbf{A}^{(m)}\right)_{i \alpha}=\mathbf{a}_{i}^{\alpha},\left(\mathbf{C}^{(m)}\right)_{\alpha j}=\frac{\mathbf{c}_{j}^{\alpha}}{\lambda_{j}^{m}},
$$

for any $s=0, \ldots, m-1$. Hence, the choice of a representative $\left(X_{s}, Z_{s}, \mathbf{A}^{(m)}, \mathbf{C}^{(m)}\right)$ in $\mathcal{C}_{n, \tilde{q}, d}^{\prime}(m)$, such that all the $X_{s}$ are in the same diagonal form and $\sum_{\alpha}\left(\mathbf{A}^{(m)}\right)_{i \alpha}=1$, is unique up to acting by $S_{n} \ltimes \mathbb{Z}_{m}^{n}$. Here, the action of an element $(\sigma, \underline{M}) \in S_{n} \ltimes \mathbb{Z}_{m}^{n}$, is represented by the matrix $g=\prod_{s} g_{\sigma} g_{\underline{M}}^{-s}$, where $g_{\sigma}$ is the permutation matrix corresponding to $\sigma$ while $g_{\underline{M}}=\operatorname{diag}\left(\zeta^{M_{1}}, \ldots, \zeta^{M_{n}}\right)$ for $\underline{M}=\left(M_{1}, \ldots, M_{n}\right)$ and $\zeta$ is a primitive $m$ th root of unity.

In the case $m=2$, write $q_{0}=e^{-2 \gamma_{0}}$ and $q_{1}=e^{-2 \gamma_{1}}$ so that $t=e^{-2 \gamma}$ for $\gamma=\gamma_{0}+\gamma_{1}$. We get

$$
\begin{aligned}
& \left(Z_{0}\right)_{i j}=\frac{e^{-2 \gamma-2 \gamma_{0}}}{2}\left(\frac{1}{\lambda_{i}-e^{-\gamma} \lambda_{j}}+\frac{1}{\lambda_{i}+e^{-\gamma} \lambda_{j}}\right) f_{i j}, \\
& \left(Z_{1}\right)_{i j}=\frac{e^{-3 \gamma}}{2}\left(\frac{1}{\lambda_{i}-e^{-\gamma} \lambda_{j}}-\frac{1}{\lambda_{i}+e^{-\gamma} \lambda_{j}}\right) f_{i j} .
\end{aligned}
$$

We can write down $\operatorname{tr} Z^{2}$ and $\operatorname{tr} Y^{2}$, which are multiples of $G_{1,0}^{2}$ and $H_{1,0}^{2}$, respectively, in $\mathcal{C}_{n, \widetilde{q}, d}^{\prime}(m)$ as

$$
\begin{aligned}
& \operatorname{tr} Z^{2}=\frac{e^{-5 \gamma-2 \gamma_{0}}}{2} \sum_{i, j}\left(\frac{1}{\lambda_{i}-e^{-\gamma} \lambda_{j}}+\frac{1}{\lambda_{i}+e^{-\gamma} \lambda_{j}}\right)\left(\frac{1}{\lambda_{j}-e^{-\gamma} \lambda_{i}}-\frac{1}{\lambda_{j}+e^{-\gamma} \lambda_{i}}\right) f_{i j} f_{j i} \\
& \operatorname{tr} Y^{2}=\operatorname{tr} Z^{2}-\sum_{i} \frac{e^{-2 \gamma-2 \gamma_{0}}+e^{-4 \gamma}}{1-e^{-2 \gamma}} \frac{f_{i i}}{\lambda_{i}^{2}}+\sum_{i} \frac{1}{\lambda_{i}^{2}}
\end{aligned}
$$

Comparing last two expressions with $\operatorname{tr} B^{2}$ and $\operatorname{tr}\left(B-A^{-1}\right)^{2}$ obtained from Section 4 strengthens our claim that the $\left(G_{j, l}^{m}\right)_{j, l}$ correspond to a spin RS system for $W=S_{n} \ltimes \mathbb{Z}_{m}^{n}$ (and $\left(H_{j, l}^{m}\right)_{j, l}$ to a modification of it).

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## Appendix A. Calculations for the spin cyclic quivers

We prove Lemma 3.1 in Section A.1, Lemma 3.2 in Section A.2, Lemma 3.3 in Section A. 3 and Proposition 3.4 in Section A.4. Most computations rely heavily on the properties of a double bracket given in 2.1.

Remark A. 1 Note that the proofs of Lemmas 3.1, 3.2 and Proposition 3.4 also apply for their analogues in the case $m=1$ considered in [34]. We make a comment on the changes that are needed in the latter case at the beginning of each of these proofs. The elements $a_{\alpha}^{\prime}, c_{\alpha}^{\prime}$ are denoted by $a_{\alpha}, b_{\alpha}$ in [34].

## A. 1 Double bracket with spin variables: Proof of Lemma 3.1

We will show that (3.11a) and (3.11c) holds, while we replace (3.11b) by

$$
\begin{align*}
\left\{\left\{a_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\}= & -\frac{1}{2} c_{\beta}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2}\left(o(\alpha, \beta)-\delta_{\alpha \beta}\right) e_{\infty} \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime} \\
& -\delta_{\alpha \beta}\left(e_{\infty} \otimes e_{0} z+\sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes a_{\lambda}^{\prime} c_{\lambda}^{\prime}\right) . \tag{A.1}
\end{align*}
$$

This is nothing else than (3.11b) because the first term vanishes. Indeed, note that $c_{\beta}^{\prime}=e_{\infty} c_{\beta}^{\prime} e_{m-1}$, so that $c_{\beta}^{\prime} \gamma=0$ for any $\gamma$ which is a path beginning by $x, z$ or some $a_{\alpha}^{\prime}=w_{\alpha}$ since then $\gamma=e_{0} \gamma$. However, we will carry on such terms of the form $c_{\beta}^{\prime} \gamma$, because our proof also applies in the case of a Jordan quiver (see [34, Lemma 3.1]) where it does not vanish. Indeed, if we allow the case $m=1$ and set $F_{b}=e_{0} \otimes e_{0}$ for any $b \in \mathbb{Z}$, The double brackets between the elements $x, z, v_{\alpha}, w_{\alpha}$ given in Section 3 exactly match the double brackets in [34, Section 3.1.2].

We prove the results by induction using (3.10). Knowing the double brackets in Section 3, if we want to compute the bracket $\left\{\left\{\Gamma, c_{\beta}^{\prime}\right\}\right\}$ for some $\Gamma \in A$, we first find $\left\{\left\{\Gamma, c_{1}^{\prime}\right\}\right\}=\left\{\left\{\Gamma, v_{1} z\right\}\right.$ and then show our statement by induction using

$$
\begin{equation*}
\left\{\left\{\Gamma, c_{\alpha}^{\prime}\right\}\right\}=\sum_{\lambda=1}^{\alpha-1}\left(v_{\alpha} w_{\lambda}\left\{\left\{\Gamma, c_{\lambda}^{\prime}\right\}\right\}+\left\{\left\{\Gamma, v_{\alpha} w_{\lambda}\right\}\right\} c_{\lambda}^{\prime}\right)+\left\{\left\{\Gamma, v_{\alpha} z\right\}\right\} \tag{A.2}
\end{equation*}
$$

To get (3.11a), we first compute $\left\{\left\{x, c_{\alpha}^{\prime}\right\}\right\}$ and show how to deal with the idempotents. Recalling that $F_{1}=\sum_{s} e_{s} \otimes e_{s-1}$, we get from the double brackets in Section 3

$$
\begin{aligned}
\left\{\left\{x, v_{\alpha} z\right\}\right\}= & \left\{\left\{x, v_{\alpha}\right\}\right\} z+v_{\alpha}\{\{x, z\}\} \\
= & \frac{1}{2}\left(v_{\alpha} x \otimes e_{0} z-v_{\alpha} \otimes x e_{0} z+v_{\alpha} z x F_{1}+v_{\alpha} F_{1} x z-v_{\alpha} x F_{1} z+v_{\alpha} z F_{1} x\right) \\
= & \frac{1}{2}\left(v_{\alpha} x e_{1} \otimes e_{0} z-v_{\alpha} e_{0} \otimes e_{m-1} x z+v_{\alpha} z x e_{0} \otimes e_{m-1}\right. \\
& \left.+v_{\alpha} e_{0} \otimes e_{m-1} x z-v_{\alpha} x e_{1} \otimes e_{0} z+v_{\alpha} z e_{m-1} \otimes e_{m-2} x\right) \\
= & \frac{1}{2}\left(v_{\alpha} z x \otimes e_{m-1}+v_{\alpha} z \otimes x e_{m-1}\right) .
\end{aligned}
$$

In order to simplify the $F_{1}$ to go from the second to the third equality, we used that $v_{\alpha}=v_{\alpha} e_{0}, x \in$ $\oplus_{s \in I} e_{s} A e_{s+1}$ and $z \in \oplus_{s \in I} e_{s+1} A e_{s}$. For example, $v_{\alpha} z x F_{1}=v_{\alpha} z x e_{0} F_{1}=v_{\alpha} z x e_{0} \otimes e_{m-1}$. In particular, if we use $c_{1}^{\prime}=v_{1} z$ we get the expression for $\left\{\left\{x, c_{1}^{\prime}\right\}\right\}$ given in (3.11a) as our basis for the induction.

Meanwhile, we compute

$$
\left\{\left\{x, v_{\alpha} w_{\lambda}\right\}\right\}=v_{\alpha}\left\{\left\{x, w_{\lambda}\right\}\right\}+\left\{\left\{x, v_{\alpha}\right\}\right\} w_{\lambda}=\frac{1}{2}\left(v_{\alpha} \otimes x w_{\lambda}-v_{\alpha} x \otimes w_{\lambda}\right)+\frac{1}{2}\left(v_{\alpha} x \otimes w_{\lambda}-v_{\alpha} \otimes x w_{\lambda}\right)=0,
$$

so that if we assume that the first equality in (3.11a) is true for any $\lambda<\alpha$, we get from (A.2)

$$
\begin{aligned}
\left\{\left\{x, c_{\alpha}^{\prime}\right\}\right\} & =\sum_{\lambda=1}^{\alpha-1}\left(v_{\alpha} w_{\lambda}\left\{\left\{x, c_{\lambda}^{\prime}\right\}\right\}+\left\{\left\{x, v_{\alpha} w_{\lambda}\right\}\right\} c_{\lambda}^{\prime}\right)+\left\{\left\{x, v_{\alpha} z\right\}\right\} \\
& =\sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda}\left(\frac{1}{2} c_{\lambda}^{\prime} x \otimes e_{m-1}+\frac{1}{2} c_{\lambda}^{\prime} \otimes x e_{m-1}\right)+\frac{1}{2}\left(v_{\alpha} z x \otimes e_{m-1}+v_{\alpha} z \otimes x e_{m-1}\right) \\
& =\frac{1}{2}\left(\sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+v_{\alpha} z\right) x \otimes e_{m-1}+\frac{1}{2}\left(\sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+v_{\alpha} z\right) \otimes x e_{m-1},
\end{aligned}
$$

which is exactly the first equality in (3.11a) by using (3.10). For the bracket $\left\{\left\{z, c_{\alpha}^{\prime}\right\}\right\}$, we compute

$$
\begin{aligned}
\left\{\left\{z, v_{\alpha} z\right\}\right\} & =\left\{\left\{z, v_{\alpha}\right\}\right\} z+v_{\alpha}\{\{z, z\}\} \\
& =\frac{1}{2}\left(v_{\alpha} z \otimes e_{0} z-v_{\alpha} \otimes z e_{0} z-v_{\alpha} z^{2} F_{-1}+v_{\alpha} F_{-1} z^{2}\right) \\
& =\frac{1}{2}\left(v_{\alpha} z e_{1} \otimes e_{0} z-v_{\alpha} e_{0} \otimes e_{1} z^{2}-v_{\alpha} z^{2} e_{m-2} \otimes e_{m-1}+v_{\alpha} e_{0} \otimes e_{1} z^{2}\right) \\
& =\frac{1}{2}\left(-v_{\alpha} z^{2} \otimes e_{m-1}+v_{\alpha} z \otimes z e_{m-1}\right),
\end{aligned}
$$

and $\left\{\left\{z, c_{1}^{\prime}\right\}\right\}$ given by the second equality in (3.11a) holds. We can find $\left\{\left\{z, v_{\alpha} w_{\lambda}\right\}\right\}=0$ so that the general case follows by induction, in a way similar to $\left\{\left\{x, c_{\alpha}^{\prime}\right\}\right\}$.

To get (A.1), recall that $a_{\alpha}^{\prime}=w_{\alpha}$ by definition. We first compute

$$
\begin{aligned}
\left\{\left\{v_{\beta} z, a_{\alpha}^{\prime}\right\}\right\}= & v_{\beta} *\left\{\left\{z, a_{\alpha}^{\prime}\right\}\right\}+\left\{\left\{v_{\beta}, a_{\alpha}^{\prime}\right\}\right\} * z \\
= & \frac{1}{2}\left(e_{0} \otimes v_{\beta} z a_{\alpha}^{\prime}-e_{0} z \otimes v_{\beta} a_{\alpha}^{\prime}\right) \\
& +\left[\delta_{\alpha \beta} e_{0} z \otimes e_{\infty}+\frac{1}{2}\left[o(\beta, \alpha)+\delta_{\alpha \beta}\right]\left(e_{0} z \otimes v_{\beta} a_{\alpha}^{\prime}+a_{\alpha}^{\prime} v_{\beta} z \otimes e_{\infty}\right)\right] .
\end{aligned}
$$

Using $\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} z\right\}\right\}=-\left\{\left\{v_{\beta} z, a_{\alpha}^{\prime}\right\}\right\}^{\circ}$, we can write

$$
\begin{aligned}
\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} z\right\}\right\}= & \frac{1}{2}\left(v_{\beta} a_{\alpha}^{\prime} \otimes e_{0} z-v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}\right)-\delta_{\alpha \beta} e_{\infty} \otimes e_{0} z \\
& +\frac{1}{2}\left[o(\alpha, \beta)-\delta_{\alpha \beta}\right]\left(v_{\beta} a_{\alpha}^{\prime} \otimes e_{0} z+e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z\right) \\
= & -\delta_{(\alpha \geqslant \beta)}\left(\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z+\frac{1}{2} v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}+\delta_{\alpha \beta} e_{\infty} \otimes e_{0} z\right) \\
& +\delta_{(\alpha<\beta)}\left(v_{\beta} a_{\alpha}^{\prime} \otimes e_{0} z-\frac{1}{2} v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z\right),
\end{aligned}
$$

recalling that $o(\alpha, \beta)=\delta_{(\alpha<\beta)}-\delta_{(\alpha>\beta)}$. In particular, this yields

$$
\left\{\left\{a_{\alpha}^{\prime}, c_{1}^{\prime}\right\}\right\}=-\frac{1}{2} c_{1}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}-\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} c_{1}^{\prime}-\delta_{\alpha \beta} e_{\infty} \otimes e_{0} z
$$

which is exactly the case $\beta=1$ in (A.1) (and $c_{1}^{\prime} a_{\alpha}^{\prime}=0$ as we mentioned at the beginning of the proof to get in fact (3.11b)). Next, we can compute

$$
\begin{aligned}
\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} w_{\lambda}\right\}\right\}= & v_{\beta}\left\{\left\{a_{\alpha}^{\prime}, w_{\lambda}\right\}\right\}+\left\{\left\{a_{\alpha}^{\prime}, v_{\beta}\right\}\right\} w_{\lambda} \\
= & -\frac{1}{2} o(\alpha, \lambda)\left(v_{\beta} w_{\lambda} \otimes w_{\alpha}+v_{\beta} w_{\alpha} \otimes w_{\lambda}\right) \\
& -\delta_{\alpha \beta} e_{\infty} \otimes w_{\lambda}+\frac{1}{2}\left[o(\alpha, \beta)-\delta_{\alpha \beta}\right]\left(v_{\beta} a_{\alpha}^{\prime} \otimes w_{\lambda}+e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda}\right)
\end{aligned}
$$

and this implies that

$$
\begin{aligned}
\sum_{\lambda=1}^{\beta-1}\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} w_{\lambda}\right\}\right\} c_{\lambda}^{\prime}= & -\frac{1}{2} \sum_{\lambda=1}^{\beta-1} o(\alpha, \lambda)\left(v_{\beta} w_{\lambda} \otimes w_{\alpha} c_{\lambda}^{\prime}+v_{\beta} w_{\alpha} \otimes w_{\lambda} c_{\lambda}^{\prime}\right)-\delta_{\alpha \beta} \sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes w_{\lambda} c_{\lambda}^{\prime} \\
& +\frac{1}{2}\left[o(\alpha, \beta)-\delta_{\alpha \beta}\right] \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} a_{\alpha}^{\prime} \otimes w_{\lambda} c_{\lambda}^{\prime}+e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right) .
\end{aligned}
$$

In the case $\alpha \geqslant \beta$ this gives since $w_{\alpha}=a_{\alpha}^{\prime}$

$$
\sum_{\lambda=1}^{\beta-1}\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} w_{\lambda}\right\}\right\} c_{\lambda}^{\prime} \stackrel{\alpha \geqslant \beta}{=}-\delta_{\alpha \beta} \sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes w_{\lambda} c_{\lambda}^{\prime}+\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} w_{\lambda} \otimes w_{\alpha} c_{\lambda}^{\prime}-e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right)
$$

Otherwise, we just write

$$
\begin{aligned}
\sum_{\lambda=1}^{\beta-1}\left\{\left\{a_{\alpha}^{\prime}, v_{\beta} w_{\lambda}\right\}\right\} c_{\lambda}^{\prime} \stackrel{\alpha<\beta}{=}- & \frac{1}{2}\left(\sum_{\lambda=\alpha+1}^{\beta-1}-\sum_{\lambda=1}^{\alpha-1}\right)\left(v_{\beta} w_{\lambda} \otimes w_{\alpha} c_{\lambda}^{\prime}+v_{\beta} w_{\alpha} \otimes w_{\lambda} c_{\lambda}^{\prime}\right) \\
& +\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} a_{\alpha}^{\prime} \otimes w_{\lambda} c_{\lambda}^{\prime}+e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right)
\end{aligned}
$$

Now, assume by induction that (A.1) holds for any $\lambda<\beta$, which we can write

$$
\begin{aligned}
& \left\{\left\{a_{\alpha}^{\prime}, c_{\lambda}^{\prime}\right\}\right\} \stackrel{\alpha \geqslant \lambda}{=}-\frac{1}{2} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}-\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} c_{\lambda}^{\prime}-\delta_{\alpha \lambda}\left(e_{\infty} \otimes e_{0} z+\sum_{\gamma=1}^{\lambda-1} e_{\infty} \otimes a_{\gamma}^{\prime} c_{\gamma}^{\prime}\right), \\
& \left\{\left\{a_{\alpha}^{\prime}, c_{\lambda}^{\prime}\right\}\right\} \stackrel{\alpha \leq \lambda}{=}-\frac{1}{2} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} c_{\lambda}^{\prime},
\end{aligned}
$$

In the first case, $\alpha \geq \beta$, we find from (A.2) and (3.10)

$$
\begin{aligned}
\left.\left\{\left\{a_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\}\right\}^{\alpha \geqslant \beta}- & \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}-\frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} e_{\infty} \otimes a_{\alpha}^{\prime} c_{\lambda}^{\prime} \\
& -\delta_{\alpha \beta} \sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes w_{\lambda} c_{\lambda}^{\prime}+\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} w_{\lambda} \otimes w_{\alpha} c_{\lambda}^{\prime}-e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right) \\
& -\left(\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z+\frac{1}{2} v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}+\delta_{\alpha \beta} e_{\infty} \otimes e_{0} z\right) \\
= & -\frac{1}{2} c_{\beta}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}-\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime}-\delta_{\alpha \beta} e_{\infty} \otimes\left(\sum_{\lambda=1}^{\beta-1} a_{\lambda}^{\prime} c_{\lambda}^{\prime}+e_{0} z\right)
\end{aligned}
$$

which coincide with (A.1). In the second case, we get

$$
\begin{aligned}
\left\{\left\{a_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} & \stackrel{\alpha<\beta}{=} \sum_{\lambda=1}^{\alpha}\left[-\frac{1}{2} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}-\frac{1}{2} v_{\beta} w_{\lambda} \otimes a_{\alpha}^{\prime} c_{\lambda}^{\prime}\right]-v_{\beta} w_{\alpha} \otimes e_{0} z-\sum_{\gamma=1}^{\alpha-1} v_{\beta} w_{\alpha} \otimes a_{\gamma}^{\prime} c_{\gamma}^{\prime} \\
& +\sum_{\lambda=\alpha+1}^{\beta-1}\left(-\frac{1}{2} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} v_{\beta} w_{\lambda} \otimes a_{\alpha}^{\prime} c_{\lambda}^{\prime}\right) \\
& -\frac{1}{2}\left(\sum_{\lambda=\alpha+1}^{\beta-1}-\sum_{\lambda=1}^{\alpha-1}\right)\left(v_{\beta} w_{\lambda} \otimes w_{\alpha} c_{\lambda}^{\prime}+v_{\beta} w_{\alpha} \otimes w_{\lambda} c_{\lambda}^{\prime}\right) \\
& +\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} a_{\alpha}^{\prime} \otimes w_{\lambda} c_{\lambda}^{\prime}+e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right) \\
& +\left(v_{\beta} a_{\alpha}^{\prime} \otimes e_{0} z-\frac{1}{2} v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z\right)
\end{aligned}
$$

which, after some easy manipulations on the sums, yields

$$
\begin{aligned}
\left\{\left\{a_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha<\beta}{=} & -\frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} \sum_{\lambda=1}^{\beta-1} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} w_{\lambda} c_{\lambda}^{\prime}-\frac{1}{2} v_{\beta} z a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} v_{\beta} z \\
& =-\frac{1}{2} c_{\beta}^{\prime} a_{\alpha}^{\prime} \otimes e_{0}+\frac{1}{2} e_{\infty} \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime}
\end{aligned}
$$

as expected from (A.1) since the first term is zero.
As an intermediate result for (3.11c), we need
Lemma A. 2 For any $\alpha, \beta=1, \ldots, d$,

$$
\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\}=\frac{1}{2} c_{\beta}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) v_{\alpha} \otimes c_{\beta}^{\prime}
$$

Proof. Note that the first term vanishes, but we keep it for the case $m=1$ as explained at the beginning of the proof. We compute

$$
\begin{aligned}
\left\{\left\{v_{\alpha}, v_{\beta} z\right\}\right\} & =\left\{\left\{v_{\alpha}, v_{\beta}\right\}\right\} z+v_{\beta}\left\{\left\{v_{\alpha}, z\right\}\right\} \\
& =-\frac{1}{2} o(\alpha, \beta)\left(v_{\beta} \otimes v_{\alpha} z+v_{\alpha} \otimes v_{\beta} z\right)-\frac{1}{2} v_{\beta} \otimes v_{\alpha} z+\frac{1}{2} v_{\beta} z e_{0} \otimes v_{\alpha}
\end{aligned}
$$

We keep the last vanishing term for computations. In particular, we get

$$
\left\{\left\{v_{\alpha}, c_{1}^{\prime}\right\}\right\} \stackrel{\alpha>1}{=} \frac{1}{2} v_{\alpha} \otimes c_{1}^{\prime}+\frac{1}{2} c_{1}^{\prime} e_{0} \otimes v_{\alpha}, \quad\left\{\left\{v_{1}, c_{1}^{\prime}\right\}\right\}=-\frac{1}{2} v_{1} \otimes c_{1}^{\prime}+\frac{1}{2} c_{1}^{\prime} e_{0} \otimes v_{1},
$$

which agrees with our statement for $\beta=1$. Now, we compute

$$
\begin{aligned}
\left\{\left\{v_{\alpha}, v_{\beta} w_{\lambda}\right\}\right\}= & \left\{\left\{v_{\alpha}, v_{\beta}\right\}\right\} w_{\lambda}+v_{\beta}\left\{\left\{v_{\alpha}, w_{\lambda}\right\}\right\} \\
= & -\frac{1}{2} o(\alpha, \beta)\left(v_{\beta} \otimes v_{\alpha} w_{\lambda}+v_{\alpha} \otimes v_{\beta} w_{\lambda}\right)+\delta_{\alpha \lambda} v_{\beta} \otimes e_{\infty} \\
& +\frac{1}{2}\left[o(\alpha, \lambda)+\delta_{\alpha \lambda}\right]\left(v_{\beta} \otimes v_{\alpha} w_{\lambda}+v_{\beta} w_{\lambda} v_{\alpha} \otimes e_{\infty}\right) .
\end{aligned}
$$

Assume by induction that for all $\lambda<\beta$,

$$
\left\{\left\{v_{\alpha}, c_{\lambda}^{\prime}\right\}\right\}=\frac{1}{2} c_{\lambda}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2}\left(o(\alpha, \lambda)+\delta_{\alpha \lambda}\right) v_{\alpha} \otimes c_{\lambda}^{\prime},
$$

then we get by (A.2)

$$
\begin{aligned}
\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\}= & \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2} o(\alpha, \beta) \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+v_{\alpha} \otimes v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right) \\
& +\delta_{(\alpha<\beta)} v_{\beta} \otimes c_{\alpha}^{\prime}+\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left[o(\alpha, \lambda)+\delta_{\alpha \lambda}\right] v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \\
& -\frac{1}{2} o(\alpha, \beta)\left(v_{\beta} \otimes v_{\alpha} z+v_{\alpha} \otimes v_{\beta} z\right)-\frac{1}{2} v_{\beta} \otimes v_{\alpha} z+\frac{1}{2} v_{\beta} z e_{0} \otimes v_{\alpha}
\end{aligned}
$$

In the case $\alpha>\beta$, we find

$$
\begin{aligned}
\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha>\beta}{=} & \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} e_{0} \otimes v_{\alpha}+\frac{1}{2} v_{\beta} z e_{0} \otimes v_{\alpha}+\frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\alpha} \otimes v_{\beta} w_{\lambda} c_{\lambda}^{\prime}+\frac{1}{2} v_{\alpha} \otimes v_{\beta} z \\
& =\frac{1}{2} c_{\beta}^{\prime} e_{0} \otimes v_{\alpha}+\frac{1}{2} v_{\alpha} \otimes c_{\beta}^{\prime}
\end{aligned}
$$

In the case $\alpha=\beta$, we have

$$
\begin{gathered}
\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha=\beta}{=} \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} e_{0} \otimes v_{\alpha}+\frac{1}{2} v_{\beta} z e_{0} \otimes v_{\alpha}-\frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-\frac{1}{2} v_{\beta} \otimes v_{\alpha} z \\
=\frac{1}{2} c_{\beta}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2} v_{\alpha} \otimes c_{\beta}^{\prime} .
\end{gathered}
$$

Finally, for $\alpha<\beta$ we get

$$
\begin{aligned}
\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha<\beta}{=} & \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2} \sum_{\lambda=1}^{\beta-1}\left(v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+v_{\alpha} \otimes v_{\beta} w_{\lambda} c_{\lambda}^{\prime}\right)+v_{\beta} \otimes c_{\alpha}^{\prime} \\
& +\frac{1}{2}\left[\sum_{\lambda=\alpha}^{\beta-1}-\sum_{\lambda=1}^{\alpha-1}\right] v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-\frac{1}{2}\left(v_{\beta} \otimes v_{\alpha} z+v_{\alpha} \otimes v_{\beta} z\right)-\frac{1}{2} v_{\beta} \otimes v_{\alpha} z+\frac{1}{2} v_{\beta} z e_{0} \otimes v_{\alpha} \\
= & \frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\beta} w_{\lambda} c_{\lambda}^{\prime} \otimes v_{\alpha}+\frac{1}{2} v_{\beta} z \otimes v_{\alpha}-\frac{1}{2} \sum_{\lambda=1}^{\beta-1} v_{\alpha} \otimes v_{\beta} w_{\lambda} c_{\lambda}^{\prime}-\frac{1}{2} v_{\alpha} \otimes v_{\beta} z \\
& +v_{\beta} \otimes c_{\alpha}^{\prime}-\sum_{\lambda=1}^{\alpha-1} v_{\beta} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-v_{\beta} \otimes v_{\alpha} z
\end{aligned}
$$

which is exactly $\frac{1}{2} c_{\beta}^{\prime} e_{0} \otimes v_{\alpha}-\frac{1}{2} v_{\alpha} \otimes c_{\beta}^{\prime}$ since the two last terms can be written as $-v_{\beta} \otimes c_{\alpha}^{\prime}$.

We can finish the proof of Lemma 3.1 by showing (3.11c). It is easier to use the induction in the first variable, that is

$$
\begin{equation*}
\left\{\left\{c_{\alpha}^{\prime}, \Gamma\right\}\right\}=\sum_{\lambda=1}^{\alpha-1}\left(v_{\alpha} w_{\lambda} *\left\{\left\{c_{\lambda}^{\prime}, \Gamma\right\}\right\}+\left\{\left\{v_{\alpha} w_{\lambda}, \Gamma\right\}\right\} * c_{\lambda}^{\prime}\right)+\left\{\left\{v_{\alpha} z, \Gamma\right\}\right\} \tag{A.3}
\end{equation*}
$$

with $\Gamma=c_{\beta}^{\prime}$ in our case. By doing so, we can repeatedly use (3.11a), (A.1) and Lemma A.2. We first get

$$
\begin{aligned}
\left\{\left\{v_{\alpha} z, c_{\beta}^{\prime}\right\}\right\} & =\left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\} * z+v_{\alpha} *\left\{\left\{z, c_{\beta}^{\prime}\right\}\right\} \\
& =\frac{1}{2} c_{\beta}^{\prime} e_{0} z \otimes v_{\alpha}-\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) v_{\alpha} z \otimes c_{\beta}^{\prime}-\frac{1}{2} c_{\beta}^{\prime} z \otimes v_{\alpha} e_{m-1}+\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z \\
& =-\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) v_{\alpha} z \otimes c_{\beta}^{\prime}+\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z
\end{aligned}
$$

using that the first and third terms vanishes (they would cancel out in the Jordan quiver case). This gives in particular $\left\{\left\{c_{1}^{\prime}, c_{\beta}^{\prime}\right\}\right\}=-\frac{1}{2} c_{1}^{\prime} \otimes c_{\beta}^{\prime}+\frac{1}{2} c_{\beta}^{\prime} \otimes c_{1}^{\prime}$. Now using (A.1) as $w_{\lambda}=a_{\lambda}^{\prime}$, we can compute

$$
\begin{aligned}
\left\{\left\{v_{\alpha} w_{\lambda}, c_{\beta}^{\prime}\right\}\right\}= & \left\{\left\{v_{\alpha}, c_{\beta}^{\prime}\right\}\right\} * w_{\lambda}+v_{\alpha} *\left\{\left\{w_{\lambda}, c_{\beta}^{\prime}\right\}\right\} \\
= & \frac{1}{2} c_{\beta}^{\prime} e_{0} w_{\lambda} \otimes v_{\alpha}-\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) v_{\alpha} w_{\lambda} \otimes c_{\beta}^{\prime}-\frac{1}{2} c_{\beta}^{\prime} w_{\lambda} \otimes v_{\alpha} \\
& +\frac{1}{2}\left(o(\lambda, \beta)-\delta_{\lambda \beta}\right) e_{\infty} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}-\delta_{\lambda \beta}\left(e_{\infty} \otimes v_{\alpha} z+\sum_{\gamma=1}^{\beta-1} e_{\infty} \otimes v_{\alpha} w_{\gamma} c_{\gamma}^{\prime}\right) .
\end{aligned}
$$

The first and third terms cancel out, so we can write

$$
\begin{aligned}
\sum_{\lambda=1}^{\alpha-1}\left\{\left\{v_{\alpha} w_{\lambda}, c_{\beta}^{\prime}\right\}\right\} * c_{\lambda}^{\prime}= & -\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) \sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime}+\frac{1}{2} \sum_{\lambda=1}^{\alpha-1}\left(o(\lambda, \beta)-\delta_{\lambda \beta}\right) c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime} \\
& -\delta_{(\beta<\alpha) c_{\beta}^{\prime}} \otimes v_{\alpha} z-\delta_{(\beta<\alpha)} \sum_{\gamma=1}^{\beta-1} c_{\beta}^{\prime} \otimes v_{\alpha} w_{\gamma} c_{\gamma}^{\prime}
\end{aligned}
$$

Now, assume by induction that for all $\lambda<\alpha$,

$$
\left\{\left\{c_{\lambda}^{\prime}, c_{\beta}^{\prime}\right\}\right\}=\frac{1}{2}\left[o(\lambda, \beta)+\delta_{\lambda \beta}\right]\left(c_{\beta}^{\prime} \otimes c_{\lambda}^{\prime}-c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime}\right),
$$

and let us show that this holds for $\lambda=\alpha$. Note that it is exactly (3.11c) since in the case $\lambda=\beta$ the two terms cancel out. We find by (A.3) and our previous computations

$$
\begin{aligned}
\left\{\left\{c_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\}= & \frac{1}{2} \sum_{\lambda=1}^{\alpha-1}\left[o(\lambda, \beta)+\delta_{\lambda \beta}\right]\left(c_{\beta}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}\right) \\
& -\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) \sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime}+\frac{1}{2} \sum_{\lambda=1}^{\alpha-1}\left(o(\lambda, \beta)-\delta_{\lambda \beta}\right) c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime} \\
& -\delta_{(\beta<\alpha)} c_{\beta}^{\prime} \otimes v_{\alpha} z-\delta_{(\beta<\alpha)} \sum_{\gamma=1}^{\beta-1} c_{\beta}^{\prime} \otimes v_{\alpha} w_{\gamma} c_{\gamma}^{\prime}-\frac{1}{2}\left(o(\alpha, \beta)+\delta_{\alpha \beta}\right) v_{\alpha} z \otimes c_{\beta}^{\prime}+\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z
\end{aligned}
$$

If $\alpha>\beta$ we find

$$
\begin{aligned}
\left\{\left\{c_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha>\beta}{=} & \frac{1}{2}\left(\sum_{\lambda=1}^{\beta}-\sum_{\lambda=\beta+1}^{\alpha-1}\right)\left(c_{\beta}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}\right)+\frac{1}{2} \sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime} \\
& +\frac{1}{2}\left(\sum_{\lambda=1}^{\beta-1}-\sum_{\lambda=\beta}^{\alpha-1}\right) c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}-\sum_{\lambda=1}^{\beta-1} c_{\beta}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}+\frac{1}{2} v_{\alpha} z \otimes c_{\beta}^{\prime}-\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z \\
& =-\frac{1}{2} \sum_{\lambda=1}^{\alpha-1} c_{\beta}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z+\frac{1}{2} \sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime}+\frac{1}{2} v_{\alpha} z \otimes c_{\beta}^{\prime},
\end{aligned}
$$

which gives us $-\frac{1}{2}\left(c_{\beta}^{\prime} \otimes c_{\alpha}^{\prime}-c_{\alpha}^{\prime} \otimes c_{\beta}^{\prime}\right)$. In the other cases,

$$
\begin{gathered}
\left\{\left\{c_{\alpha}^{\prime}, c_{\beta}^{\prime}\right\}\right\} \stackrel{\alpha \leqslant \beta}{=} \frac{1}{2} \sum_{\lambda=1}^{\alpha-1}\left(c_{\beta}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\lambda}^{\prime}-c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}\right)-\frac{1}{2} \sum_{\lambda=1}^{\alpha-1} v_{\alpha} w_{\lambda} c_{\lambda}^{\prime} \otimes c_{\beta}^{\prime} \\
\\
+\frac{1}{2} \sum_{\lambda=1}^{\alpha-1} c_{\lambda}^{\prime} \otimes v_{\alpha} w_{\lambda} c_{\beta}^{\prime}-\frac{1}{2} v_{\alpha} z \otimes c_{\beta}^{\prime}+\frac{1}{2} c_{\beta}^{\prime} \otimes v_{\alpha} z
\end{gathered}
$$

and this is trivially $+\frac{1}{2}\left(c_{\beta}^{\prime} \otimes c_{\alpha}^{\prime}-c_{\alpha}^{\prime} \otimes c_{\beta}^{\prime}\right)$.

## A. 2 Proof of Lemma 3.2

This proof can be applied without change in the case $m=1$ treated in [34]. Indeed, we use (A.1) instead of (3.11b) when computing $\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime}, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\}$ below. In that way, all the double brackets that we use during this proof are the ones in [34] if we set $m=1$.

We assume that the integers $k, l \geq 1$ satisfy the conditions for the elements to be non-zero, otherwise the proof is trivial. The first equality is an easy computations, or can be obtained as a consequence of [1, Lemma A.3]. Next, we compute from (3.6a) and (3.11a)

$$
\begin{equation*}
\left\{\left\{x, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\}=\frac{1}{2} e_{0} \otimes x a_{\alpha}^{\prime} c_{\beta}^{\prime}-\frac{1}{2} e_{0} x \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime}+\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x \otimes e_{m-1}+\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} \otimes x e_{m-1} \tag{A.4}
\end{equation*}
$$

Combining this result with (3.5a), $S_{1}:=\left\{\left\{x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}\right\}$ becomes

$$
\begin{gather*}
S_{1}=\sum_{\sigma=1}^{k} x^{\sigma-1} *\left\{\left\{x, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\} x^{l} * x^{k-\sigma}+\sum_{\sigma=1}^{k} \sum_{\tau=1}^{l} x^{\sigma-1} * a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1}\{\{x, x\}\} x^{l-\tau} * x^{k-\sigma} \\
= \\
\frac{1}{2} \sum_{\sigma=1}^{k}\left(e_{0} x^{k-\sigma} \otimes x^{\sigma} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}-e_{0} x^{k-\sigma+1} \otimes x^{\sigma-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right.  \tag{A.5}\\
\left.\quad+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma+1} \otimes x^{\sigma-1} e_{m-1} x^{l}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} \otimes x^{\sigma} e_{m-1} x^{l}\right) \\
+\frac{1}{2} \sum_{\sigma=1}^{k} \sum_{\tau=1}^{l} \sum_{s \in I}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau+1} e_{s} x^{k-\sigma} \otimes x^{\sigma-1} e_{s-1} x^{l-\tau}\right. \\
\left.\quad-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1} e_{s} x^{k-\sigma} \otimes x^{\sigma-1} e_{s-1} x^{l-\tau+2}\right)
\end{gather*}
$$

If we apply the multiplication $m$, we have in the last two terms that the non-vanishing terms are for $s \in I$ such that $e_{m-1} x^{\tau+1} e_{s}=x^{\tau+1}$ and $e_{m-1} x^{\tau-1} e_{s}=x^{\tau-1}$, respectively, and we get that only the third and fourth terms do not cancel out. We find that $\left\{x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}=k a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k} e_{m-1} x^{l}=k a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l}$ since $x^{k} e_{m-1}=e_{m-1} x^{k}$ by assumption on $k$. Next,

$$
\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}\right\}=a_{\gamma}^{\prime} c_{\epsilon}^{\prime} *\left\{\left\{x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\prime}\right\}\right\}+a_{\alpha}^{\prime} c_{\beta}^{\prime}\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime}, x^{\prime}\right\}\right\} * x^{k}+\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime}, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\} x^{l} * x^{k} .
$$

From (A.4) and (A.5), we can get for the first two terms

$$
\begin{aligned}
S_{2}:= & a_{\gamma}^{\prime} c_{\epsilon}^{\prime} *\left\{\left\{x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}\right\}-\sum_{\tau=1}^{l} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1}\left\{\left\{x, a_{\gamma}^{\prime} c_{\epsilon}^{\prime}\right\}\right\}^{\circ} x^{l-\tau} * x^{k} \\
= & \frac{1}{2} \sum_{\sigma=1}^{k}\left(e_{0} x^{k-\sigma} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}-e_{0} x^{k-\sigma+1} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right. \\
& \left.+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma+1} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} e_{m-1} x^{l}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma} e_{m-1} x^{l}\right) \\
+ & \frac{1}{2} \sum_{\sigma=1}^{k} \sum_{\tau=1}^{l} \sum_{s \in I}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau+1} e_{s} x^{k-\sigma} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} e_{s-1} x^{l-\tau}\right. \\
& \left.\quad-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1} e_{s} x^{k-\sigma} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} e_{s-1} x^{l-\tau+2}\right) \\
+ & \frac{1}{2} \sum_{\tau=1}^{l}\left(-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} \otimes e_{0} x^{l-\tau}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} \otimes e_{0} x^{l-\tau+1}\right) \\
+ & +\frac{1}{2} \sum_{\tau=1}^{l}\left(-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1} e_{m-1} x^{k} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau+1}-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} e_{m-1} x^{k} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-t}\right)
\end{aligned}
$$

## Applying the multiplication map and relabelling indices yields

$$
\begin{aligned}
S_{2}= & \frac{1}{2}\left[\sum_{\sigma=1}^{k}-\sum_{\sigma=0}^{k-1}\right] e_{0} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}+\frac{1}{2}\left[\sum_{\sigma=0}^{k-1}+\sum_{\sigma=1}^{k}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma} e_{m-1} x^{l} \\
+ & \frac{1}{2} \sum_{\sigma=1}^{k} \sum_{\tau=1}^{l} \sum_{s \in I}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau+1} e_{s} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} e_{s-1} x^{l-\tau}\right. \\
& \left.-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau-1} e_{s} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma-1} e_{s-1} x^{l-\tau+2}\right) \\
& +\frac{1}{2}\left[-\sum_{\tau=1}^{l}+\sum_{\tau=0}^{l-1}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} e_{0} x^{l-\tau}-\frac{1}{2}\left[\sum_{\tau=0}^{l-1}+\sum_{\tau=1}^{l}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} e_{m-1} x^{k} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-t} .
\end{aligned}
$$

By assumption, $l, k=1$ modulo $m$, so that $e_{s} x^{k}=x^{k} e_{s+1}$ and $e_{s} x^{k}=x^{k} e_{s+1}$ for any $s \in I$. Hence $a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l} e_{0}=a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}$ and $e_{m-1} x^{l} a_{\alpha}^{\prime} c_{\beta}^{\prime}=x^{l} a_{\alpha}^{\prime} c_{\beta}^{\prime}$, so we can drop the idempotents in the first line modulo commutators. Similarly, this can be done in the last line. For the first term in the middle line, $a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau+1} e_{s}$ gives $s=\tau \bmod m$ while $e_{s-1} x^{l-\tau} a_{\alpha}^{\prime} c_{\beta}^{\prime}$ gives $s-1+(1-\tau)=0 \bmod m$, which is the same condition. Thus we can drop the idempotent corresponding to $s=\tau$ modulo commutators. For the second term, we
get $s=\tau-2$ in the same way and we can drop the idempotent. So we can write

$$
\begin{aligned}
S_{2}= & \frac{1}{2}\left[\sum_{\sigma=1}^{k}-\sum_{\sigma=0}^{k-1}\right] x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}+\frac{1}{2}\left[\sum_{\sigma=0}^{k-1}+\sum_{\sigma=1}^{k}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l+\sigma} \\
& +\frac{1}{2} \sum_{\sigma=1}^{k} \sum_{\tau=1}^{l}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma+\tau+1} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau+\sigma-1}-a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma+\tau-1} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau+\sigma+1}\right) \\
& +\frac{1}{2}\left[-\sum_{\tau=1}^{l}+\sum_{\tau=0}^{l-1}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-\tau}-\frac{1}{2}\left[\sum_{\tau=0}^{l-1}+\sum_{\tau=1}^{l}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-t}
\end{aligned}
$$

Note that the middle line can be decomposed as

$$
\frac{1}{2}\left[\sum_{\sigma=0}^{k-1} \sum_{\tau=l}+\sum_{\sigma=0} \sum_{\tau=1}^{l-1}-\sum_{\sigma=1}^{k-1} \sum_{\tau=0}-\sum_{\sigma=k} \sum_{\tau=0}^{l-1}\right] a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma+\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau+\sigma}
$$

We can then rewrite $S_{2}$ as

$$
\begin{aligned}
S_{2}= & \frac{1}{2} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}-\frac{1}{2} x^{k} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}+\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l}+\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l}+\sum_{\sigma=1}^{k-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l+\sigma} \\
& +\frac{1}{2} \sum_{\sigma=0}^{k-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma}+\frac{1}{2} \sum_{\tau=1}^{l-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau} \\
& -\frac{1}{2} \sum_{\sigma=1}^{k-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l+\sigma}-\frac{1}{2} \sum_{\tau=0}^{l-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-\tau} \\
& +\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l}-\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k}-\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l}-\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l} a_{\gamma}^{\prime} c_{\epsilon}^{\prime}-\sum_{\tau=1}^{l-1} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau}
\end{aligned}
$$

We can cancel terms together (some of them modulo commutators) to obtain

$$
\begin{aligned}
S_{2}= & +\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l}-\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l} a_{\gamma}^{\prime} c_{\epsilon}^{\prime}+\frac{1}{2} \sum_{\sigma=1}^{k-1}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l+\sigma}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l-\sigma} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{\sigma}\right) \\
& -\frac{1}{2} \sum_{\tau=1}^{l-1}\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-\tau}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+\tau} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l-\tau}\right) \\
= & \frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l}-\frac{1}{2} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l}+\frac{1}{2}\left[\sum_{v=1}^{k}-\sum_{v=1}^{l}\right]\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-v}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l-v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{v}\right)
\end{aligned}
$$

where we added the terms $v=k, l$ in the sums because they cancel out together. Now, we compute

$$
\begin{aligned}
&\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime}, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\} \\
&=\left\{\left\{a_{\gamma}^{\prime}, a_{\alpha}^{\prime}\right\}\right\} c_{\beta}^{\prime} * c_{\epsilon}^{\prime}+a_{\alpha}^{\prime}\left\{\left\{a_{\gamma}^{\prime}, c_{\beta}^{\prime}\right\}\right\} * c_{\epsilon}^{\prime}+a_{\gamma}^{\prime} *\left\{\left\{c_{\epsilon}^{\prime}, a_{\alpha}^{\prime}\right\}\right\} c_{\beta}^{\prime}+a_{\gamma}^{\prime} * a_{\alpha}^{\prime}\left\{\left\{c_{\epsilon}^{\prime}, c_{\beta}^{\prime}\right\}\right\} \\
&=-\frac{1}{2} o(\gamma, \alpha)\left(a_{\gamma}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\alpha}^{\prime} c_{\beta}^{\prime}+a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}\right)+\frac{1}{2} o(\epsilon, \beta)\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime}-a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}\right) \\
&-\frac{1}{2} a_{\alpha}^{\prime} c_{\beta}^{\prime} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} \otimes e_{0}+\frac{1}{2}\left(o(\gamma, \beta)-\delta_{\gamma \beta}\right) a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}-\delta_{\gamma \beta}\left(a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes e_{0} z+\sum_{\mu=1}^{\beta-1} a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\mu}^{\prime} c_{\mu}^{\prime}\right) \\
&+\frac{1}{2} e_{0} \otimes a_{\gamma}^{\prime} c_{\epsilon}^{\prime} a_{\alpha}^{\prime} c_{\beta}^{\prime}-\frac{1}{2}\left(o(\alpha, \epsilon)-\delta_{\alpha \epsilon}\right) a_{\alpha}^{\prime} c_{\epsilon}^{\prime} \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}+\delta_{\alpha \epsilon}\left(e_{0} z \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}+\sum_{\lambda=1}^{\epsilon-1} a_{\lambda}^{\prime} c_{\lambda}^{\prime} \otimes a_{\gamma}^{\prime} c_{\beta}^{\prime}\right),
\end{aligned}
$$

which we have to multiply on the right by $x^{l}$ (for the outer bimodule structure) and $x^{k}$ (for the inner bimodule structure). After doing so, we apply the multiplication map and denote by $S_{3}$ the expression obtained in that way, i.e. $S_{3}=m \circ\left(\left\{\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime}, a_{\alpha}^{\prime} c_{\beta}^{\prime}\right\}\right\} x^{l} * x^{k}\right)$. We finally get

$$
\begin{aligned}
&\left\{a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k}, a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}\right\}=S_{2}+S_{3} \\
&=+\frac{1}{2}\left[\sum_{v=1}^{k}-\sum_{v=1}^{l}\right]\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k+l-v}+a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k+l-v} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{v}\right) \\
&+\frac{1}{2} o(\alpha, \gamma)\left(a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{l}+a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}\right)+\frac{1}{2} o(\epsilon, \beta)\left(a_{\alpha}^{\prime} c_{\beta}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\epsilon}^{\prime} x^{l}-a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}\right) \\
&-\frac{1}{2}\left(o(\beta, \gamma)+\delta_{\gamma \beta}\right) a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}-\delta_{\gamma \beta}\left(a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} z x^{l}+\sum_{\mu=1}^{\beta-1} a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\mu}^{\prime} c_{\mu}^{\prime} x^{l}\right) \\
&+\frac{1}{2}\left(o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right) a_{\alpha}^{\prime} c_{\epsilon}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}+\delta_{\alpha \epsilon}\left(z x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}+\sum_{\lambda=1}^{\epsilon-1} a_{\lambda}^{\prime} c_{\lambda}^{\prime} x^{k} a_{\gamma}^{\prime} c_{\beta}^{\prime} x^{l}\right)
\end{aligned}
$$

modulo commutators. This is our claim.

## A. 3 Proof of Lemma 3.3

Let's restate the setting. For $u \in\left\{x, y, z, \sum_{s} e_{s}+x y\right\}$, set $\epsilon(x)=+1, \epsilon(y)=-1, \epsilon(z)=-1$ or $\epsilon\left(\sum_{s} e_{s}+x y\right)=+1$. We also set $\theta(u)=\epsilon(u)$ if $u=x, y, z$, while $\theta\left(\sum_{s} e_{s}+x y\right)=0$. With these notations, we have $u \in \oplus_{s} e_{s} A e_{s+\theta(u)}$, and we can write that $\{\{u, u\}\}=\frac{1}{2} \epsilon(u)\left[u^{2} F_{\theta(u)}-F_{\theta(u)} u^{2}\right]$. Moreover, we can also obtain in all cases that

$$
\begin{equation*}
\left\{\left\{u, w_{\alpha}\right\}\right\}=\frac{1}{2} e_{0} \otimes u w_{\alpha}-\frac{1}{2} e_{0} u \otimes w_{\alpha}, \quad\left\{\left\{u, v_{\alpha}\right\}\right\}=\frac{1}{2} v_{\alpha} u \otimes e_{0}-\frac{1}{2} v_{\alpha} \otimes u e_{0} . \tag{A.6}
\end{equation*}
$$

For the first statement, we compute for any $\alpha, \beta=1, \ldots, d$

$$
\left\{\left\{u, w_{\alpha} v_{\beta}\right\}\right\}=\frac{1}{2}\left(w_{\alpha} v_{\beta} u \otimes e_{0}-w_{\alpha} v_{\beta} \otimes u e_{0}+e_{0} \otimes u w_{\alpha} v_{\beta}-e_{0} u \otimes w_{\alpha} v_{\beta}\right),
$$

We find in a similar way to (A.5) in the proof of Lemma 3.2,

$$
\begin{aligned}
\left\{\left\{u^{k}, w_{\alpha} v_{\beta} u^{l}\right\}\right\}= & \frac{1}{2} \sum_{\sigma=1}^{k}\left(e_{0} u^{k-\sigma} \otimes u^{\sigma} w_{\alpha} v_{\beta} u^{l}-e_{0} u^{k-\sigma+1} \otimes u^{\sigma-1} w_{\alpha} v_{\beta} u^{l}\right. \\
& \left.+w_{\alpha} v_{\beta} u^{k-\sigma+1} \otimes u^{\sigma-1} e_{0} u^{l}-w_{\alpha} v_{\beta} u^{k-\sigma} \otimes u^{\sigma} e_{0} u^{l}\right) \\
& +\frac{1}{2} \sum_{\sigma=1}^{k} \sum_{\tau=1}^{l} \sum_{s \in I}\left(w_{\alpha} v_{\beta} u^{\tau+1} e_{s} u^{k-\sigma} \otimes u^{\sigma-1} e_{s-\theta(u)} u^{l-\tau}\right. \\
& \left.-w_{\alpha} v_{\beta} u^{\tau-1} e_{s} u^{k-\sigma} \otimes u^{\sigma-1} e_{s-\theta(u)} u^{l-\tau+2}\right) .
\end{aligned}
$$

We now apply the multiplication map, and we clearly see that the terms in the first two lines cancel out. In the last two lines, we obtain factors $e_{s} u^{k-1} e_{s-\theta(u)}=u^{k-1} e_{s+(k-1) \theta(u)} e_{s-\theta(u)}$ because $u \in \oplus_{s} e_{s} A e_{s+\theta(u)}$. Thus, these two lines clearly disappear if $k$ is not divisible by $m$. Assuming now that $k=0 \bmod m$, we also remark that we have the factor $w_{\alpha} v_{\beta} u^{\tau+1} e_{s}$ in the third line, and since $v_{\beta}=v_{\beta} e_{0}$ this implies that the only $s$ that gives a non-zero term is such that $s-(\tau+1) \theta(u)=0 \bmod m$. The same argument in the last line allows to remove the idempotents and the sum over $s \in I$. Thus, all the terms in those sums are just $w_{\alpha} v_{\beta} u^{\tau+k+l}$, and they cancel out together.

For the second claim, we show more generally that for any fixed $\alpha=1, \ldots, d$, the elements $\left(u^{k}, w_{\alpha} v_{\alpha} u^{l}\right)$ form a commutative Lie subalgebra in $A /[A, A]$. It is just an application of [1, Lemma A.3] to show $\left\{u^{k}, u^{l}\right\}=0$, and we have from the previous part that $\left\{u^{k}, w_{\alpha} v_{\alpha} u^{l}\right\}=0$. Thus, it remains to prove that $\left\{w_{\alpha} v_{\alpha} u^{k}, w_{\alpha} v_{\alpha} u^{l}\right\}=0$ in $A /[A, A]$. On one hand, we get again by adapting the argument in the proof of Lemma 3.2

$$
\begin{aligned}
m \circ & \left(w_{\alpha} v_{\alpha} *\left\{\left\{u^{k}, w_{\alpha} v_{\alpha} u^{l}\right\}\right\}+w_{\alpha} v_{\alpha}\left\{\left\{w_{\alpha} v_{\alpha}, u^{l}\right\}\right\} * u^{k}\right) \\
= & \frac{1}{2}\left[\sum_{\sigma=1}^{k}-\sum_{\sigma=0}^{k-1}\right] u^{k-\sigma} w_{\alpha} v_{\alpha} u^{\sigma} w_{\alpha} v_{\alpha} u^{l}+\frac{1}{2}\left[\sum_{\sigma=0}^{k-1}-\sum_{\sigma=1}^{k}\right] w_{\alpha} v_{\alpha} u^{k-\sigma} w_{\alpha} v_{\alpha} u^{l+\sigma} \\
& +\frac{1}{2}\left[\sum_{\sigma=0}^{k-1} \sum_{\tau=l}+\sum_{\sigma=0} \sum_{\tau=1}^{l-1}-\sum_{\sigma=1}^{k-1} \sum_{\tau=0}-\sum_{\sigma=k}^{l-1} \sum_{\tau=0}^{l-1}\right] w_{\alpha} v_{\alpha} x^{k-\sigma+\tau} w_{\alpha} v_{\alpha} x^{l-\tau+\sigma} \\
& +\frac{1}{2}\left[-\sum_{\tau=1}^{l}+\sum_{\tau=0}^{l-1}\right] w_{\alpha} v_{\alpha} u^{\tau} w_{\alpha} v_{\alpha} u^{k+l-\tau}+\frac{1}{2}\left[-\sum_{\tau=0}^{l-1}+\sum_{\tau=1}^{l}\right] w_{\alpha} v_{\alpha} u^{k+\tau} w_{\alpha} v_{\alpha} u^{l-t},
\end{aligned}
$$

because we can get rid of the idempotents modulo commutators, after careful analysis. After simplification, all terms vanish modulo commutators.

On the other hand, we compute

$$
\left\{\left\{w_{\alpha} v_{\alpha}, w_{\alpha} v_{\alpha}\right\}\right\}=e_{0} \otimes w_{\alpha} v_{\alpha}-w_{\alpha} v_{\alpha} \otimes e_{0}+\frac{1}{2} e_{0} \otimes\left(w_{\alpha} v_{\alpha}\right)^{2}-\frac{1}{2}\left(w_{\alpha} v_{\alpha}\right)^{2} \otimes e_{0} .
$$

Hence $m \circ\left(\left\{\left\{w_{\alpha} v_{\alpha}, w_{\alpha} v_{\alpha}\right\}\right\} x^{l} * x^{k}\right)=0$ modulo commutators and we can conclude.

## A. 4 Proof of Proposition 3.4

This proof can be applied without change in the case $m=1$ treated in [34], after setting $e_{s}=e_{0}$ for each $s \in I$, and $F_{b}=e_{0} \otimes e_{0}$ for all $b \in \mathbb{Z}$.

We begin with the first identity, and let $U_{\alpha}=u(1+\eta \phi)$ instead of $U_{+, \alpha}$ to ease notations. Writing $\left\{\left\{U_{\alpha}, U_{\eta}\right\}\right\}=a^{\prime} \otimes a^{\prime \prime}$, we get

$$
\begin{equation*}
\frac{1}{K L}\left\{U_{\alpha}^{K}, U_{\eta}^{L}\right\}=U_{\eta}^{L-1} a^{\prime} U_{\alpha}^{K-1} a^{\prime \prime} \quad \bmod [A, A], \tag{A.7}
\end{equation*}
$$

So we have to compute

$$
\begin{equation*}
\{\{u+\alpha u \phi, u+\eta u \phi\}\}=\{\{u, u\}\}+\alpha\{\{u \phi, u\}+\eta\{\{u, u \phi\}\}+\alpha \eta\{\{u \phi, u \phi\}\} . \tag{A.8}
\end{equation*}
$$

With the notations of the proof of Lemma 3.3, we find

$$
\{\{u, u\}\}=\frac{1}{2} \epsilon(u)\left[u^{2} F_{\theta(u)}-F_{\theta(u)} u^{2}\right], \quad\{\{\phi, \gamma\}\}=\frac{1}{2} \phi *\left(\gamma F_{0}-F_{0} \gamma\right)+\frac{1}{2}\left(\gamma F_{0}-F_{0} \gamma\right) * \phi,,
$$

where $\gamma$ is any word in the letters $\left\{e_{s}, x_{s}, y_{s}\right\}$ (with possible inverses). The second equation is obtained by combining (2.4) and Lemma 2.5 applied to the subquiver based at $I$, the set of all vertices in the cycle. We see that we can write

$$
\{\{\phi, u\}\}=\frac{1}{2}\left(u F_{0} \phi-F_{0} \phi u\right)+\frac{1}{2}\left(u \phi F_{0}-\phi F_{0} u\right), \quad\{\{\phi, \phi\}\}=\frac{1}{2}\left(\phi^{2} F_{0}-F_{0} \phi^{2}\right),
$$

because $\phi \in \oplus_{s} e_{s} A e_{s}$, so $\phi$ commutes with any $e_{s}$. As $u \in \oplus_{s} e_{s} A e_{s+\theta(u)}$ we have $u e_{s}=e_{s-\theta(u)} u$, so that

$$
\{\{u, \phi\}\}=\frac{1}{2} \phi\left(u F_{\theta(u)}-F_{\theta(u)} u\right)+\frac{1}{2}\left(u F_{\theta(u)}-F_{\theta(u)} u\right) \phi .
$$

From these basic results, we directly get the first term in (A.8). For the second term, we compute

$$
\begin{aligned}
\{\{u \phi, u\}\} & =u *\{\{\phi, u\}\}+\{\{u, u\}\} * \phi \\
& =\frac{1}{2} u *\left(u F_{0} \phi-F_{0} \phi u\right)+\frac{1}{2} u *\left(u \phi F_{0}-\phi F_{0} u\right)+\frac{1}{2} \epsilon(u)\left(u^{2} \phi F_{\theta(u)}-\phi F_{\theta(u)} u^{2}\right) \\
& =\frac{1}{2}\left(u F_{\theta(u)} u \phi-F_{\theta(u)} u \phi u+u \phi F_{\theta(u)} u-\phi F_{\theta(u)} u^{2}\right)+\frac{1}{2} \epsilon(u)\left(u^{2} \phi F_{\theta(u)}-\phi F_{\theta(u)} u^{2}\right)
\end{aligned}
$$

using that $u * F_{0}=F_{\theta(u)} u$ since $u e_{s}=e_{s-\theta(u)} u$. The term $\{\{u, u \phi\}\}=-\{\{u \phi, u\}\}^{\circ}$ follows from the following result.

Lemma A. 3 Fix some $r \in \mathbb{N}$ and let $a \in \oplus_{s} e_{s} A e_{s}, b_{0}, b_{1} \in \oplus_{s} e_{s} A e_{s+r}$ and $c \in \oplus_{s} e_{s} A e_{s+2 r}$. Then $\left(b_{0} F_{r} b_{1}\right)^{\circ}=b_{1} F_{r} b_{0}$ and $\left(c F_{r} a\right)^{\circ}=a F_{r} c$.

Proof. We compute $\left(b_{0} F_{r} b_{1}\right)^{\circ}=\sum_{s} e_{s} b_{1} \otimes b_{0} e_{s+r}=\sum_{s} b_{1} e_{s+r} \otimes e_{s} b_{0}=b_{1} F_{r} b_{0}$. The second equality follows similarly.

Taking $r=\theta(u), b_{0}=u$ and $b_{1}=u \theta$ gives $\left(u F_{\theta(u)} u \phi\right)^{\circ}=u \phi F_{\theta(u)} u$. Using the lemma on the other terms of $\{\{u \phi, u\}\}$ yields

$$
\{\{u, u \phi\}\}=-\frac{1}{2}\left(u \phi F_{\theta(u)} u-u \phi u F_{\theta(u)}+u F_{\theta(u)} u \phi-u^{2} F_{\theta(u)} \phi\right)+\frac{1}{2} \epsilon(u)\left(u^{2} F_{\theta(u)} \phi-F_{\theta(u)} u^{2} \phi\right) .
$$

Computing that

$$
\begin{aligned}
\{\{u \phi, \phi\}\} & =\{\{u, \phi\}\} * \phi+u *\{\{\phi, \phi\}\} \\
& =\frac{1}{2} \phi\left(u F_{\theta(u)}-F_{\theta(u)} u\right) * \phi+\frac{1}{2}\left(u F_{\theta(u)}-F_{\theta(u)} u\right) \phi * \phi+\frac{1}{2} u *\left(\phi^{2} F_{0}-F_{0} \phi^{2}\right) \\
& =\frac{1}{2}\left(\phi u \phi F_{\theta(u)}+u \phi F_{\theta(u)} \phi-\phi F_{\theta(u)} u \phi-F_{\theta(u)} u \phi^{2}\right),
\end{aligned}
$$

we find for the fourth term $\{\{u \phi, u \phi\}\}=u\{\{u \phi, \phi\}\}+\{\{u \phi, u\}\rangle \phi$ that

$$
\{\{u \phi, u \phi\}\}=\frac{1}{2}\left(u \phi u \phi F_{\theta(u)}+u^{2} \phi F_{\theta(u)} \phi-F_{\theta(u)} u \phi u \phi-\phi F_{\theta(u)} u^{2} \phi\right)+\frac{1}{2} \epsilon(u)\left(u^{2} \phi F_{\theta(u)} \phi-\phi F_{\theta(u)} u^{2} \phi\right) .
$$

Remarking that $U_{\alpha}-u=\alpha u \phi$ and $U_{\eta}-u=\eta u \phi$, we find

$$
\begin{aligned}
\alpha \eta\{\{u \phi, u \phi\}\}= & \frac{1}{2} \eta u \phi\left(U_{\alpha}-u\right) F_{\theta(u)}+\frac{1}{2} \eta u\left(U_{\alpha}-u\right) F_{\theta(u)} \phi-\frac{1}{2} \alpha F_{\theta(u)} u \phi\left(U_{\eta}-u\right) \\
& -\frac{1}{2} \alpha \phi F_{\theta(u)} u\left(U_{\eta}-u\right)+\frac{1}{2} \epsilon(u) \eta u\left(U_{\alpha}-u\right) F_{\theta(u)} \phi-\frac{1}{2} \epsilon(u) \alpha \phi F_{\theta(u)} u\left(U_{\eta}-u\right) .
\end{aligned}
$$

Now, we sum all the terms appearing in (A.8), which yields

$$
\begin{aligned}
\left\{\left\{U_{\alpha}, U_{\eta}\right\}\right\}= & \frac{1}{2} \epsilon(u)\left(u^{2} F_{\theta(u)}-F_{\theta(u)} u^{2}\right)+\frac{1}{2} \alpha \epsilon(u) u^{2} \phi F_{\theta(u)}-\frac{1}{2} \eta \epsilon(u) F_{\theta(u)} u^{2} \phi \\
& +\frac{1}{2} \alpha\left(u F_{\theta(u)} u \phi+u \phi F_{\theta(u)} u\right)-\frac{1}{2} \eta\left(u \phi F_{\theta(u)} u+u F_{\theta(u)} u \phi\right) \\
& +\frac{1}{2} \eta u \phi U_{\alpha} F_{\theta(u)}+\frac{1}{2} \eta u U_{\alpha} F_{\theta(u)} \phi-\frac{1}{2} \alpha F_{\theta(u)} u \phi U_{\eta} \\
& -\frac{1}{2} \alpha \phi F_{\theta(u)} u U_{\eta}+\frac{1}{2} \epsilon(u) \eta u U_{\alpha} F_{\theta(u)} \phi-\frac{1}{2} \epsilon(u) \alpha \phi F_{\theta(u)} u U_{\eta} .
\end{aligned}
$$

As $u$ is assumed to be invertible, we can repeat the substitution under the form $u^{-1}\left(U_{\alpha}-u\right)=\alpha \phi$. We find in this way

$$
\begin{aligned}
\left\{\left\{U_{\alpha}, U_{\eta}\right\}\right\}= & \frac{1}{2} \epsilon(u)\left(u^{2} F_{\theta(u)}-F_{\theta(u)} u^{2}\right)+\frac{1}{2} \epsilon(u) u\left(U_{\alpha}-u\right) F_{\theta(u)}-\frac{1}{2} \epsilon(u) F_{\theta(u)} u\left(U_{\eta}-u\right) \\
& +\frac{1}{2}\left(u F_{\theta(u)}\left(U_{\alpha}-u\right)+\left(U_{\alpha}-u\right) F_{\theta(u)} u\right)-\frac{1}{2}\left(\left(U_{\eta}-u\right) F_{\theta(u)} u+u F_{\theta(u)}\left(U_{\eta}-u\right)\right) \\
& +\frac{1}{2}\left(U_{\eta}-u\right) U_{\alpha} F_{\theta(u)}+\frac{1}{2} u U_{\alpha} F_{\theta(u)} u^{-1}\left(U_{\eta}-u\right)-\frac{1}{2} F_{\theta(u)}\left(U_{\alpha}-u\right) U_{\eta} \\
& -\frac{1}{2} u^{-1}\left(U_{\alpha}-u\right) F_{\theta(u)} u U_{\eta}+\frac{1}{2} \epsilon(u) u U_{\alpha} F_{\theta(u)} u^{-1}\left(U_{\eta}-u\right)-\frac{1}{2} \epsilon(u) u^{-1}\left(U_{\alpha}-u\right) F_{\theta(u)} u U_{\eta}
\end{aligned}
$$

This may be reduced to the form

$$
\begin{aligned}
\left\{\left\{U_{\alpha}, U_{\eta}\right\}\right\}= & +\frac{1}{2}(1+\epsilon(u))\left[u U_{\alpha} F_{\theta(u)} u^{-1} U_{\eta}-u^{-1} U_{\alpha} F_{\theta(u)} u U_{\eta}\right] \\
& +\frac{1}{2}\left(u F_{\theta(u)} U_{\alpha}+U_{\alpha} F_{\theta(u)} u\right)-\frac{1}{2}\left(U_{\eta} F_{\theta(u)} u+u F_{\theta(u)} U_{\eta}\right) \\
& -u U_{\alpha} F_{\theta(u)}+F_{\theta(u)} u U_{\eta}+\frac{1}{2}\left(U_{\eta} U_{\alpha} F_{\theta(u)}-F_{\theta(u)} U_{\alpha} U_{\eta}\right)
\end{aligned}
$$

The latter expression can be put back in (A.7), and we get

$$
\begin{align*}
\left\{U_{\alpha}^{K}, U_{\eta}^{L}\right\}= & \frac{1}{2}(1+\epsilon(u))\left[U_{\eta}^{L} u U_{\alpha}^{K} u^{-1}-U_{\eta}^{L} u^{-1} U_{\alpha}^{K} u\right]  \tag{A.9}\\
& +\frac{1}{2}\left(-U_{\eta}^{L-1} u U_{\alpha}^{K}+U_{\eta}^{L-1} U_{\alpha}^{K} u+U_{\eta}^{L} U_{\alpha}^{K-1} u-U_{\eta}^{L} u U_{\alpha}^{K-1}\right)
\end{align*}
$$

all $\bmod [A, A]$. Indeed, since we have the decomposition $U_{\alpha} \in \oplus_{s} e_{s} A e_{s+\theta(u)}$ we can write when we insert the first term of $\left\{\left\{U_{\alpha}, U_{\eta}\right\}\right\}$ in (A.7) that

$$
\begin{aligned}
\sum_{s} U_{\eta}^{L-1} u U_{\alpha} e_{s+\theta(u)} U_{\alpha}^{K-1} e_{s} u^{-1} U_{\eta} & =U_{\eta}^{L-1} u U_{\alpha}\left(\sum_{s} e_{s+\theta(u)} e_{s-(K-1) \theta(u)}\right) U_{\alpha}^{K-1} u^{-1} U_{\eta} \\
& =U_{\eta}^{L-1} u U_{\alpha} U_{\alpha}^{K-1} u^{-1} U_{\eta}
\end{aligned}
$$

for $(K-1) \theta(u) \equiv-\theta(u) \bmod m$, that is $K$ is divisible by $m$ if $\theta(u)= \pm 1$ (for $u=x, y, z$ ), while $K \geq 1$ for $\theta(u)=0$ (for $u=\sum_{s} e_{s}+x y$ ). For every other element, we can proceed in the same way and establish (A.9). By assumption, the first line in (A.9) vanishes for $\epsilon(u)=-1$. The second line is trivially zero if $\alpha=\eta$. Otherwise we use $u=\frac{1}{\alpha-\eta}\left(\alpha U_{\eta}-\eta U_{\alpha}\right)$ and we also get that the second line vanishes.

The same proof works when $\epsilon(z)=+1$ to show that $\left\{U_{-, \alpha}^{K}, U_{-, \eta}^{L}\right\}=0$ modulo commutators for $U_{-, \alpha}=u\left(1+\alpha \phi^{-1}\right)$. We only need to notice that $\left\{\left\{\phi^{-1}, a\right\}\right\}=-\phi^{-1} *\{\{\phi, a\}\} * \phi^{-1}$, so we just need to replace in the expression $\{\{\phi, a\}\}$ the factors $\phi$ by $\phi^{-1}$ and multiply by an overall factor -1 . Thus, reproducing the proof in the first case with some sign changes, we get

$$
\frac{1}{K L}\left\{U_{-, \alpha}^{K}, U_{-, \eta}^{L}\right\}=\frac{1}{2}(-1+\epsilon(u))\left(U_{-, \eta}^{L} u U_{-, \alpha}^{K} u^{-1}-U_{-, \eta}^{L} u^{-1} U_{-, \alpha}^{K} u\right),
$$

modulo commutators. This yields the desired result for $\epsilon(u)=+1$.

## Appendix B. Poisson isomorphism between MQVs

Before proving Proposition 5.3, let's remark that Lemma 3.2 together with (2.13) give

$$
\begin{aligned}
& \left\{\operatorname{tr} X^{k}, \operatorname{tr} X^{l}\right\}_{\mathrm{P}}=0, \quad\left\{\operatorname{tr} X^{k} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{l}\right)\right\}_{\mathrm{P}}=k \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{k+l}\right), \\
& \left\{\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{k}\right), \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{l}\right)\right\}_{\mathrm{P}} \\
& \quad=\frac{1}{2}\left(\sum_{v=1}^{k}-\sum_{v=1}^{l}\right)\left(\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{v} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{k+l-v}\right)+\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{k+l-v} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{v}\right)\right)
\end{aligned}
$$

$$
\begin{align*}
& +\frac{1}{2} o(\alpha, \gamma)\left(\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{l}\right)+\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right)\right) \\
& +\frac{1}{2} o(\epsilon, \beta)\left(\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{l}\right)-\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right)\right) \\
& +\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& -\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& +\delta_{\alpha \epsilon} \operatorname{tr}\left(\left[t^{-1} Z+\sum_{\lambda=1}^{\epsilon-1} \mathbf{A}^{(m)} E_{\lambda \lambda} \mathbf{C}^{(m)}\right] X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& -\delta_{\beta \gamma} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k}\left[t^{-1} Z+\sum_{\mu=1}^{\beta-1} \mathbf{A}^{(m)} E_{\mu \mu} \mathbf{C}^{(m)}\right] X^{l}\right) . \tag{B.1b}
\end{align*}
$$

Note the appearance of two constants $t^{-1}$ in the last two terms. Indeed, we used that $\left(\mathbf{A}^{(m)}\right)_{i \alpha}$ is the $i$ th component of the covector representing $a_{\alpha}^{\prime}$, while $\left(\mathbf{C}^{(m)}\right)_{\beta j}$ is the $j$ th component of the vector representing $t^{-1} c_{\alpha}^{\prime}$, while $X$ and $Z$ respectively represent $x, z$. Furthermore, for the last equality, it is an easy exercise to see that both matrices $Z$ in the right-hand side can be replaced by $Z_{m-1}$ after using that $k, l=1$ modulo $m$ in that expression. The second set of Poisson brackets that we need are given by (4.6a)-(4.6b) for the coordinates defined in (4.5), and we write in our case for $k_{0}, l_{0} \geq 1$

$$
\begin{align*}
& \left\{\operatorname{tr}\left(A^{k_{0}}\right), \operatorname{tr}\left(A^{l_{0}}\right)\right\}_{\mathrm{P}}=0, \quad\left\{\operatorname{tr}\left(A^{k_{0}}\right), \operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{l_{0}}\right)\right\}_{\mathrm{P}}=k_{0} \operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k_{0}+l_{0}}\right)  \tag{B.2a}\\
& \left\{\operatorname{tr}\left(\mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k_{0}}\right), \operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{l_{0}}\right)\right\}_{\mathrm{P}} \\
& = \\
& \quad \frac{1}{2}\left(\sum_{r=1}^{k_{0}}-\sum_{r=1}^{l_{0}}\right)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{r} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k_{0}+l_{0}-r}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k_{0}+l_{0}-r} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{r}\right)\right) \\
& \quad+\frac{1}{2} o(\alpha, \gamma)\left(\operatorname{tr}\left(\mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\alpha \beta} \mathbf{C} A^{l_{0}}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)\right) \\
& \quad+\frac{1}{2} o(\epsilon, \beta)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{l_{0}}\right)-\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)\right) \\
& \quad+\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)-\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right) \\
& \quad+\delta_{\alpha \epsilon} \operatorname{tr}\left(\left[B+\sum_{\lambda=1}^{\epsilon-1} \mathbf{A} E_{\lambda \lambda} \mathbf{C}\right] A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)  \tag{B.2b}\\
& \quad-\delta_{\beta \gamma} \operatorname{tr}\left(\left[B+\sum_{\mu=1}^{\beta-1} \mathbf{A} E_{\mu \mu} \mathbf{C}\right] A^{l_{0}} \mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}}\right) .
\end{align*}
$$

Proof. [Proposition 5.3]. It suffices to show that the map $\psi: \mathcal{C}_{n, t, d}^{\circ} \rightarrow \mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$ is a Poisson map with respect to a basis of functions on $\mathcal{C}_{n, \tilde{q}, d}^{\circ}(m)$. It is not hard to see that we can pick the functions $F_{k}:=\operatorname{tr}\left(X^{k}\right)$ and $G_{l}^{\gamma \epsilon}:=\operatorname{tr}\left(\mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{l}\right)$, which are non-zero for $k=k_{0} m$ and $l=l_{0} m+1$ with $k_{0}, l_{0} \geq 1$. We
always assume such a choice for the indices from now on (which thus depends on the function $F_{k}$ or $\left.G_{l}^{\gamma \epsilon}\right)$. Using the notations from (4.5), we can see that

$$
\begin{equation*}
\psi^{*} F_{k}=m \operatorname{tr}\left(A^{k_{0}}\right)=m f_{k_{0}}, \quad \psi^{*} G_{l}^{\gamma \epsilon}=\operatorname{tr}\left(A^{-1} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{l_{0}+1}\right)=g_{l_{0}}^{\gamma \epsilon} . \tag{B.3}
\end{equation*}
$$

Indeed, we have $\mathbf{C}^{(m)} X^{l}=\mathbf{C}^{(m)} X_{m-1}\left(X_{0} \ldots X_{m-1}\right)^{l_{0}}$ which is $\mathbf{C} A^{l_{0}+1}$ under $\psi^{*}$. Hence, we have to show that the following equalities hold (writing $\{-,-\}_{\mathrm{P}}$ for both Poisson brackets)

$$
\psi^{*}\left\{F_{k}, F_{l}\right\}_{\mathrm{P}}=m^{2}\left\{f_{k_{0}}, f_{l_{0}}\right\}_{\mathrm{P}}, \quad \psi^{*}\left\{F_{k}, G_{l}^{\alpha \beta}\right\}_{\mathrm{P}}=m\left\{f_{k_{0}}, g_{l_{0}}^{\alpha \beta}\right\}_{\mathrm{P}}, \quad \psi^{*}\left\{G_{k}^{\gamma \epsilon}, G_{l}^{\alpha \beta}\right\}_{\mathrm{P}}=\left\{g_{k_{0}}^{\gamma \epsilon}, g_{l_{0}}^{\alpha \beta}\right\}_{\mathrm{P}}
$$

The first equality is obvious as both sides vanish. For the second one,

$$
\begin{equation*}
\psi^{*}\left\{F_{k}, G_{l}^{\alpha \beta}\right\}_{\mathrm{P}}=k \psi^{*} G_{k+l}^{\alpha \beta}=\left(k_{0} m\right) g_{k_{0}+l_{0}}^{\alpha \beta}=m\left\{f_{k_{0}}, g_{l_{0}}^{\alpha \beta}\right\}_{\mathrm{P}}, \tag{B.4}
\end{equation*}
$$

since $k=k_{0} m$ and $l=l_{0} m+1$, so that $k+l=\left(k_{0}+l_{0}\right) m+1$. For the last equality, we have written at the beginning of this appendix that the left-hand side is

$$
\begin{aligned}
& \frac{1}{2}\left(\sum_{v=1}^{k}-\sum_{v=1}^{l}\right)\left(\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{v} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{k+l-v}\right)+\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{k+l-v} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{v}\right)\right) \\
& \quad+\frac{1}{2} o(\alpha, \gamma)\left(\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{l}\right)+\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right)\right) \\
& \quad+\frac{1}{2} o(\epsilon, \beta)\left(\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \beta} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \epsilon} \mathbf{C}^{(m)} X^{l}\right)-\psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right)\right) \\
& \quad+\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] \psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& \quad-\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] \psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& \quad+\delta_{\alpha \epsilon} \psi^{*} \operatorname{tr}\left(\left[t^{-1} Z_{m-1}+\sum_{\lambda=1}^{\epsilon-1} \mathbf{A}^{(m)} E_{\lambda \lambda} \mathbf{C}^{(m)}\right] X^{k} \mathbf{A}^{(m)} E_{\gamma \beta} \mathbf{C}^{(m)} X^{l}\right) \\
& \quad-\delta_{\beta \gamma} \psi^{*} \operatorname{tr}\left(\mathbf{A}^{(m)} E_{\alpha \epsilon} \mathbf{C}^{(m)} X^{k}\left[t^{-1} Z_{m-1}+\sum_{\mu=1}^{\beta-1} \mathbf{A}^{(m)} E_{\mu \mu} \mathbf{C}^{(m)}\right] X^{l}\right)
\end{aligned}
$$

In the first sum, we need $v$ to be congruent to 1 modulo $m$ to have non-zero terms, which means that we can sum over $v=v_{0} m+1$ with $v_{0}=0, \ldots, k_{0}$ or $v_{0}=0, \ldots, l_{0}$. In that case, $\mathbf{C}^{(m)} X^{v}=$ $\mathbf{C}^{(m)} X_{m-1}\left(X_{0} \ldots X_{m-1}\right)^{v_{0}}$, and we can write the same for $v=k$, $l$. Composing with $\psi$, we write this last
expression as

$$
\begin{aligned}
& \frac{1}{2}\left(\sum_{v_{0}=0}^{k_{0}}-\sum_{v_{0}=0}^{l_{0}}\right)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{\nu_{0}} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k_{0}+l_{0}-\nu_{0}}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k_{0}+l_{0}-v_{0}} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{v_{0}}\right)\right) \\
&+\frac{1}{2} o(\alpha, \gamma)\left(\operatorname{tr}\left(\mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\alpha \beta} \mathbf{C} A^{l_{0}}\right)+\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)\right) \\
&+\frac{1}{2} o(\epsilon, \beta)\left(\operatorname{tr}\left(\mathbf{A} E_{\alpha \beta} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \epsilon} \mathbf{C} A^{l_{0}}\right)-\operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)\right) \\
&+\frac{1}{2}\left[o(\epsilon, \alpha)+\delta_{\alpha \epsilon}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right)-\frac{1}{2}\left[o(\beta, \gamma)+\delta_{\beta \gamma}\right] \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}}\right) \\
&+\delta_{\alpha \epsilon} \operatorname{tr}\left(\left[A^{-1} B+\sum_{\lambda=1}^{\epsilon-1} A^{-1} \mathbf{A} E_{\lambda \lambda} \mathbf{C}\right] A^{k_{0}} \mathbf{A} E_{\gamma \beta} \mathbf{C} A^{l_{0}+1}\right) \\
& \quad-\delta_{\beta \gamma} \operatorname{tr}\left(\mathbf{A} E_{\alpha \epsilon} \mathbf{C} A^{k_{0}+1}\left[A^{-1} B+\sum_{\mu=1}^{\beta-1} A^{-1} \mathbf{A} E_{\mu \mu} \mathbf{C}\right] A^{l_{0}}\right),
\end{aligned}
$$

which is precisely $\left\{g_{k_{0}}^{\gamma \epsilon}, g_{l_{0}}^{\alpha \beta}\right\}_{\mathrm{P}}$.

## Appendix C. Calculations for the dynamics

Our method goes as follows: the Hamiltonians come from functions of the form $\operatorname{tr}\left(\mathcal{X}\left(u_{\eta}\right)^{K}\right)$, for some $u_{\eta} \in$ $A$. Then, defining the derivation $d / d t_{K}:=\left\{\operatorname{tr}\left(\mathcal{X}\left(u_{\eta}\right)^{K}\right),-\right\}_{\mathrm{p}}$, the evolution of a matrix $\mathcal{X}(c)$ representing an element $c \in A$ is governed by the ODE

$$
\begin{equation*}
\frac{d \mathcal{X}(c)}{d t_{K}}=\mathcal{X}\left(\left\{u_{\eta}^{K}, c\right\}\right),\left.\quad \mathcal{X}(c)\right|_{t=0}:=C_{0}, \tag{C.1}
\end{equation*}
$$

using 2.14, for some initial condition $C_{0}$. Thus, we are interested in computing the left Loday bracket $\left\{u_{\eta}^{K}, c\right\}=m \circ\left\{\left\{u_{\eta}^{K}, c\right\}\right\}$, which can be found by

$$
\begin{equation*}
\left\{u_{\eta}^{K}, c\right\}=K\left\{\left\{u_{\eta}, c\right\}\right\}^{\prime} u_{\eta}^{K-1}\left\{\left\{u_{\eta}, c\right\}\right\}^{\prime \prime}, \tag{C.2}
\end{equation*}
$$

after using the derivation property in the first variable then multiplying. Hence we need to compute $\left\{\left\{u_{\eta}, c\right\}\right\}$, then substitute the result back into (C.2). Note that from the discussion at the end of Section 2.2, we get for the ideal $J=(\Phi-q)$ that $\left\{u_{\eta}^{K}, J\right\} \subset J$, hence (C.1) defines flows in $\operatorname{Rep}\left(\Lambda^{\tilde{q}}, \widetilde{\alpha}\right)$ that we can project in $\mathcal{C}_{n, \tilde{q}, d}(m)$. The data of (C.2) for a set of generators in $A$ can be seen as an analogue in the quasi-Poisson case to an Hamiltonian $O D E$ on $A$ as defined in [48, Section 2.4] for a double Poisson algebra.

First, we look at the family $\left(G_{k}^{m}\right)_{k}$, which are the symmetric functions of the matrix representing the element $u_{\eta}:=z(1+\eta \phi)$. We need the double brackets

$$
\begin{aligned}
\{\{z, z\}\} & =-\frac{1}{2}\left(z^{2} F_{-1}-F_{-1} z^{2}\right), \quad\{\{z, x\}\}=-\frac{1}{2}\left(x z F_{-1}+F_{-1} z x-z F_{-1} x+x F_{-1} z\right), \\
\left\{\left\{z, w_{\beta}\right\}\right\} & =\frac{1}{2} e_{0} \otimes z w_{\beta}-\frac{1}{2} e_{0} z \otimes w_{\beta}, \quad\left\{\left\{z, v_{\beta}\right\}\right\}=\frac{1}{2} v_{\beta} z \otimes e_{0}-\frac{1}{2} v_{\beta} \otimes z e_{0},
\end{aligned}
$$

obtained from (3.5a)-(3.7) and (A.6), together with

$$
\begin{align*}
\{\{\phi, a\}\} & =\frac{1}{2} \phi *\left(a F_{0}-F_{0} a\right)+\frac{1}{2}\left(a F_{0}-F_{0} a\right) * \phi, \quad \text { for } a \in\{x, z\},  \tag{C.3a}\\
\left\{\left\{\phi, v_{\beta}\right\}\right\} & =\frac{1}{2}\left(v_{\beta} \phi \otimes e_{0}-v_{\beta} \otimes \phi e_{0}\right), \quad\left\{\left\{\phi, w_{\beta}\right\}\right\}=\frac{1}{2}\left(e_{0} \otimes \phi w_{\beta}-e_{0} \phi \otimes w_{\beta}\right) . \tag{C.3b}
\end{align*}
$$

Note that the equations involving $v_{\beta}$ or $w_{\beta}$ need to be computed and do not follow from Lemma 2.5, because such arrows appear from the framing which is not in the initial cyclic quiver for which $\phi$ is a moment map. We do it for the double bracket containing $v_{\beta}$ in (C.3b), and the second case is left as an exercise. Write $\phi=\phi_{+} \phi_{-}^{-1}$ for $\phi_{+}=\sum_{s} e_{s}+x y$, and $\phi_{-}=\sum_{s} e_{s}+y x$, and remark that (A.6) is satisfied for both $u=\phi_{+}, \phi_{-}$. Therefore

$$
\left\{\left\{\phi, v_{\beta}\right\}\right\}=\left\{\left\{\phi_{+}, v_{\beta}\right\}\right\} * \phi_{-}^{-1}-\phi_{+} \phi_{-}^{-1} *\left\{\left\{\phi, v_{\beta}\right\}\right\} * \phi_{-}^{-1}=\frac{1}{2}\left(v_{\beta} \phi_{+} \phi_{-}^{-1} \otimes e_{0}-v_{\beta} \otimes \phi_{+} \phi_{-}^{-1} e_{0}\right),
$$

as desired. Now, we can begin the computations. First,

$$
\begin{aligned}
\left\{\left\{u_{\eta}, x\right\}\right\}= & \{z, x\}\} *(1+\eta \phi)+\eta z *\{\{\phi, x\}\} \\
= & -\frac{1}{2}\left(x z F_{-1}+F_{-1} z x-z F_{-1} x+x F_{-1} z\right) *(1+\eta \phi) \\
& +\frac{1}{2} \eta\left(z \phi *\left(x F_{0}-F_{0} x\right)+z *\left(x F_{0}-F_{0} x\right) * \phi\right) \\
= & -\frac{1}{2}\left(x z(1+\eta \phi) F_{-1}+(1+\eta \phi) F_{-1} z x-z(1+\eta \phi) F_{-1} x+x(1+\eta \phi) F_{-1} z\right) \\
& +\frac{1}{2} \eta\left(\left(x F_{-1} z \phi-F_{-1} z \phi x\right)+\left(x \phi F_{-1} z-\phi F_{-1} z x\right)\right),
\end{aligned}
$$

where we used that $\phi \in \oplus_{s} e_{s} A e_{s}$, while $z \in \oplus_{s} e_{s} A e_{s-1}$. By definition, $u_{\eta}=z(1+\eta \phi)$, so that $u_{\eta}-z=\eta z \phi$. We can also use both expressions after multiplication from the left by $z^{-1}$. Thus

$$
\begin{aligned}
\left\{\left\{u_{\eta}, x\right\}\right\}= & -\frac{1}{2}\left(x u_{\eta} F_{-1}+z^{-1} u_{\eta} F_{-1} z x-u_{\eta} F_{-1} x+x z^{-1} u_{\eta} F_{-1} z\right) \\
& +\frac{1}{2}\left(\left(x F_{-1}\left(u_{\eta}-z\right)-F_{-1}\left(u_{\eta}-z\right) x\right)+\left(x z^{-1}\left(u_{\eta}-z\right) F_{-1} z-z^{-1}\left(u_{\eta}-z\right) F_{-1} z x\right)\right) \\
= & -z^{-1} u_{\eta} F_{-1} z x-x F_{-1} z+F_{-1} z x+\frac{1}{2}\left(x F_{-1} u_{\eta}-x u_{\eta} F_{-1}-F_{-1} u_{\eta} x+u_{\eta} F_{-1} x\right)
\end{aligned}
$$

Remarking that $u_{\eta}^{K-1} \in \oplus_{s} e_{s-1} A e_{s}$ for $K \in m \mathbb{N}$, we find

$$
\frac{1}{K}\left\{u_{\eta}^{K}, x\right\}=-z^{-1} u_{\eta} u_{\eta}^{K-1} z x-x u_{\eta}^{K-1} z+u_{\eta}^{K-1} z x=-\eta \phi u_{\eta}^{K-1} z x-x u_{\eta}^{K-1} z
$$

while this expression vanishes for $K \notin m \mathbb{N}$ since then $e_{s-1} u_{\eta}^{K-1} e_{s}=0$. This is similar in the other cases, hence we restrict to the case $K \in m \mathbb{N}$ from now on. Doing the same computations with $z$, we can find

$$
\begin{aligned}
\left\{\left\{u_{\eta}, z\right\}\right\}= & \{\{z, z\}\} *(1+\eta \phi)+\eta z *\{\{\phi, z\}\} \\
= & -\frac{1}{2}\left(z u_{\eta} F_{-1}-z^{-1} u_{\eta} F_{-1} z^{2}\right)+\frac{1}{2}\left(z F_{-1}\left(u_{\eta}-z\right)-F_{-1}\left(u_{\eta}-z\right) z\right) \\
& +\frac{1}{2}\left(\left(u_{\eta}-z\right) F_{-1} z-\left(z^{-1} u_{\eta}-1\right) F_{-1} z^{2}\right) \\
= & F_{-1} z^{2}-z F_{-1} z+\frac{1}{2}\left(z F_{-1} u_{\eta}-z u_{\eta} F_{-1}+u_{\eta} F_{-1} z-F_{-1} u_{\eta} z\right) .
\end{aligned}
$$

Hence $\frac{1}{K}\left\{u_{\eta}^{K}, z\right\}=-z u_{\eta}^{K-1} z+u_{\eta}^{K-1} z^{2}$. Next, we get

$$
\begin{aligned}
\left\{\left\{u_{\eta}, v_{\beta}\right\}\right\} & =\left\{\left\{z, v_{\beta}\right\}\right\} *(1+\eta \phi)+\eta z *\left\{\left\{\phi, v_{\beta}\right\}\right\} \\
& =\frac{1}{2}\left(v_{\beta} u_{\eta} \otimes e_{0}-v_{\beta} z^{-1} u_{\eta} \otimes z e_{0}+v_{\beta}\left(z^{-1} u_{\eta}-1\right) \otimes z e_{0}-v_{\beta} \otimes\left(u_{\eta}-z\right) e_{0}\right) \\
& =\frac{1}{2}\left(v_{\beta} u_{\eta} \otimes e_{0}-v_{\beta} \otimes u_{\eta} e_{0}\right),
\end{aligned}
$$

which gives $\left\{u_{\eta}^{K}, v_{\beta}\right\}=0$. Similarly, $\left\{u_{\eta}^{K}, w_{\beta}\right\}=0$. Gathering the expressions, we have proved
Lemma C. 1 Write $u_{\eta}=z(1+\eta \phi)$ with $\phi=\left(\sum_{s} e_{s}+x y\right)\left(\sum_{s} e_{s}+y x\right)^{-1}$. The left Loday bracket $\{-,-\}: A \times A \rightarrow A$ satisfies for any $K \in m \mathbb{N}$

$$
\begin{aligned}
\frac{1}{K}\left\{u_{\eta}^{K}, x\right\} & =-\eta \phi u_{\eta}^{K-1} z x-x u_{\eta}^{K-1} z, \quad \frac{1}{K}\left\{u_{\eta}^{K}, z\right\}=-z u_{\eta}^{K-1} z+u_{\eta}^{K-1} z^{2} \\
\frac{1}{K}\left\{u_{\eta}^{K}, v_{\beta}\right\} & =0, \quad \frac{1}{K}\left\{u_{\eta}^{K}, w_{\beta}\right\}=0 .
\end{aligned}
$$

We now adapt the discussion to the family $\left(H_{k}^{m}\right)_{k}$, which are the symmetric functions of the matrix representing the element $\bar{u}_{\eta}=y(1+\eta \phi)$. Note that, by doing so, we assume the invertibility of the element $x$ (which was used to make sense of $z^{-1}$ when deriving the double brackets $\left\{\left\{u_{\eta},-\right\}\right\}$ ), but it can be proved by only inverting $y$ instead. Hence, passing from $u_{\eta}$ to $\bar{u}_{\eta}$, it is not hard to see that the double brackets involving $x$ only differ by an additional term $-F_{-1}$ when replacing $\{\{z, x\}\}$ by $\{\{y, x\}\}$, so that

$$
\begin{align*}
\frac{1}{K}\left\{\bar{u}_{\eta}^{K}, x\right\} & =-(1+\eta \phi) \bar{u}_{\eta}^{K-1}-y^{-1} \bar{u}_{\eta} \bar{u}_{\eta}^{K-1} y x-x \bar{u}_{\eta}^{K-1} y+\bar{u}_{\eta}^{K-1} y x  \tag{C.4}\\
& =-\bar{u}_{\eta}^{K-1}-x \bar{u}_{\eta}^{K-1} y-\eta \phi \bar{u}_{\eta}^{K-1}(1+y x) .
\end{align*}
$$

The double bracket with $y$ instead of $z$ does not change: $\frac{1}{K}\left\{\bar{u}_{\eta}^{K}, y\right\}=-y \bar{u}_{\eta}^{K-1} y+\bar{u}_{\eta}^{K-1} y^{2}$. The same holds for the couple $\left(y, w_{\beta}\right)$ replacing $\left(z, w_{\beta}\right)$, or doing it with $v_{\beta}$, so that $\left\{\bar{u}_{\eta}^{K}, w_{\beta}\right\}=0$ and $\left\{\bar{u}_{\eta}^{K}, v_{\beta}\right\}=0$. Therefore

Lemma C. 2 Write $\bar{u}_{\eta}=y(1+\eta \phi)$ with $\phi=\left(\sum_{s} e_{s}+x y\right)\left(\sum_{s} e_{s}+y x\right)^{-1}$. The left Loday bracket $\{-,-\}: A \times A \rightarrow A$ satisfies for any $K \in m \mathbb{N}$

$$
\begin{aligned}
\frac{1}{K}\left\{\bar{u}_{\eta}^{K}, x\right\} & =-\bar{u}_{\eta}^{K-1}-x u_{\eta}^{K-1} y-\eta \phi u_{\eta}^{K-1}(1+y x), \quad \frac{1}{K}\left\{\bar{u}_{\eta}^{K}, y\right\}=-y u_{\eta}^{K-1} y+u_{\eta}^{K-1} y^{2}, \\
\frac{1}{K}\left\{\bar{u}_{\eta}^{K}, v_{\beta}\right\} & =0, \quad \frac{1}{K}\left\{\bar{u}_{\eta}^{K}, w_{\beta}\right\}=0 .
\end{aligned}
$$

For the family $\left(F_{k}^{m}\right)_{k}$ of symmetric functions of the matrix representing the element $\tilde{u}_{\eta}=\left(\sum_{s} e_{s}+\right.$ $x y)\left(1+\eta \phi^{-1}\right)$, we also do the computations assuming that $x$ is invertible so that $\sum_{s} e_{s}+x y=x z$ and $\tilde{u}_{\eta}=x z(1+\eta \phi)$. As a first intermediate result, note that

$$
\{\{x z, x\}\}=\frac{1}{2} x^{2} z F_{0}-\frac{1}{2} F_{0} x z x-\frac{1}{2} x z F_{0} x-\frac{1}{2} x F_{0} x z .
$$

This directly yields

$$
\begin{aligned}
\left\{\left\{\tilde{u}_{\eta}, x\right\}\right\}= & \{\{x z, x\}\} *\left(1+\eta \phi^{-1}\right)-\eta x z \phi^{-1} *\{\{\phi, x\}\} * \phi^{-1} \\
= & \frac{1}{2}\left(x \tilde{u}_{\eta} F_{0}-(x z)^{-1} \tilde{u}_{\eta} F_{0} x z x-\tilde{u}_{\eta} F_{0} x-x(x z)^{-1} \tilde{u}_{\eta} F_{0} x z\right) \\
& +\frac{1}{2}\left(-x\left[(x z)^{-1} \tilde{u}_{\eta}-1\right] F_{0} x z+\left[(x z)^{-1} \tilde{u}_{\eta}-1\right] F_{0} x z x-x F_{0}\left[\tilde{u}_{\eta}-x z\right]+F_{0}\left[\tilde{u}_{\eta}-x z\right] x\right) .
\end{aligned}
$$

After simplification, we obtain for any $K \in \mathbb{N}$

$$
\frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, x\right\}=-x(x z)^{-1} \tilde{u}_{\eta}^{K} x z-\tilde{u}_{\eta}^{K-1} x z x+x \tilde{u}_{\eta}^{K-1} x z=-\tilde{u}_{\eta}^{K-1} x z x-\eta x \phi^{-1} \tilde{u}_{\eta}^{K-1} x z .
$$

Second, we compute $\left\{\tilde{u}_{\eta}^{K}, x z\right\}$ using

$$
\begin{aligned}
\left\{\left\{\tilde{u}_{\eta}, x z\right\}\right\}= & \{x z, x z\}\}\left(1+\eta \phi^{-1}\right)-\eta x z \phi^{-1} *\{\{\phi, x z\}\} * \phi^{-1} \\
= & \frac{1}{2}\left(x z \tilde{u}_{\eta} F_{0}-(x z)^{-1} \tilde{u}_{\eta} F_{0}(x z)^{2}\right) \\
& +\frac{1}{2}\left(-\left[\tilde{u}_{\eta}-x z\right] F_{0} x z+\left[(x z)^{-1} \tilde{u}_{\eta}-1\right] F_{0}(x z)^{2}-x z F_{0}\left[\tilde{u}_{\eta}-x z\right]+F_{0}\left[\tilde{u}_{\eta}-x z\right] x z\right) .
\end{aligned}
$$

After cancellations, this is just

$$
\frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, x z\right\}=x z \tilde{u}_{\eta}^{K-1} x z-\tilde{u}_{\eta}^{K-1}(x z)^{2} .
$$

Finally, we get $\left\{\left\{\tilde{u}_{\eta}, v_{\beta}\right\}\right\}=\frac{1}{2} v_{\beta} \tilde{u}_{\eta} \otimes e_{0}-\frac{1}{2} v_{\beta} \otimes \tilde{u}_{\eta} e_{0}$, so that $\left\{\tilde{u}_{\eta}^{K}, v_{\beta}\right\}=0$ as before. The same is true for $w_{\beta}$.

Lemma C. 3 Write $\tilde{u}_{\eta}=u(1+\eta \phi)$ with $\phi=\left(\sum_{s} e_{s}+x y\right)\left(\sum_{s} e_{s}+y x\right)^{-1}$ and $u=\sum_{s} e_{s}+x y$. The left Loday bracket $\{-,-\}: A \times A \rightarrow A$ satisfies for any $K \in \mathbb{N}$

$$
\begin{aligned}
\frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, x\right\} & =-\tilde{u}_{\eta}^{K-1} u x-\eta x \phi^{-1} \tilde{u}_{\eta}^{K-1} u, \quad \frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, u\right\}=-\tilde{u}_{\eta}^{K-1} u^{2}+u \tilde{u}_{\eta}^{K-1} u \\
\frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, v_{\beta}\right\} & =0, \quad \frac{1}{K}\left\{\tilde{u}_{\eta}^{K}, w_{\beta}\right\}=0 .
\end{aligned}
$$

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[^1]:    ${ }^{1}$ Note that after this reduction, the spin variables $\left(f_{i j}\right)$ are not attached to a specific particle any more, but they represent collective degrees of freedom.

[^2]:    ${ }^{2}$ Strictly speaking, what we only use to get Theorem 2.3 is the total ordering $<_{s}$ for each $s$ on the arrows $a \in \bar{Q}$ with $t(a)=s$. However, defining an ordering as we do is easier to write the assumption in Proposition 2.4.

[^3]:    ${ }^{3}$ To be precise, we have local coordinates on the connected component of $\mathcal{C}_{n, t, d}^{\circ}$ that contains the subspace $\mathcal{C}_{n, t, d}^{\prime}$ defined below. It is conjectured in [34] that $\mathcal{C}_{n, t, d}^{\circ}$ itself is connected and we work under the latter assumption. If $\mathcal{C}_{n, t, d}^{\circ}$ is not connected, then we get from [34] that the Poisson brackets (4.6a)-(4.6b) determine the Poisson structure only on the connected component of $\mathcal{C}_{n, t, d}^{\circ}$ containing $\mathcal{C}_{n, t, d}^{\prime}$, and Proposition 5.3 only holds between the latter connected component and its image in $\mathcal{C}_{n, \widetilde{q}, d}^{\circ}(m)$.

[^4]:    ${ }^{4}$ The expansion differs from the one in Section 5.2, but each of these two families can be obtained from the other one.

