

Article

An Efficient Energy Management in Office Using Bio-Inspired Energy Optimization Algorithms

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Abstract: Energy is one of the valuable resources in this biosphere. However, with the rapid increase of the population and increasing dependency on the daily use of energy due to smart technologies and the Internet of Things (IoT), the existing resources are becoming scarce. Therefore, to have an optimum usage of the existing energy resources on the consumer side, new techniques and algorithms are being discovered and used in the energy optimization process in the smart grid (SG). In SG, because of the possibility of bi-directional power flow and communication between the utility and consumers, an active and optimized energy scheduling technique is essential, which minimizes the end-user electricity bill, reduces the peak-to-average power ratio (PAR) and reduces the frequency of interruptions. Because of the varying nature of the power consumption patterns of consumers, optimized scheduling of energy consumption is a challenging task. For the maximum benefit of both the utility and consumers, to decide whether to store, buy or sale extra energy, such active environmental features must also be taken into consideration. This paper presents two bio-inspired energy optimization techniques; the grasshopper optimization algorithm (GOA) and bacterial foraging algorithm (BFA), for power scheduling in a single office. It is clear from the simulation results that the consumer electricity bill can be reduced by more than 34.69% and 37.47%, while PAR has a reduction of 56.20% and 20.87% with GOA and BFA scheduling, respectively, as compared to unscheduled energy consumption with the day-ahead pricing (DAP) scheme.

Keywords: appliance scheduling techniques; bacterial foraging algorithm (BFA); energy management system; energy optimization algorithms; grasshopper optimization algorithm (GOA); smart grid

1. Introduction

With the increased use of modern technologies and smart appliances in every field of life, energy consumption is rapidly increasing. The rising electricity demand cannot be fulfilled by the traditional electric power grid. That is why the smart grid is becoming more popular to fulfil daily electricity demand. The smart grid (SG) is supposed to be the incorporation of information technologies (IT) in the existing power grids to increase their robustness and consistency. Smart meters (SM) are used for communication and energy monitoring purposes in SG. To schedule smart appliances in residential, commercial and industrial sectors, an energy management controller (EMC) is installed at the consumer premises. Demand side management (DSM) has many strategies that help to solve the energy optimization problem by peak clipping, load shifting, strategic conservation, flexible load shifting, strategic load growth and valley filling. By using these strategies, the load is shifted from high demand timings to low demand timings [1]. The two main functionalities of DSM are

proper management of the load and demand response (DR) [2]. Consumer load management is also known as DSM. It is the process of shifting electricity demand from high-demand (on-peak) hours to low-demand (off-peak) hours to decrease the energy cost. DR is the consumer's response to variable pricing signals. There are two shapes of DR: in the form of energy price reduction or some incentives to consumers [3,4].

The main objectives of the energy management system (EMS) are the reduction of the energy bill, PAR and consumer discomfort. Many algorithms have been designed to accomplish the aforementioned objectives. For cost and energy consumption minimization, mixed integer linear programming (MILP), mixed integer nonlinear programming (MINLP), non-integer linear programming (NILP) and convex programming were used in [5–8]. However, these techniques are used for fewer appliances and have a large convergence time. In order to overcome these deficiencies, researchers use meta-heuristic techniques to resolve the issue of energy optimization. For cost minimization, the genetic algorithm (GA) was proposed by the authors in [9,10]. For cost minimization and aggregated power consumption, differential evolution (DE) and ant colony optimization (ACO) were used in [11,12].

In this research work, we use GOA and BFA techniques for a single office using the DAP pricing signal. The simulation is performed in MATLAB, and we obtained the results of PAR, cost and average waiting time. The rest of the paper is divided into the following sections: Related work is illustrated in Section 2. Section 3 discusses the problem statement and approach. Section 4 depicts the system model and problem formulation. The proposed schemes are described in Section 5. Simulation results are illustrated in Section 6 to demonstrate some of the achievements. The paper is concluded in Section 7.

2. Related Work

In SG, numerous algorithms have been proposed by researchers, for energy-efficient optimization in residential, commercial and industrial areas, for the benefits of both consumers and the utility. The main targets of researchers have been balancing the load and decreasing electricity cost. Different parameters such as pricing mechanisms, types of appliances and different user demands are considered.

Hybrid bacterial foraging and genetic (HBG) algorithm-based DSM for smart homes was proposed by the authors in [13]. They focused on peak load reduction, cost minimization, user comfort maximization and load shifting. Through HBG cost, PAR and waiting time were reduced compared to GA and BFA. A smart community-based energy optimization technique was discussed in [14]. The authors focused on the end-user's high comfort level and less energy usage with integration of renewable energy sources using particle swarm optimization (PSO). A time-constrained nature-inspired algorithm-based home energy management (HEM) system was proposed by the authors in [15]. GA, moth-flame optimization algorithm (MFO) and their hybridization were proposed for energy bill reduction and achieving end-users' high comfort level. A HEM system using cuckoo search was proposed in [16]. The performance of GA and the cuckoo search algorithm was compared with respect to the reduction of energy cost, PAR and user discomfort by using the DAP signal. Cuckoo search incorporation with levy flights of some kind of birds and fruit-flies were considered for the breeding strategy in [17]. In many optimization problems, because of its generic and robust nature, the cuckoo search is superior to GA and PSO. The authors used GA, TLBO (teacher learning-based algorithm), LP (linear programming) and TLGO (teacher learning genetic optimization) algorithms for appliances scheduling in [18]. They categorized flexible appliances as "time flexible" and "power flexible" for proficient energy consumption of consumers in SG. This approach enables energy consumers to schedule their appliances to get optimized energy consumption. This approach also maximizes the comfort level of customers with restricted total energy consumption. In [19], the authors discussed optimal operation methods for a micro-grid. They used the improved adaptive evolutionary algorithm and swarm optimization algorithm. In [20], the authors presented an optimal scheduling scheme for residential appliances, using the DAP signal in smart homes. This algorithm reduced peak cost to 22.6% and normal price to 11.7%. This approach does not rely on the energy optimization approach. In [21], the authors discussed load shifting, cost minimization and the energy storage system

(ESS). They proposed a system that enables the user to buy energy during low demand timings and sale their stored energy to the utility during on-peak hours.

In [22], the gradient-based particle swarm optimization (GPSO) technique for demand response (DR) in smart homes, considering the load and energy price uncertainties, was discussed. Having an optimal scheduling of power, the heuristic-based genetic algorithm (GA) was used for demand response (DR) in HEM systems in [23]. In this paper, the authors used GA, TLBO (teaching learning-based optimization), EDE (enhanced differential evolution) and proposed EDTLA (enhanced differential teaching learning algorithm) for minimization of the residential total energy cost and end-user discomfort level. The authors in [24] discussed the cooperative multi-swarm particle swarm optimization (PSO) technique for achieving their goals of cost minimization; however, they did not consider PAR. In [25], the authors used GA with the DAP scheme for optimally scheduling the load demand. In [26], the authors introduced a load balancing mechanism in commercial, residential and industrial areas. They compared the usage of electricity with GA and without GA in DSM. By using GA-based DSM, they reduced the electricity usage during peak hours. However, PAR and end-user discomfort were not discussed. In [27], the authors used PSO for scheduling of smart electric appliances for electricity cost minimization. They took different cases of changing the renewable energy consumption rate and user comfort level and applied it in a smart community as a case study. The aforementioned optimization techniques achieved the energy cost minimization and PAR reduction by losing the end-user comfort. Therefore, in this work, we have explored and analyzed two bio-inspired algorithms for the energy optimization problem in the residential sector: GOA and BFA. This is because the algorithms were developed based on the perfect optimization behavior of naturally-available organisms. Through simulations, we have shown that using bio-inspired optimization algorithms, the energy cost and PAR can be reduced compared to the unscheduled load.

3. Problem Statement and Approach

Traditional electric power grids are unable to fulfill today's electricity demand. This deficiency has raised the demand for an energy management system. Through different techniques and algorithms, we can solve the energy optimization problem. Researchers have applied different bio-inspired algorithms, however, they have not considered the end-user comfort by reducing their waiting time along with the reduction of energy cost and PAR. Therefore, in this work, we use the GOA and BFA techniques for the office energy management system (OEMS), using DAP. Eight appliances have been considered, named automatically operating appliances (AOAs). We have divided 12-h office-timings into 60 time slots of 12 min in duration. The simulation results show that by using GOA and BFA in OEMS, we can reduce the total cost to 34.69% and 37.47% and PAR to 56.20% and 20.87%, respectively.

4. System Model and Problem Formulation

4.1. Model Architecture

The efficient utilization of the existing energy resources is necessary in our daily life. The proposed system model architecture is depicted in Figure 1. It consists of a smart meter (SM), the energy management controller (EMC), automatically-operated appliances (AOAs) and advance distribution and communication systems. EMC receives the required energy consumption outline from all connected appliances, which schedule the energy consumption pattern according to the pricing signal. The utility sends the pricing signal to the smart meter, which is then forwarded to the EMC. At the same time, the SM receives the consumed electricity reading from EMC and transmits it to the utility. Through a wireless communication network, i.e., Wi-MAX, ZigBee, Bluetooth, WiFi, GSM or GPRS or using PLC (power line communication), the utility and SM communicate with each other. In this work, we considered only a single office with eight appliances. In our case, the decision would be made after every 12 min, not 1 h, because we have divided 24 h into 120 time slots, each equal to

12 min. Here, we considered 120/2 slots for offices because offices only consume energy during the daytime, which is denoted by symbol s .

$$s \in S = \{1, 2, 3 \dots 60\} \tag{1}$$

The scheduled vector of office energy consumption (OEC) for a single appliance is:

$$OEC_{ac}^s = \{OEC_{ac}^1, OEC_{ac}^2, OEC_{ac}^3 \dots OEC_{ac}^{60}\} \tag{2}$$

Total energy consumption OEC_T is calculated as:

$$OEC_T = \sum_{s=1}^{60} \left(\sum_{i=1}^{12} OEC_i^s \right) \tag{3}$$

Table 1 gives the specifications of different appliances in an office.

Table 1. Specifications of office automatically operating appliances (AOAs).

S. No.	AOAs	LOT	Power Rating (kW)	OTIs
1	Air conditioner	30	4.00	1–60
2	Computer	40	0.25	5–55
3	Electric kettle	2	3.00	1–55
4	Coffee maker	3	2.00	10–45
5	Water dispenser	45	2.5	1–60
6	Oven	5	5.00	10–50
7	Fan	25	3.5	1–60
8	Light	35	2	1–60

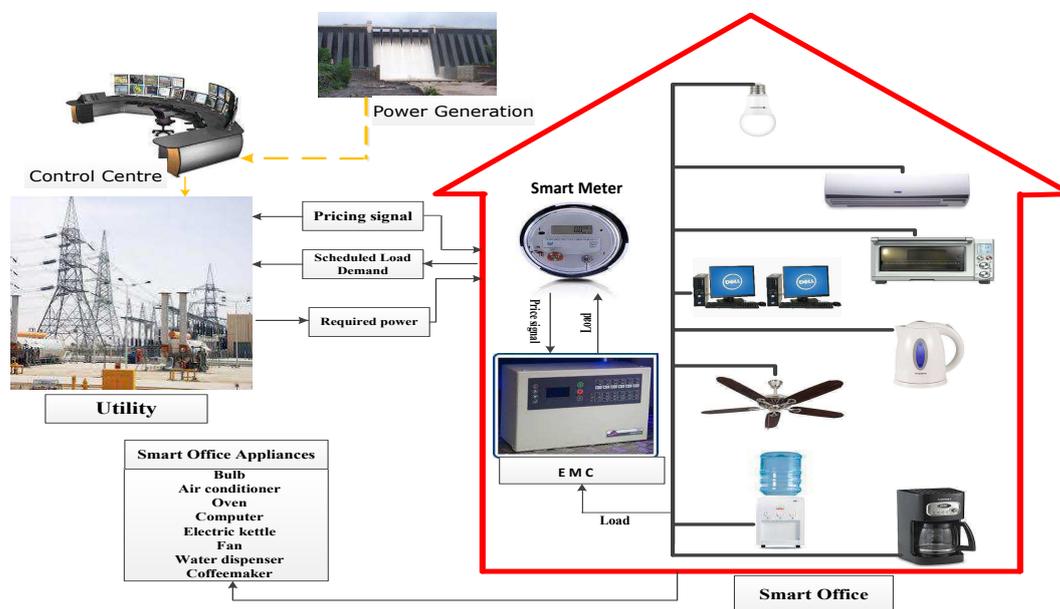


Figure 1. The proposed system model architecture.

4.2. Problem Formulation

In the proposed work, we formulate our problems of: (a) end-user high comfort level, (b) consumers' electricity bill minimization and (c) minimization of PAR by optimization of the energy consumption profiles of office appliances, using the multiple knapsack problem (MKP) scheduling

technique. MKP is a capacity (resources) allotment problem. It consists of N number of capacities and Q number of objects [28].

MKP is a combinatorial problem. In MKP, the stuff quantity, having different weights and values, can be kept into a knapsack of a certain capacity, such that the worth of the knapsack should be maximum, as shown in Figure 2.

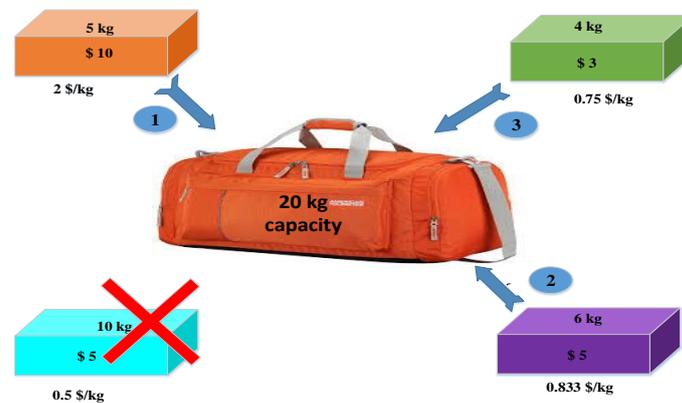


Figure 2. The multiple knapsack problem (MKP) formulation.

We consider U number of knapsacks and use MKP as the scheduling mechanism to map our problem as follows:

- Power capacities of consumers in every time interval are mapped as U number of knapsacks;
- Appliances in an office are mapped as “Q” number of objects;
- The weight of every object in MKP is mapped as appliances’ consumed energy in every time interval. This is assumed to be time invariant;
- In MKP, the worth of each object in a particular time interval is mapped as the cost of appliances’ consumed energy in that interval of time [29].

If OEC_T is the maximum energy capacity in every time slot, then the end-user electricity cost along with PAR can be minimized, keeping aggregated energy consumption of the cumulative office appliances within the maximum threshold limit of C_T .

Mathematically, this constraint can be shown as follows:

$$OEC_T \leq OEC_{max} \quad (4)$$

Here, OEC_T is the cumulative energy demand of the end-user and OEC_{max} is the maximum energy capacity in a particular interval of time available from the utility grid. MKP scheduling tells us to keep the total energy demand of the end-user less than or equal to this maximum energy capacity threshold.

4.3. The Electricity Cost

In order to calculate total energy cost, we use the following equation:

$$C = \sum_{h=1}^{60} (E_{rate} \times P_{rate}) \quad (5)$$

C is the total cost in 60 time slots; E_{rate} is the energy cost per hour; P_{rate} is the connected appliances’ power rating.

4.4. The Power Consumption

The power consumption of each appliance is calculated by the following equation:

$$Load = \sum_{h=1}^{60} P_{rate} \times X \quad (6)$$

P_{rate} is the power rating, and X is the ON/OFF status of an appliance.

4.5. PAR

For RAR, the following equation is used.

$$PAR = \frac{\max(load)}{\text{Avg}(load)} \quad (7)$$

4.6. Waiting Time

This is that time interval when a consumer wants to switch-ON an appliance. However, due to the scheduling of appliances, the consumer has to wait for a certain amount of time. Figure 3 shows that α is the appliance starting time, but actually, the appliance will start its operation at η . mathematically, the waiting time is given as:

$$\tau_w = \eta - \alpha \quad (8)$$

The normalized waiting time is given by:

$$\tau_w = \frac{\eta - \alpha}{(\beta - LOT) - \alpha} \quad (9)$$

where $(\beta - LOT)$ is the last starting time of an appliance, so that it will complete its operation.

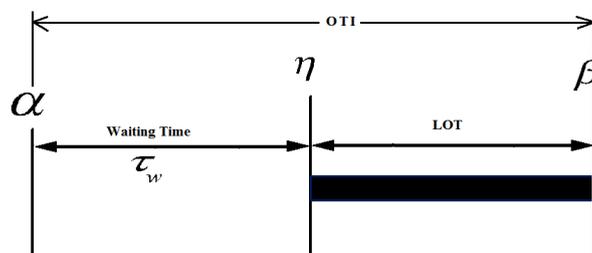


Figure 3. Appliances starting time, operation ending time and waiting time.

4.7. Objective Function

Our objective function can mathematically be expressed as follows:

$$\min \left(\sum_{m=1}^{60} [\omega_1 \times \sum_{n=1}^N (OEC_{T,n} \times E_{rate}) + (\omega_2 \times \tau_w)] \right) \quad (10)$$

where E_{rate} is the energy cost in every interval of time. The aim of our objective function is to minimize electricity cost, while keeping a higher consumer comfort level by the reduction of waiting time. ω_1 and ω_2 are weighting factors of the two portions of our objective function. Their values can be either "0" or "1", so that $(\omega_1 + \omega_2) = 1$ [9]. This reveals that either ω_1 or ω_2 could be zero or one. This means that, if a consumer does not want to schedule his/her appliances, then these weighting factors will be $\omega_1 = 1$ and $\omega_2 = 0$ in the objective function.

5. Scheduling Algorithms

To solve the appliances optimal scheduling problem, in order to achieve the lowest energy cost, lower PAR and less user discomfort, different scheduling algorithms have been proposed in the literature. In this paper, we have proposed GOA and BFA. A brief description of both of these algorithms is given below.

5.1. Grasshopper Optimization Algorithm

A grasshopper is a kind of destructive insect, which is known as a pest because it damages crops. There are eleven thousand species of grasshopper [30]. It is generally considered as a flying animal. As a grasshopper reaches its adult stage, it passes through the stages of eggs, nymph and adult, as shown in the Figure 4.

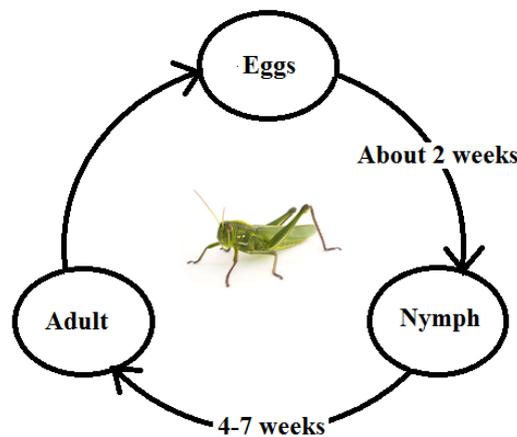


Figure 4. The lifecycle of a grasshopper.

Usually, grasshoppers can be seen in the form of a swarm in nature. They attack agricultural lands and become a nightmare for farmers. The swarming behaviour is found in both adult and nymph grasshoppers [31,32]. Generally, a locust swarm contains five billion of grasshoppers and spread over an area of 60 square miles. Nature-inspired algorithms have a unique search mechanism for food. This consists of two techniques: exploration and exploitation.

(a) Exploration: The process in which the algorithm finds a new solution from the current solutions in the search space.

(b) Exploitation: The process in which algorithm searches the surrounding search space.

The mathematical model of GOA, which carries the swarming behaviour of a grasshopper, is given as in [33].

$$P_i = S_i + V_i + A_i \tag{11}$$

In the above equation, P_i shows the i^{th} position of a grasshopper, S_i gives the social collaboration, V_i gives the gravitational force over a grasshopper and A_i is the air-advection. To produce randomness in the above equation, it becomes:

$$P_i = (x_1 \times S_i) + (x_2 \times V_i) + (x_3 \times A_i) \tag{12}$$

where x_1, x_2 and x_3 are random numbers between zero and one. S_i is modelled as:

$$S_i = \sum_{j=1}^N s(d_{ij}) \hat{d}_{ij} \dots \dots \dots j \neq i \tag{13}$$

where N is the number of search agents, s defines the social interaction between two grasshoppers i and j , d_{ij} is the respective distance between i^{th} and j^{th} grasshoppers and is given by:

$$d_{ij} = |P_j - P_i| \quad (14)$$

and:

$$\hat{d}_{ij} = \frac{(P_j - P_i)}{d_{ij}} \quad (15)$$

is the unit vector from the i^{th} grasshopper to the j^{th} grasshopper. Mathematically, the social force is given as follows:

$$s(d) = Fe^{\frac{-d}{l}} - e^{-r} \quad (16)$$

where F is the attractive force, d shows the distance and l is the measure of attraction.

The V component in Equation (1) is given as:

$$V_i = -v\hat{e}_v \quad (17)$$

where v is the gravitational force, and the negative sign shows its direction towards the centre of the Earth, while \hat{e}_v is the unit vector in the direction of the Earth.

Now, the A component in Equation (1) is given as:

$$A_i = v\hat{e}_w \quad (18)$$

where v is the constant drift when there is a wind and \hat{e}_w shows the wind directional unit vector. By putting the values of S , G and A in Equation (1), we get:

$$S_i = \sum_{i=1}^N s(|P_j - P_i|) \frac{(P_j - P_i)}{d_{ij}} - g\hat{e}_g + v\hat{e}_w \quad (19)$$

We utilize the above equation for the swarm in free space and use it in simulation to describe the interaction between the grasshoppers in a swarm. The steps involved in the GOA algorithm are given in Algorithm 1 and are depicted in Figure 5.

Algorithm 1: GOA algorithm.

- 1 **Initialization:** Generation of price signal according to the scheme used
 - 2 LOTs' specification of appliances
 - 3 power ratings of appliances
 - 4 **Input:** variables u_b, l_b, dim, N
 - 5 Initialize position of grasshopper
 - 6 **for** $h = 1$ to H **do**
 - 7 Find electricity cost
 - 8 Find cost of all appliances' LOTs
 - 9 Find F_{best}, L_{best} and G_{best}
 - 10 **for** $It = 1$ to It_{Max} **do**
 - 11 **for** $i = 1$ to N_{VAR} **do**
 - 12 **end**
 - 13 Find the best position
 - 14 **end**
 - 15 Update the LOTs of appliances
 - 16 **end**
 - 17 **Output:** $OEC_T, load, PAR$.
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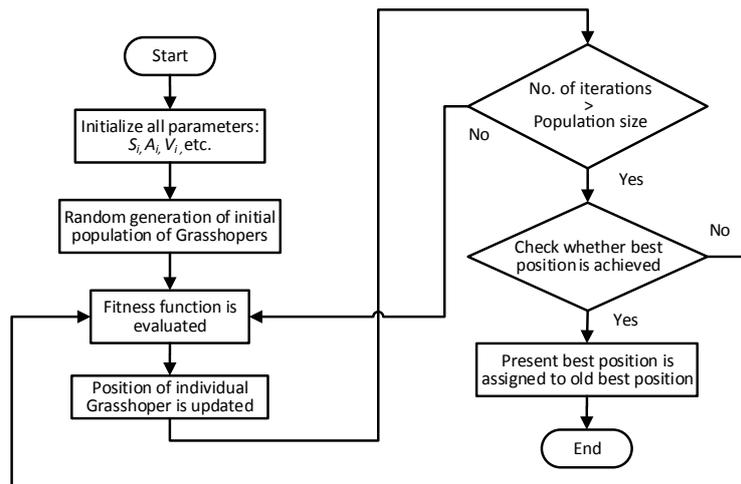


Figure 5. Flowchart of grasshopper optimization algorithm (GOA).

5.2. Bacterial Foraging Algorithm

BFA was proposed by Kevin Passino in 2002 [34]. In this algorithm, the group foraging strategy of a swarm of *Escherichia coli* (*E. coli*) bacteria is the key point. Bacteria forage for food and nutrients, to maximize their energy per unit time. By sending a signal, bacteria also communicate with each other. Because of predators, the prey may be mobile. Therefore, it is chased by the bacterium in an optimal way. When a bacterium maximizes its energy by getting sufficient food, then it does other activities like sheltering, mating, fighting, etc.

The following steps are needed in order to explain BFA.

- (a) Chemotaxis
- (b) Swarming
- (c) Reproduction
- (d) Elimination

5.2.1. Chemotaxis

In the chemotaxis step, the *E. coli* move from one place to another through flagella. According to the biological point of view, its motion is observed in two different ways: it may either swim or tumble.

To consider the chemotaxis movement of bacteria, we have the following equation:

$$\delta^j(i+1, k, l) = \delta^j(i, k, l) + Q(j) \frac{\Delta(j)}{\sqrt{\Delta^T(j)\Delta(j)}} \quad (20)$$

In the above equation, $\delta^j(i, k, l)$ shows the position of the j^{th} bacterium at the i^{th} chemotactic, the k^{th} reproductive and the l^{th} elimination-dispersal step. $Q(i)$ represents the size of the step taken by the bacterium in a random direction when it tumbles. Δ shows the vector in random direction $[-1, 1]$.

5.2.2. Swarming

The *E. coli* bacterium is blessed with swarming behaviour. In this step, bacteria cells form a ring-shaped structure and move in search of nutrients. A high level of succinate usage stimulates the cells, due to which attractant-aspartate is released by the cells, which helps them to bind in groups.

5.2.3. Reproduction

When a bacterium is in a feasible and nutritious environment, it reproduces, splits into two bacteria and keeps the number of cells in a swarm fixed.

5.2.4. Elimination and Dispersal

The scarcity of nutrients kills the bacterium or disperses them into another environment. They are also killed due to high temperature. If there is a poor condition in the environment, the bacteria may place themselves near a good food source, hence assisting chemotaxis.

To calculate the fitness of each bacterium, the following equation can be used:

$$F_j[i, k, l] = F_j[i, k, l] + F_{cc}(\delta_j[i, k, l], P[i, k, l]) \quad (21)$$

In the above equation, F_j shows the fitness of the bacterium and δ_j is the position of the bacterium.

$$F_{cc} = \sum_{d=1}^{d-1} (100 \times (\delta(j, d+1) - (\delta(j, d))^2)^2 + (\delta(j, d) - 1)^2) \quad (22)$$

In order to achieve the time-varying objective, we must put the objective function J_{cc} into the actual objective function F_j . The steps involved in the BFA algorithm are given in Algorithm 2 and are depicted in Figure 6.

Algorithm 2: Bacterial foraging algorithm.

- 1 **Initialization:** Generation of the price signal according to the scheme used, LOTs' specification of appliances, power ratings of appliances
 - 2 **Input:** Give initial values to variables; $pop, N_p, N_e, N_c, N_r, N_s, D, C$.
 - 3 Evaluate fitness for each bacterium (J_{last}).
 - 4 **for** $l = 1$ to N_e **do**
 - 5 **for** $k = 1$ to N_r **do**
 - 6 **for** $j = 1$ to N_c **do**
 - 7 **for** $i = 1$ to N_p **do**
 - 8 Find new position of the bacterium
 - 9 Find the fitness
 - 10 **for** $s = 1$ to N_s **do**
 - 11 **end**
 - 12 **if** $J_i < J_{last}$ **then**
 - 13 Replace the previous position of the bacterium with the new position
 - 14 Go back to line 10
 - 15 **else**
 - 16 Assign a random direction
 - 17 Evaluate the fitness
 - 18 Go back to line no. 10
 - 19 **end**
 - 20 **end**
 - 21 **end**
 - 22 Evaluate the fitness of the bacterium
 - 23 Select the best one Random elimination and dispersal
 - 24 **end**
 - 25 **if** $1 < N_e$ **then**
 - 26 **else**
 - 27 Go back to the initial elimination step
 - 28 **end**
 - 29 **end**
 - 30 **Output:** $OEC_T, load, PAR$.
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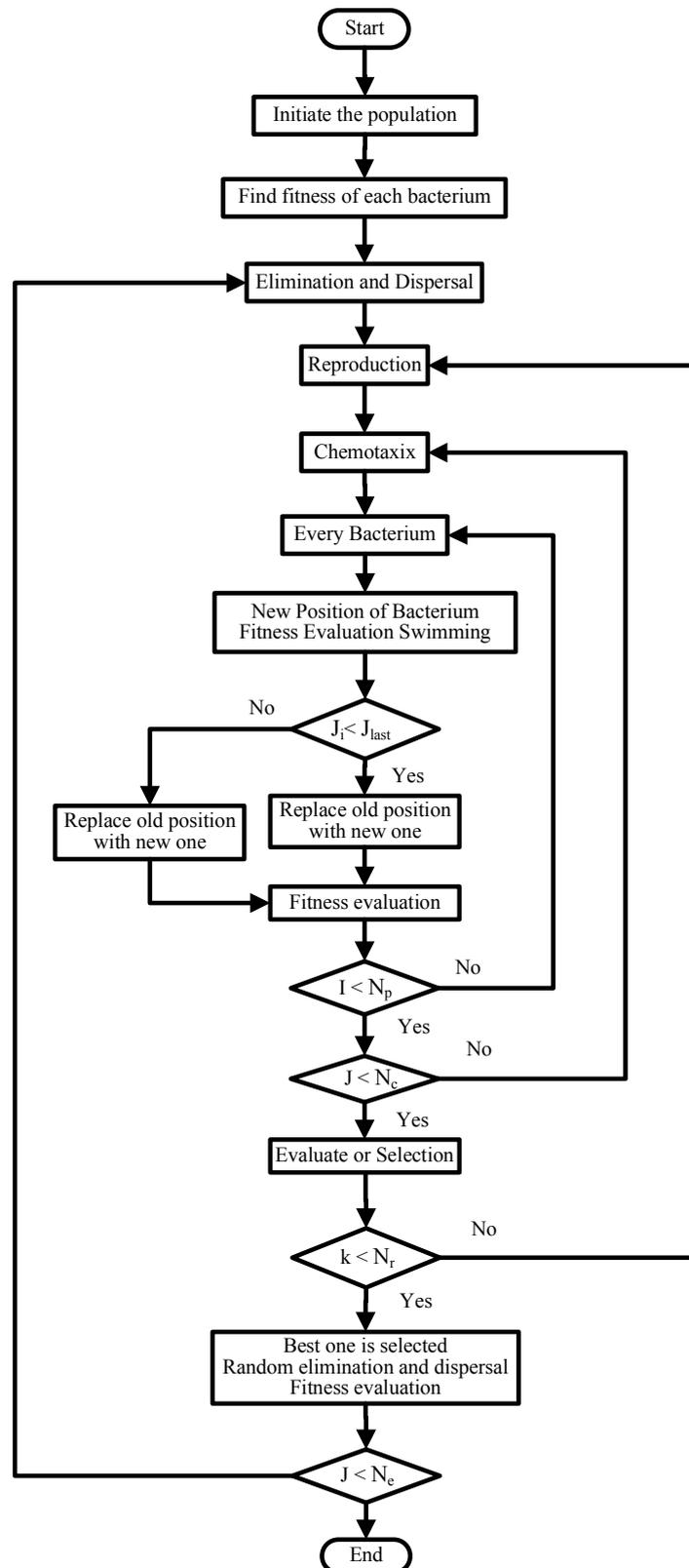


Figure 6. Flowchart of bacterial foraging algorithm (BFA).

6. Simulation Results

A substantial simulation was performed to show the performance of different algorithms in terms of minimization of electricity cost by shifting appliances from on-peak hours to off-peak hours,

minimization of PAR and minimization of end-user discomfort due to waiting time. In this paper, eight appliances were selected, as shown in the Table 1. For comparison purpose, firefly algorithm (FA), cuckoo search algorithm (CSA) and ant colony optimization algorithm (ACO) are considered in the same scenario for thirty-days load scheduling. Figure 7 gives the day-ahead pricing (DAP) signal, taken from the daily report of the New York Independent System Operator (NYISO) [35]. The total time of 24 h was divided into 24 time slots. For an office, usually 8–12 h was used, so time was taken from 8:00–20:00. Figure 8 shows the daily unscheduled load and scheduled load with the GOA and BFA algorithms. The figure shows that GOA outperformed by eliminating the peak in the unscheduled load. Figure 9 shows the hourly unscheduled (Un-sch) and scheduled load with GOA and BFA cost. It is clear that the hourly cost is averaged compared to the unscheduled cost, especially the high cost in the on-peak hours due to shifting of the load from on-peak hours to off-peak hours. Figure 10 shows that the office monthly load was equal for all algorithms, as each algorithm had to reschedule the appliances only. Figure 11 depicts the total monthly cost in dollars. In the unscheduled case, we had a maximum cost of 267.45 \$; when scheduled by GOA, it became 174.67 \$ (34.69% reduction); and in the case of BFA, it became 161.23 \$ (37.47% reduction). The comparison of these proposed algorithms with state-of-the-art algorithms for the same scenario is depicted in Table 2. Figure 12 depicts the daily PAR. It is clear from the figure that our proposed schemes minimized the PAR. Before scheduling, the PAR value was 7.81, and after scheduling with GOA and BFA, the PAR values became 3.42 (56.20% reduction) and 6.18 (20.87% reduction), respectively. Figure 13 depicts the average waiting time. The waiting time in the case of GOA was 1.28 h, and BFA was 1.32 h. This shows that the waiting time of BFA was greater than GOA because it had reduced the total cost more than that reduced by BFA. Table 2 shows that, there is always a trade-off between energy cost and waiting time.

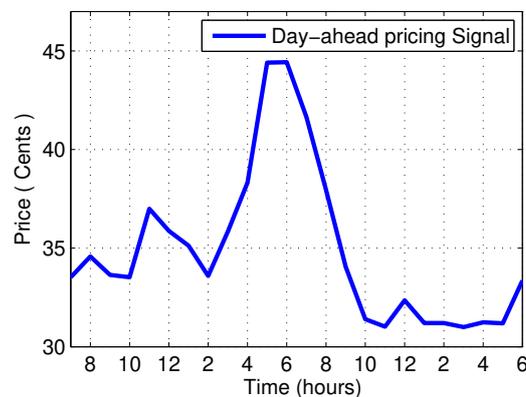


Figure 7. Day-ahead pricing signal [35].

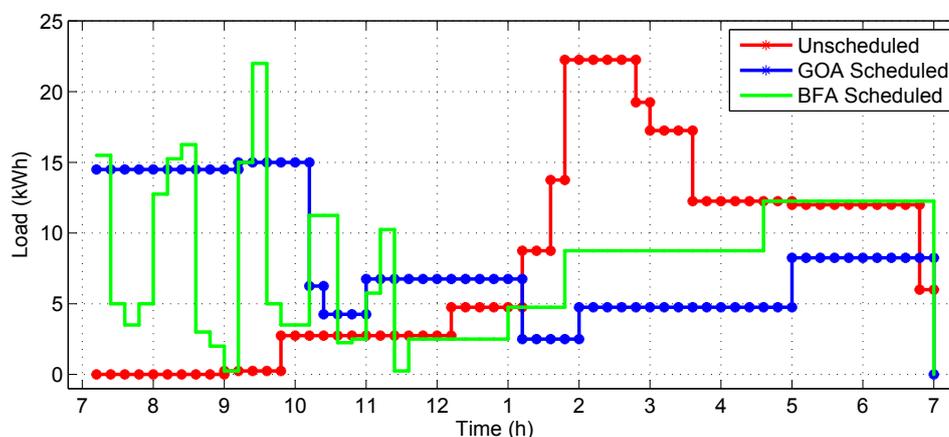


Figure 8. Hourly load for unscheduled load and scheduled load with the GOA and BFA algorithms.

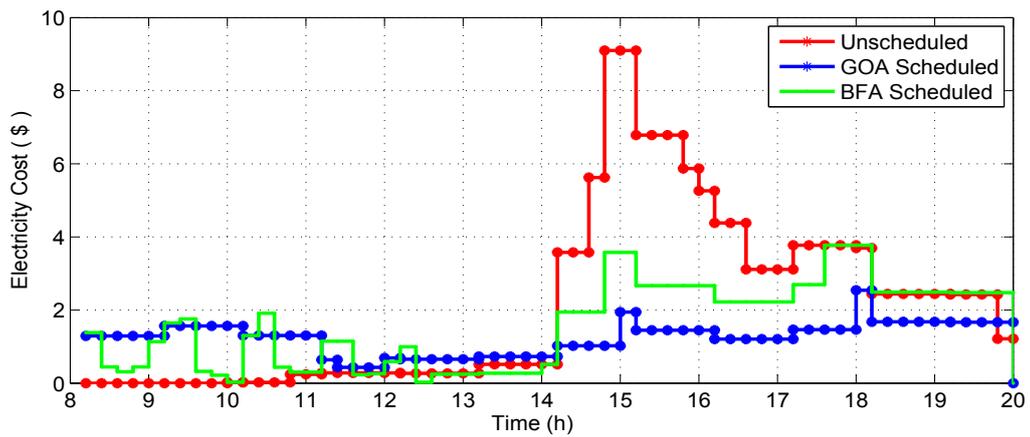


Figure 9. Hourly cost for unscheduled load and scheduled load with the GOA and BFA algorithms.

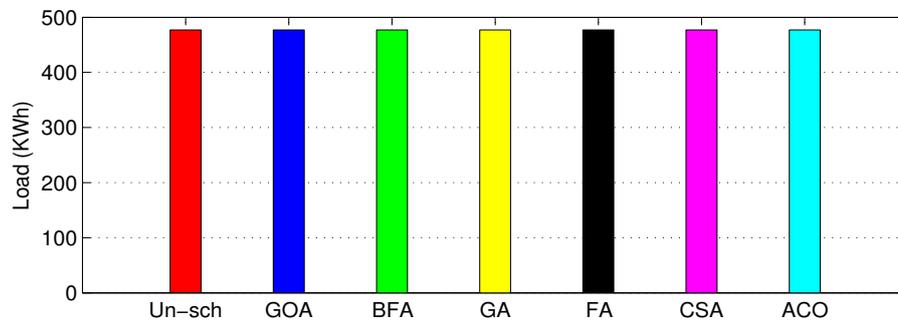


Figure 10. Total monthly load.

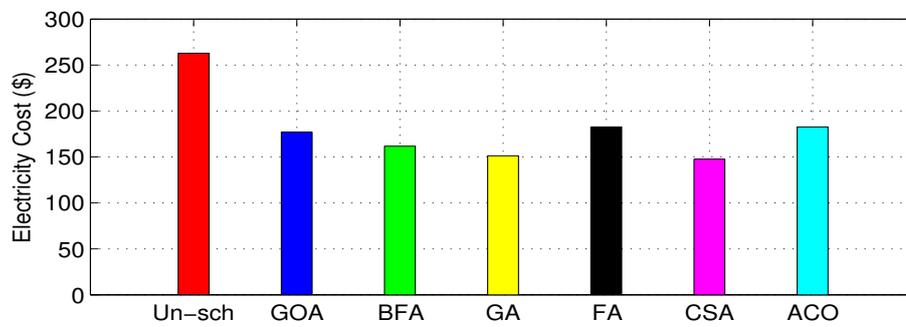


Figure 11. Total cost.

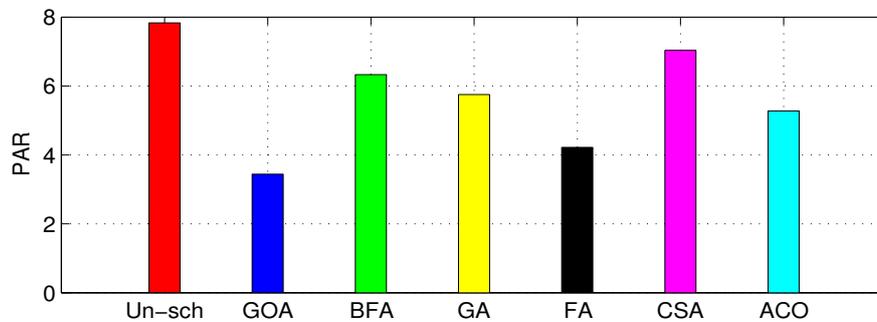


Figure 12. The peak-to-average power ratio (PAR).

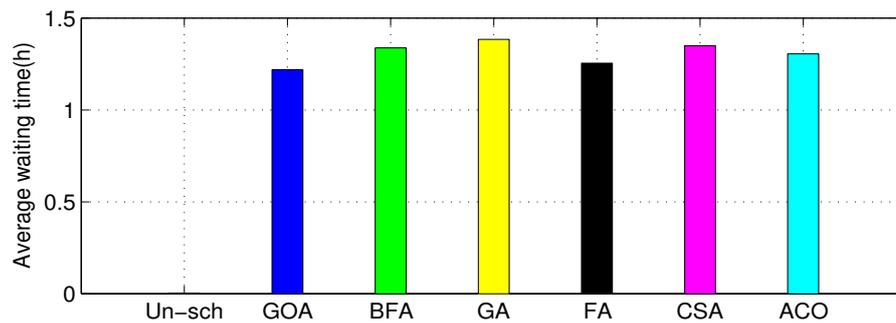


Figure 13. Average waiting time.

Table 2 compares the performance of the proposed algorithms with unscheduled load and state-of-the-art algorithms like firefly algorithm (FA), cuckoo search algorithm (CSA) and ant colony optimization (ACO) with respect to three parameters; energy cost, waiting time and PAR.

Table 2. Comparison of the unscheduled load and scheduled load with the GOA, BFA, GA, FA, CSA and ACO algorithms.

Techniques	Days	Cost (\$)	Cost Reduction	Waiting Time (h)	PAR	PAR Change
Unschedule	30 days	267.45	–	–	7.81	–
GOA-scheduled	30 days	174.67	34.69%	1.28	3.42	56.20%
BFA-scheduled	30 days	161.23	37.47%	1.32	6.18	20.87%
GA-scheduled	30 days	150.07	43.89%	1.39	5.84	25.22%
FA-scheduled	30 days	177.39	33.68%	1.25	4.17	46.60%
CSA-scheduled	30 days	147.68	44.79%	1.38	7.11	08.96%
ACO-scheduled	30 days	176.83	33.89%	1.27	5.34	31.62%

Table 3 shows the run-time of the proposed algorithms using an Intel (R) Core (TM) i5 processor, with 4.00 GB of installed memory (RAM) and the 32-bit Windows 7 Operating system.

Table 3. Run-time of the proposed algorithms for 30 days of load scheduling.

Proposed Algorithm	No. of Days	Run-Time (s)
GOA	30 days	11.695
BFA	30 days	13.171

7. Conclusions

In this paper, we have proposed a novel technique of appliances' scheduling in an office. We used two nature-inspired optimization algorithms, GOA and BFA, to achieve our objective functions of end-user electricity bill minimization along with a reduction of PAR and user discomfort due to appliance scheduling. We considered only eight appliances to check our proposed algorithms' performance. We compared our results with a few state-of-the-art nature-inspired algorithms in the literature like GA, FA, CSA and ACO for the three mentioned fitness functions, i.e., minimization of the electricity bill, PAR and waiting time. Indeed, numerous countries in the world can fulfil electricity demand. However, keeping in view the minimization of the electricity bill, the reliability of the existing system and improvements towards smart grids to facilitate the customers, with increased dependency on electricity with automation, energy optimization is a big issue throughout the world. Furthermore, with increased electricity generation, carbon emission increases due to the use of different types of fuels, which pollute this biosphere day by day. Therefore, the advantage of these algorithms for energy optimization is not only to save money, but to reduce pollution, as well. The simulation results show that our proposed energy optimization schemes performed well in the case of minimization of PAR

and cost. However, when energy cost is minimized, user waiting time will increase as a penalty. In the future, multi-objective algorithms will be designed to minimize the energy cost and PAR while keeping in view the high comfort level of consumers. Furthermore, the proposed algorithms will be applied to residential, commercial and industrial areas for the greater benefit of both the utility and consumers. For this purpose, more nature-inspired algorithms will be used and analyzed.

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Abbreviations

The following abbreviations are used in this manuscript:

OEC	Office energy consumption
LOT	Length of operational time
OTI	Operational time interval
AOAs	Automatically operating appliances
PAR	Peak-to-average power ratio
Un-sch	Un-scheduled load
FA	Firefly algorithm
CSA	Cuckoo search algorithm
ACO	Ant colony optimization
s	Each time slot
C	The total electricity cost in sixty time slots
P_{rate}	Power rating of connected appliances
$Load$	Power consumption of each appliance
τ_w	Waiting time for an appliance
S	Set of 60 time slots
E_{rate}	Energy cost per hour
X	ON-OFF states of an appliance
α	Starting time of an appliance
η	Operational starting time of an appliance
β	Ending time of an appliance

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