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On the temporal modelling of solar photovoltaic soiling: Energy and economic impacts in seven cities

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Abstract

This work developed a framework to predict the energy and economic impacts of solar photovoltaic soiling. This framework includes the effects of relative humidity, precipitation and tilt angle on solar photovoltaic soiling. A concept of relative net-present value change was introduced to determine the optimal cleaning interval. The uncertainties in the economic analysis were accounted for using a Monte Carlo simulation method. The framework was used to study the soiling-induced efficiency and economic losses of solar photovoltaic modules in seven cities (*i.e.* Taichung, Tokyo, Hami, Malibu, Sanlucar la Mayor, Doha, and Walkaway). Overall, the efficiency loss (in ascending order) for Tokyo/Walkaway < Taichung < Sanlucar la Mayor < Malibu/Hami < Doha for a one-year study period. Doha experiences an efficiency loss over 80% for a 140-day exposure, while Tokyo has an efficiency loss less than 4% for a one-year exposure. Malibu has longest optimal cleaning intervals (70 days for manual cleaning and 49 days for machine-assisted cleaning) that leads to the relative net-present value changes of 1.7% and 1.1%. Doha has the shortest optimal cleaning intervals (23 days for manual cleaning and 17 days for machine-assisted cleaning) that leads to the relative net-present value changes of 21% and 19%. The work serves as an effective tool for designing optimal cleaning protocols for solar photovoltaic systems.

Keywords: Solar PV; Soiling; Energy loss; Economics; Cleaning; Renewable energy.

INTRODUCTION

World energy consumption was projected to increase by 28% between 2015 and 2040 in accordance with the rapid growth in electricity demand and economy [1]. Limited reserves of fossil fuels and widespread concerns over greenhouse gas (GHG) emissions from fossil fuel consumption stimulate extensive research in renewable energy development. As a major form

of renewable energy, solar photovoltaic (PV) electricity generation has drawn an ever-increasing attention due to its abundance, accessibility, and technical maturity [2].

However, solar PV systems are plagued by the issue of natural soiling whereby particulate matters (PM) accumulate on the surface of solar PV panels, resulting in light transmission blockage and irradiance reduction. The solar conversion efficiency of solar PV modules could be lowered by 4 – 25% due to the soiling [3-5]. Piliouguine et al. [6] found that an average daily energy loss of 2.5% was resulted by soiling. Solar PV soiling is especially a concern for the regions where there are frequent sandstorms or haze episodes [7]. This issue could also be exacerbated during dry seasons when there is insufficient rainfall to clean PV surfaces [8]. The soiling-induced efficiency reduction not only adversely affects the stability and overall energy performance of solar PV systems but also incurs additional economic and logistics requirements upon solar PV cleaning [9]. Moreover, solar PV soiling has also becomes an important factor that needs to be considered during PV grid integration [10] and the evaluation of solar irradiation potential [11].

Particle deposition and accumulation on solar PV panels are affected by a variety of factors including relative humidity, wind speed, panel tilt angle, and rainfall. Under high relative humidity conditions, hygroscopic particles could be enlarged due to the absorption of environmental moisture [12]. The change in particle size could significantly affect the velocity of particle deposition [13]. Particle deposition also increases with the increase of wind speeds due to an enhanced effect of turbulent deposition [14]. The tilt of PV panels reduces particle deposition and thus the efficiency loss by soiling [15]. Elminir et al. found that the particle deposition density was 15.84 g/m² for a tilt angle of 0° and decreased to 4.48 g/m² for a tilt angle of 90° based on a seven-month experiment in Egypt [16]. Mejia and

Kleissl found that the average soiling losses for a tilt angle smaller than 5° are five times of that for a tilt angle larger than 5° in California [17]. Lu and Zhao [18] found that the tilted angles of 25° , 40° , 140° and 155° corresponded to the maximum deposition rates of 14.28%, 13.53%, 6.79% and 9.78%, respectively.

To design effective protocols for solar PV cleaning, it is critical to understand the temporal impacts of solar PV soiling on the efficiency degradation of PV modules. Empirical models (*e.g.*, [19, 20]) have been developed based on the regression analysis or artificial Neural Network modelling of experimental data of a specific region. These models have the advantages of being simple, straightforward, and easy to use. However, they are highly contingent upon existing experimental data and are hard to be applied to other regions with different environmental and meteorological conditions from the region where the model was based on. CFD simulation (*e.g.*, [21]) has also been used to study the process of solar PV soiling, which, however, has a high requirement on computational resources. As a promising alternative, mechanistic models could be developed by combining the prediction of particle deposition with the relationship between particle deposition density and solar PV efficiency loss. These models have the advantage of being applicable to a wide range of regions. One such model was proposed by [22] to estimate the cleaning frequency for dirty solar modules. However, this model was based on an empirical model for ‘indoor’ particle deposition [23] which are generally subject to different environmental conditions from outdoor particle deposition.

There is still lack of mechanistic models that are specifically designed to predict the temporal solar PV soiling under outdoor environmental conditions. Especially, such models need to be able to consider the effect of relative humidity on particle deposition. On the other hand, to

develop an economically sustainable solar PV cleaning protocol, it is critical to predict the optimum cleaning interval or frequency from a system perspective. Existing studies estimated the optimum cleaning interval by matching the cleaning-related cost with the energy output loss by soiling [24]. This method, however, did not consider system-level economics and the time value of money. Hence, a system-level economic analysis is needed to evaluate the economics of cleaning plans, which has rarely been done but will allow investors to make informed decisions about when to conduct the cleaning to optimize the profitability of solar PV systems.

In this work, we propose a solar PV soiling prediction model based on the theoretical modelling of particle deposition. The effects of meteorological factors (*e.g.*, relative humidity and precipitation) on solar PV soiling are considered. The economic impacts of solar PV soiling and cleaning are evaluated based on a system-level economic analysis. The optimal cleaning interval is determined by minimizing the relative net-present value (NPV) change. The model is then used to predict and compare the soiling-induced efficiency and economic losses of solar PV modules in seven cities (*i.e.*, Taichung, Tokyo, Hami, Malibu, Sanlucar la Mayor, Doha, and Walkaway) where solar PV has been extensively deployed.

METHODOLOGY

2.1 Particle Deposition Model

Outdoor particle deposition could be considered to be driven by two mechanisms, *i.e.* gravitational settling as well as wind turbulence and boundary layer effects [25]. Correspondingly, the atmosphere beneath a convenient reference height (*e.g.*, 20 m) was segregated into two layers [26]: (a) an upper layer where particle transport was governed by an atmospheric turbulence resistance term and (b) an underlying quasi-laminar layer where

particle transport was governed by Brownian diffusion and inertial impaction that could be grouped into a quasi-laminar resistance term. In this case, particle deposition could be modelled by a resistance in parallel model including two pathways, *i.e.* atmospheric turbulence and quasi-laminar layer mass transfer, and sedimentation (Fig. 1) [25].

The total deposition velocity V_d could be expressed as

$$V_d = \frac{1}{R_{at} + R_b} + V_s \cos\theta \quad (1)$$

where $R_{at} = \frac{1}{C_{DS} U}$ accounts for the atmospheric turbulence resistance term in the upper layer with C_{DS} being the surface drag coefficient and U (ms^{-1}) being the mean wind velocity. C_{DS} accounts for the intense turbulence when the wind blows over rough surfaces such as land and is related to atmospheric stability and surface roughness [27, 28]. C_{DS} has a global yearly average value of 1.2×10^{-2} over land and 1.2×10^{-3} over oceans [29]. The former will be used in this work. Wind speed is usually measured with an anemometer at a height of 10 m at weather stations according to the World Meteorological Organization [30]. Hence, a reference height of 10 m is considered for all wind speed reported unless otherwise stated. $C_{DS} U$ (ms^{-1}) represents the capability of wind to transfer kinetic energy to particles in the air.

$R_b = \frac{1}{u_* \left[Sc^{-0.5} + \frac{St^2}{1+St^2} \right]}$ accounts for the quasi-laminar layer resistance which factors in processes like Brownian diffusion and inertial impaction. $\cos\theta$ is used to account for the effect of solar PV panel tilt as explained later.

u_* (ms^{-1}) is the friction velocity and is an indicator of atmospheric turbulence [31]. At neutral atmospheric conditions, u_* is calculated as [32]

$$u_* = \frac{\kappa U}{\ln\left(\frac{h}{z_0}\right)} \quad (2)$$

where $\kappa = 0.41$ is the von Karman constant. $h = 10$ m is the reference height. $z_0 = 1$ m is the roughness length for the case of urban land [33]. Sc is the Schmidt number defined as the ratio of momentum diffusivity and mass diffusivity, and is given as [34]

$$Sc = \frac{\nu}{D} \quad (3)$$

where ν is the kinematic viscosity of air ($1.48 \times 10^{-5} \text{m}^2 \text{s}^{-1}$). D ($\text{m}^2 \text{s}^{-1}$) is the Brownian diffusion coefficient and calculated as

$$D = \frac{kTC_c}{3\pi\mu d_p} \quad (4)$$

where k is the Boltzmann constant ($1.38 \times 10^{-23} \text{JK}^{-1}$). T is the air temperature. C_c is the Cunningham correction factor. St is the Stokes number defined as the ratio of the characteristic time of particle to a characteristic time of the flow. It is calculated as [34]

$$St = \frac{(u_*)^2 V_s}{g\nu} \quad (5)$$

Gravitational settling is represented by the sedimentation velocity term (V_s). The suspension of aerosol particles in the air is dilute thus the particles are assumed to fall at their single particle terminal velocity [35]. V_s (ms^{-1}) is calculated by

$$V_s = \frac{\rho_p g d_p^2}{18\mu} \text{ for } Re_p \leq 1.0$$

$$V_s = \left(\frac{4\rho_p d_p g}{3C_D \rho_f} \right)^{0.5} \text{ for } Re_p > 1.0 \quad (6)$$

where $Re_p = \frac{\rho_f V_s d_p}{\mu}$ is the particle Reynolds number. ρ_f is the density of air (1.2kgm^{-3}).

ρ_p is the density of aerosol particle and is assumed to be 1000kgm^{-3} [29, 36]. g is the gravitational acceleration (9.81ms^{-2}). d_p (m) is the diameter of particle. μ is the viscosity of air ($1.81 \times 10^{-5} \text{kgm}^{-1} \text{s}^{-1}$). C_D is the drag coefficient. For $Re_p > 1.0$, we have

$C_D (Re_p)^2 = \frac{4\rho_p \rho_f g d_p^3}{3\mu^2}$ and it is used to determine the sedimentation velocity graphically [35].

The dry particle size is used in the equations above. It is important to consider the influence of relative humidity on particle deposition because fine hygroscopic dust particles may grow and enlarge by absorbing ambient moisture [37]. In this case, the dry particle size may not be accurate and should be replaced by a wet particle size [38]

$$r_w = \left(\frac{C_1 r_d^{C_2}}{C_3 r_d^{C_4 - \log_{10}[\text{Relative humidity}]} + r_d^3} \right)^{1/3} \quad (7)$$

where r_w is the wet particle radius, and $r_d = \frac{d_p}{2}$ is the dry particle radius. For urban aerosol particles, $C_1 = 0.3926$, $C_2 = 3.101$, $C_3 = 4.19 \times 10^{-11}$, and $C_4 = -1.404$. An increase in the diameter of microparticles due to the humidity effect will affect Solar PV soiling by mitigating Brownian diffusion-induced deposition while enhancing inertial impaction and sedimentation-induced deposition as denoted by R_b and V_s . Calculations based on Eq. (7) show that at a relative humidity of 70%, the differences between the dry and wet diameters for 1 and 10 μm particles are 14% and 20% respectively. These changes in the diameter will further lead to 19.8% and 6.7% increases in the deposition velocities of 1 and 10 μm particles, respectively. The effect of relative humidity on solar PV soiling has been rarely included in existing models.

The modelled deposition velocity is with respect to particle deposition onto horizontal surfaces. To account for the impact of the tilt of solar PV panels on particle deposition, the sedimentation velocity (Eq. (1)) is multiplied by the cosine of the tile angle, $\cos\theta$, under the assumption that the sedimentation velocity is the major component affected by the tilt [22]. Solar PV modules generally adopt an optimal tilt angle to maximize the overall energy gain. A simple rule of thumb is to consider the optimal tilt angle as the latitude of a place [39].

Based on this rule, a list of optimum tilt angles for different cities (as considered in the case studies) is given in Table 1.

2.2 Efficiency Loss

The efficiency loss (η_{loss}) is defined as the difference between the output efficiencies of solar PV module before (clean status) and after (soiling status) dust accumulation divided by the efficiency before dust accumulation. Linear relationships between the dust deposition density ρ_D ($\frac{\text{g}}{\text{m}^2}$) and efficiency loss η_{loss} have been reported [40-42]. According to the study by [42], we have

$$\eta_{\text{loss}} = 0.0139 \times \rho_D \quad (8)$$

This means that for every $1 \frac{\text{g}}{\text{m}^2}$ of dust deposition, the efficiency of the module degrades by 0.0139%. The dust deposition density ρ_D is estimated based on the deposition velocity V_d by

$$\rho_D = V_d \times C \times 10^{-6} \times \text{Duration (days)} \quad (9)$$

$V_d \times C$ is the particle deposition flux. Aerosols are usually polydisperse and have particle sizes that range over two or more orders of magnitudes. If the distribution of particle size is known, it is possible to estimate the particle deposition flux by dividing the distribution into discrete size bins and summing the deposition flux of each size bin. However, the particle size distribution has been rarely reported in the existing literature about solar PV soiling. Alternatively, PV soiling and efficiency loss studies generally used a single concentration metric (*e.g.*, $\text{PM}_{2.5}$ and PM_{10}) for the analysis [43]. Hence, for the model analysis in this work, intermediate particle sizes within the range of particle size distribution are used to test the accuracy during model validation.

Rainfall serves as a natural cleaning mechanism for PV panels, but the effectiveness of cleaning was highly contingent upon the quantity of rain. Hammonds et al. [44] suggested

that five millimeters of rainfall were sufficient to clean PV panel. But Kimber et al. [45] found that light to moderate rainfall events (<10 mm) were not sufficient to clean PV panels and a heavy rainfall event of 20 mm could restore an efficiency loss of 40%. In this work, we consider that 80% of particles on solar panels are washed off by large rainfall events (>10 mm) and 30% of particles are washed off by slight rainfall (<5 mm).

2.3 Economic Analysis

2.3.1 Economics of solar PV soiling and cleaning

One of the major concerns over solar PV soiling is its impact on the economics of solar PV systems. To evaluate the economic impact of solar PV soiling, a relative NPV change $\Delta\text{NPV}\%$ is introduced

$$\Delta\text{NPV}\% = \frac{|\text{NPV}_0 - \text{NPV}_1|}{|\text{NPV}_0|} \quad (10)$$

where NPV_0 and NPV_1 denote the NPV of the ideal case without soiling and the actual case with soiling (with or without cleaning). NPV is a way of thinking about converting future income into today's terms and a larger NPV indicates a higher profitability. NPV is calculated as

$$\text{NPV} = \sum_t^{LT} \frac{C_{it}}{(1+r)^t} - C_0 \quad (11)$$

where C_{it} is the net cash inflow in a year t ; C_0 is the total initial investment; LT denotes the lifetime of facilities and is 20 years in this work; $r = 10\%$ is the discount rate accounting for the time value of money for future investment (Ertürk, 2012; Manioğlu & Yılmaz, 2006).

The parameters involved in the economic analysis could potentially have great uncertainties. To account for the uncertainties, a Monte Carlo simulation-based method is adopted

following the study by [46]. In this method, uncertain parameters follow triangular distributions with the modes being the nominal value obtained from existing literature. The lower and upper bounds are set as 80% and 120% of the modes. During each run of simulation, a random value of each parameter is sampled from its distribution and plugged into Eq. (10) and Eq. (11) to calculate $\Delta NPV\%$. This process was repeated for ten thousand runs, giving rise to a distribution of $\Delta NPV\%$.

The cost components consist of a capital cost (*e.g.*, the costs of construction, equipment, tracking system, inverters, and electrical components), operations & maintenance (O&M) cost (*e.g.*, salary and training), and cleaning cost [47]. The benefit components mainly include electricity income. The specific values of the nominal parameters for each city are listed in Table 2.

Manual and machine-assisted methods are available for solar PV cleaning. The machine-assisted method had a cost per cleaning event 80% lower than the manual method [24]. For simplicity, the cleaning cost is considered based on an aggregated value in terms of unit electricity generation. Due to the lack of relevant data for cleaning costs for the considered cities, we apply the ones reported by [24] in the case studies: 0.19 USD/kW for manual cleaning and 0.032 USD/kW for machine-assisted cleaning (Exchange rate: 1 SAR=0.27 USD). To account for the variation of the efficiency loss with respect to time, a Monte Carlo simulation analysis is used to decide the starting time of cleaning based on which the average efficiency loss is calculated.

A flow diagram of the economic analysis is given in Fig. 2. The overall procedure is: (a) particle deposition velocities were estimated from deposition modelling (Eq. (1)) and were

then used to predict the deposition densities (Eq. (9)) and corresponding efficiency losses (Eq. (8)); (b) a uniform distribution was used to randomly determine the starting point in the temporal efficiency loss profile and an average efficiency loss was calculated for a specific cleaning interval; (c) NPV was estimated based on the triangular distributions of parameters (Eq. (11)); (d) the overall calculation was completed if the maximum number of iterations was reached, otherwise, (b)-(d) would be repeated.

2.3.2 Optimum cleaning interval

Based on the theoretical deposition model-based soiling prediction and system-level economic analysis, the optimum cleaning interval could be determined by minimizing the $\Delta\text{NPV}\%$ mean, *i.e.*

$$\min(\Delta\text{NPV}\%_{\text{mean}}) \rightarrow \text{CI}_{\text{op}} \quad (12)$$

2.4 Case Studies

The temporal variations of solar PV efficiency loss by soiling are modelled for seven cities (*i.e.* Taichung, Tokyo, Hami, Malibu, Sanlucar la Mayor, Doha, and Walkaway as shown in Fig. 3) which are world's leading solar PV implementer. They are widely distributed with distinctive climate conditions (*e.g.*, dry California climate in Malibu vs. tropical wet climate in Walkaway), which allows the comparison of the impacts of solar PV soiling across different climate and aerosol conditions. Local meteorological parameters such as monthly relative humidity, rainfall and wind speed are obtained from the World Weather Online website (<https://www.worldweatheronline.com/>) unless otherwise stated. Aerosol concentration data are from <http://aqicn.org/>. The weather and aerosol concentration conditions for different cities are listed in Table 3. The temporal variation of efficiency loss is modelled for one year for all the cities except for Doha where 140 days are modelled because

over 100% efficiency loss will be resultant for a one-year period. For each city, three tilt angle scenarios are models, *i.e.* optimal tilt angle, optimal tilt angle - 10°, and optimal tilt angle + 10°. We consider a solar PV power plant with a capacity of 1 MW (installation size) with an hour-of-daylight of 10 hours for each city. The temporal variation of efficiency loss in a year (140 days for Doha) is used as a reference for the economic analysis over the life course of the solar PV power plant. The cleaning interval is varied with a minimal resolution of 1 day for Doha and 7 days for the other cities.

There are various assumptions underlying the calculations: (1) only rainfall washing events are considered and no snow accumulation and wind-induced particle resuspension are considered; (2) rainfall are averaged by dividing the precipitation by the number of rainy days in a month and the frequency is calculated by dividing the number of days in a month by the number of rainy days in a month; (3) the particle deposition density is updated on a daily basis; (4) the average diameter of 20 μm by volume for outdoor aerosol from [42] is used to represent the size of particles that are most relevant to solar PV soiling [43].

RESULTS AND DISCUSSION

3.1 Model Validation

Model validation is conducted by comparing the model predictions with the reported experimental deposition velocities (*i.e.* [64-70]). The study by [64] includes a relevantly complete list of parameters such as relative humidity, mean wind speed, and aerosol concentration. For the other studies, the missing meteorological data were obtained from World Weather Online website (<https://www.worldweatheronline.com/>) while the aerosol concentration data PM_{2.5} and PM₁₀ were adapted from the World Air Quality website (<http://aqicn.org/city/taichung>). Other parameters followed [64]. The input parameters for

model predictions are listed in Table 4. For TSP (total suspended particulates: 20 - 50 μm), the particle sizes of 20 and 50 μm were used to model a range of deposition velocity. For PM_{10} (particulate matters smaller than 10 μm), the particle sizes of 5 and 10 μm were used to model a range of deposition velocity. For $\text{PM}_{2.5}$, (particulate matter smaller than 2.5 μm) the particle sizes of 1 and 2.5 μm were used to model a range of deposition velocity.

Fig. 4 shows that model predictions are generally within a five-time difference from the experimental data. A five-time variation in the deposition velocity suggests a five-time difference in the predicted daily efficiency loss. However, taking the case of Taichung as an example and using its meteorological data in January, a five-time variation in the predicted deposition velocity would only change the predicted daily electricity output by 3.4%. Considering that the economic analysis is based on the daily energy output, this may suggest that the model can predict the deposition velocity with satisfactory accuracy for solar PV soiling analysis. For TSP (most relevant to solar PV soiling), its deposition velocity ranges from about 1 to 20 cm/s. Note that the red line connecting two points denote the ranges of experimental data and model predictions and the two end-points denote the experimental and modelling lower and upper bounds.

3.2 Efficiency Loss

The temporal variations of the soil-induced efficiency losses of solar PV for different cities are shown in Fig. 5. Overall, the variation of the tilt angle by plus and minus ten degrees change the efficiency loss by 0.01% only.

(a) Taichung

Fig. 5 (a) shows that higher efficiency loss occurs during February, and October to December for Taichung, which is attributed to the relatively low precipitation during the months. October to December months have both low precipitation (<50 mm) and small numbers of rainy days (<15 days), leading to the most significant efficiency losses during the months: from *ca.* 1% at the beginning of October to *ca.* 25% at the end of December. For the other months, the efficiency loss is consistently less than 2% due to the high and frequent precipitation (The monthly precipitation received during the wet months is about 10 - 15 times higher than that in the dry months). Without cleaning, an efficiency loss of *ca.* 25% could be incurred after one-year dust soiling.

(b) Hami and Malibu

Without cleaning, Hami and Malibu (Fig. 5 (b) and (e)) experience the highest efficiency loss of 36% and 32% in September and August, respectively. The efficiency loss is high during most of the months for both the cities. Hami and Malibu have ‘continental desert’ and ‘Mediterranean’ climate, respectively, which are featured by low annual precipitation (*e.g.*, one order of magnitude lower than Taichung). However, compared to Malibu, Hami has higher precipitation and more rainy days, which correspond to the more significant wash-off effect from rainfall for Hami. The aerosol concentration of Hami is double of that of Malibu, which leads to a higher efficiency loss for the case of Hami.

(c) Tokyo and Walkaway

Tokyo and Walkaway (Fig. 5 (d) and (g)) have a relatively small efficiency loss over the time compared to the other cities. This is attributed to the combined effect of a lower aerosol concentration and more frequent rainfall. Without cleaning, the efficiency losses for Tokyo and Walkaway after one year soiling are 3% and 10%, respectively. Large efficiency loss

increases occur in May and December for Tokyo, while they occur on February, and September to December for Walkaway.

(d) Sanlucar la Mayor

Sanlucar la Mayor has low precipitation (<10 mm) and small numbers of rainy days (< 5 days) during June to September, which leads to a peak efficiency loss of *ca.* 14% during the months. For the other months, the efficiency loss is generally smaller than 5%. Note that Sanlucar la Mayor has a similar aerosol concentration to Tokyo. However, their different precipitation patterns cause the contrastly different efficiency loss variations between the two cities.

(e) Doha

Doha (Fig. 5 (c)) experiences the highest efficiency loss (88%) for 140-day soiling because of sparse rainfall as well as a high aerosol concentration associated with sandstorm events. Previous experimental research showed that one-month exposure led to an 18.74% decrease in the solar PV efficiency in Baghdad, Iraq [71]. A single sandstorm could reduce the power output of solar PV by 20% in the Eastern province of Saudi Arabia [7]. Rainfall cannot be relied upon for cleaning in such arid places since it occurs occasionally only [7]. Arid areas like the Middle East are characterized by limited precipitation. Coupled with the high amounts of dust, heavy soiling causes significant degradation in efficiency in the region. These places are the prime locations for the construction of concentrated solar plants because they receive high rates of solar irradiation throughout the year [72]. Overall, the efficiency loss (in ascending order) for Tokyo/Walkaway < Taichung < Sanlucar la Mayor < Malibu/Hami < Doha for a one-year period.

3.3 Economic Analysis

Fig. 6 i shows the variations of relative NPV change with respect to the cleaning interval for different cities. For comparison and illustration, the variations of electricity income loss and cleaning costs with respect to the cleaning interval are also shown (Fig. 6 ii). Conventionally, the optimal cleaning interval was determined by matching the cleaning cost with the electricity income loss, while the optimal cleaning interval corresponds to the minimization of the relative NPV change in this work. A list of optimal cleaning intervals and frequencies and NPVs under the optimal interval is given in Table 5. For comparison, the ideal NPVs for the case without soiling (*i.e.* solar PV is always clean) are also listed in Table 5.

Fig. 6 shows that the variation of $\Delta\text{NPV}\%$ has a V shape which was caused by the competitive effect of efficiency loss and cleaning. More frequent cleaning leads to a higher cleaning cost, while less frequent cleaning means a higher efficiency loss and thus electricity income loss, both of which cause a higher NPV reduction. Manual cleaning has a larger $\Delta\text{NPV}\%$ than machine-based cleaning because of the higher unit cost of manual cleaning. Table 5 shows that for the same city, the optimal cleaning intervals for the machine-assisted method are generally shorter than that for the manual method. The electricity income loss firstly decreases as the cleaning interval and then increases. More frequent cleaning does not necessarily cause a lower electricity income loss due to the existence of rainfall cleaning effects. This also suggests that there is an optimal cleaning interval where the electricity income loss is the minimal. For the case of manual cleaning, the optimal cleaning intervals estimated by the method of this work were 7-28 days longer than that by the conventional method which does not lead to the optimized profitability (NPV). For the case of machine-assisted cleaning, the optimal cleaning intervals estimated by the method of this work were

not shorter than that by the conventional method for all the cities except for Doha. For Doha, a 6-day shorter interval was estimated by the method of this work.

(a) Taichung

For Taichung, $\Delta\text{NPV}\%$ is 14.7% and 32.7% for the manual cleaning interval of 7 and 365 days, respectively, which means that the NPV of the solar PV plant is reduced by 14.7% and 32.7% respectively for the two types of manual cleaning arrangement. For the machine-assisted cleaning, $\Delta\text{NPV}\%$ is 8.2% and 32.6% under the interval of 7 and 365 days. Hence, the method (*i.e.* manual vs. machine) of cleaning plays a bigger role for more frequent cleaning due to the increase in its weight in the overall cost. The optimal cleaning interval corresponds to the minimal $\Delta\text{NPV}\%$. As listed in Table 5, it is 32 and 21 days, and the corresponding $\Delta\text{NPV}\%$ is 5.6% and 4.3%, respectively, for manual and machine-assisted cleaning for Taichung. By setting the optimal cleaning interval for the manual and machine-assisted methods, respectively, the NPV difference between the methods is only 0.01 million USD. The conventional way of optimal cleaning interval estimation (minimizing the difference between cleaning cost and electricity income loss) produces a much shorter cleaning interval for both the methods (14 days for manual and 21 days for machine).

(b) Hami

The relative NPV change of Hami is smaller than that of Taichung because of its higher absolute value of NPV. Due to the low capital and O&M costs (Table 2), Hami has a positive average NPV of 3.03 million USD. The large absolute NPV also indirectly lessens the impact of cleaning, which causes a similar optimal cleaning interval between the two methods, *i.e.* 35 days. The relative NPV changes under the cleaning interval of 7, 35, and 365 days are 8.6%, 2.6%, and 12% for manual cleaning and 6.2%, 2.2%, and 12% for machine-assisted

cleaning. Based on the conventional method, a shorter optimal cleaning interval of 21 days is obtained for manual cleaning while the same optimal cleaning interval (35 days) is obtained for machine-assisted cleaning.

(c) Hami

For Doha, the relative NPV change varies from around 20% at the optimal cleaning intervals (23 days for manual and 17 days for machine) to over 100% at the cleaning interval less than 3 days, which suggests the significant impact of soiling and relevant cleaning on the economics of solar PV plants in arid areas like Doha. Compared to the other cities, Doha is more sensitive to the cleaning interval and has much shorter cleaning intervals due to the larger soiling-induced solar PV efficiency loss. The optimal cleaning intervals for manual and machine-assisted cleaning corresponds to the relative NPV changes of 21% and 19%, respectively. The optimal cleaning intervals by the conventional method are 17 and 23 days for manual and machine-assisted cleaning, respectively.

(d) Tokyo, Walkaway and Sanlucar la Mayor

Tokyo has the same optimal cleaning intervals (49 days for manual and 35 days for machine) as Sanlucar la Mayor and Walkaway. For manual cleaning, the optimal intervals by the conventional method are 42, 28, and 28 days, for Tokyo, Sanlucar la Mayor, and Walkaway. For machine-assisted cleaning, the optimal intervals by the conventional method are 14, 35, and 21 days for Tokyo, Sanlucar la Mayor, and Walkaway. The relative NPV change at the same cleaning interval for Sanlucar la Mayor is only around a fifth to a tenth of that for Tokyo and Walkaway.

(e) Malibu

Malibu has the longest cleaning intervals: 70 days for manual and 49 days for machine which correspond to the relative NPV changes of 1.7% and 1.1%. However, the efficiency loss for Malibu is not the largest as shown in Fig. 4. This suggests that the optimal cleaning intervals are not only determined by the soiling-induced efficiency degradation but also the system's overall cost and benefit components, which re-emphasizes that it is critical to estimate the optimal cleaning interval from the perspective of the overall system economics. The conventional method predicts the optimal cleaning intervals of 42 and 35 days for manual and machine-assisted cleaning. Overall, the NPV-based system level method generally predicts longer optimal intervals than the conventional method for both cleaning methods.

3.4 Future Development

This work adopted the average efficiency loss model (Eq. (8)) that was obtained based on the experimental data for three different modules: *i.e.* mono-crystalline silicon with white glass as the surface material, poly-crystalline silicon with epoxy as the surface material, and amorphous silicon with white glass as the surface material [42]. However, the efficiency loss was also dependent on the types of PV modules and soiling particles, and solar density [40]. For example, a poly-crystalline silicon module packaged with epoxy degraded faster than a mono-crystalline silicon module with a white glass surface under the same deposition density [42]. For a similar type of module and deposition density, the efficiency reduction was the largest for red soil, followed by limestone, ash, and natural air pollutant, respectively, as a result of composition differences [73]. New models that could differentiate the effects of the factors need to be developed for more specific prediction.

For highly soiling cases such as the one of Doha, it is worth noting there might be two stages of fouling [74]. In the “early stage of fouling” single-particle deposition and re-suspension is

at an equilibrium state and the efficiency loss increases with the particle deposition density [75]. As more particles accumulate without being removed *e.g.*, via rainfall, there occurs the “later stage of fouling” where multilayer formation and clogging occurs [74]. In this case, new dust particles will deposit and settle on existing particles. Although ρ_D increases, it might not reduce the efficiency further since the surface is ‘saturated’ by particles. Hence, the efficiency loss will ‘flatten’ and plateau off instead of increasing further [76]. The extent of this saturation effect is still unknown and thus not included in this work, which warrant future studies. Finally, it will be desirable to incorporate the method of this work into the operation and management systems of existing solar PV plants to design optimal operation and management schemes.

CONCLUSIONS

This work improves the current ability of predicting temporal solar photovoltaic soiling using the upgraded mechanistic model. It introduces a new method to predict the optimal interval of solar photovoltaic cleaning based on a combination of the mechanistic model and system-level economic analysis (relative net-present value). The method could potentially be incorporated into the operation and management systems of existing solar photovoltaic plants. This will allow operators to make timely and informed decisions about when to conduct the cleaning to improve the profitability of solar net-present value systems. Based on the method, the soiling-induced efficiency and economic losses of solar photovoltaic modules in seven cities (*i.e.*, Taichung, Tokyo, Hami, Malibu, Sanlucar la Mayor, Doha, and Walkaway) were compared. It was found that varying the tilt angle by plus and minus ten degrees changed the efficiency loss by 0.01% only. Overall, the efficiency loss (in ascending order) for Tokyo/Walkaway < Taichung < Sanlucar la Mayor < Malibu/Hami < Doha for a one-year period. The predicted optimal cleaning interval ranges from 23 to 70 days and 17 to 49 days

for the manual and machine-assisted cleaning methods, respectively. Malibu has longest optimal cleaning intervals (70 days for manual cleaning and 49 days for machine-assisted cleaning) that leads to the relative net-present value changes of 1.7% and 1.1%. Doha has the shortest optimal cleaning intervals (23 days for manual cleaning and 17 days for machine-assisted cleaning) that leads to the relative net-present value changes of 21% and 19%.

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Nomenclature

C_D	Drag coefficient
C_{DS}	Surface drag coefficient
C_c	Cunningham correction factor
C ($\mu\text{g} \cdot \text{m}^{-3}$)	Atmospheric aerosol concentration
C_1, C_2, C_3, C_4	Empirical constants
d_p (m)	Particle diameter
D (m^2s^{-1})	Brownian diffusion coefficient
g ($\text{m} \cdot \text{s}^{-2}$)	Gravitational acceleration
h (m)	Reference height
k (JK^{-1})	Boltzmann constant
LT	Life time of facilities
NPV (USD)	Net-present value
$\Delta\text{NPV}\%$	Relative NPV change
R_{at} ($\text{s} \cdot \text{cm}^{-1}$)	Atmospheric turbulence resistance term
R_b ($\text{s} \cdot \text{cm}^{-1}$)	Quasi-laminar resistance term
Re_p	Particle Reynolds number
r_d (m)	Dry particle radius
r_w (m)	Wet particle radius

r	Discount rate
Sc	Schmidt number
St	Stokes number
T (K)	Air temperature
U ($m \cdot s^{-1}$)	Mean wind velocity
u_* ($m \cdot s^{-1}$)	Friction velocity
V_s ($m \cdot s^{-1}$)	Sedimentation velocity
V_d ($m \cdot s^{-1}$)	Total deposition velocity
z_0 (m)	Roughness length
ρ_f ($kg \cdot m^{-3}$)	Density of fluid
ρ_p ($kg \cdot m^{-3}$)	Density of aerosol particle
ρ_D ($g \cdot m^{-2}$)	Dust deposition density
μ ($kg \cdot m^{-1}s^{-1}$)	Viscosity of air
κ	von Karman constant
ν (m^2s^{-1})	Kinematic viscosity of air
θ ($^\circ$)	Solar PV tilt angle
η_{loss}	Efficiency loss